

ON THE VOLUMES OF BALLS

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ABSTRACT. We prove the formula for the volume of an even-dimensional ball by exhibiting an explicit, locally volume-preserving (in fact symplectic) map from a polydisk.

The volume of a ball $B_d(r)$ of radius r in d -dimensional Euclidean space is given by the well-known formula

$$\text{vol}(B_d(r)) = \frac{\pi^{d/2} r^d}{(d/2)!}.$$

If d is odd, the fractional factorial in the denominator is to be interpreted using the gamma function, but we shall be concerned only with the case of even d . In this case, we have, setting $d = 2m$,

$$\text{vol}(B_{2m}(r)) = \frac{(\pi r^2)^m}{m!} = \frac{(\text{vol}(B_2(r))^m)}{m!}.$$

Since the symmetric group of degree m acts on $B_2(r)^m$ by permuting the factors, and since almost all of the orbits of this action have size $m!$, the volume formula above strongly suggests the conjecture that there is a “nice,” volume preserving correspondence between the orbit space of $B_2(r)^m$ and $B_{2m}(r)$, or at least between subsets of full measure in these spaces. Equivalently, one expects a “nice,” locally volume preserving map $f : B_2(r)^m \rightarrow B_{2m}(r)$, such that $f(x_1, \dots, x_m)$ is unchanged by permutations of the x_i 's.

The purpose of this paper is to exhibit two such maps f . The first is the simplest one we know; the second, though slightly more complicated, enjoys additional interesting properties. Both are “nice” at least in the senses of being independent

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of r (they are each the restriction of a single map $\mathbb{C}^m \rightarrow \mathbb{C}^m$) and of being well-defined and smooth away from a singular locus of dimension $< 2m$. For additional comments about “niceness” see the last paragraph of the paper.

The existence of such maps provides a proof, more explicit than the usual computational ones, of the volume formula for even-dimensional spheres. Here “more explicit” has a meaning similar to that arising in finite combinatorics, where bijective proofs are regarded as more explicit than computational ones. Just as in finite combinatorics, a proof based on an explicit bijection has the virtue that the bijection may preserve more structure than originally envisaged; indeed, this occurs for the second of our two maps, as we shall explain after the construction.

To describe our maps, it is convenient to regard $B_{2m}(r)$ as a ball centered at the origin in \mathbb{C}^m . In particular, $B_2(r)$ is a disk in \mathbb{C} , and so $B_2(r)^m$ is identified with $\{(z_1, \dots, z_m) \mid \max_j |z_j| < r\} \subseteq \mathbb{C}^m$. We write $z_j = r_j e^{i\alpha_j}$ for the j th coordinate in \mathbb{C}^m .

The first of our maps f is defined as follows. Given (z_1, \dots, z_m) , first re-order the components so that $r_1 \geq r_2 \geq \dots \geq r_m$, and then produce as output the m -tuple

$$\left(\sqrt{r_1^2 - r_2^2} e^{i\alpha_1}, \sqrt{r_2^2 - r_3^2} e^{i\alpha_2}, \dots, \sqrt{r_{m-1}^2 - r_m^2} e^{i\alpha_{m-1}}, r_m e^{i\alpha_m} \right).$$

The re-ordering instruction is ambiguous when two of the z_j have the same modulus r_j ; for example, $(1, i)$ can be re-ordered as either $(1, i)$ or $(i, 1)$, resulting in an f -value of either $(0, i)$ or $(0, 1)$. So our function f is well-defined only where all r_j are distinct. This is almost all of \mathbb{C}^n , so the exceptional locus where f is undefined doesn't affect any volumes.

We note that f maps $D = \{(z_1, \dots, z_m) \mid \text{all } |z_j| \text{ distinct}\}$ onto $\{(z_1, \dots, z_m) \mid z_j \neq 0 \text{ for } j < m\}$, and that two points in D have the same image under f if and only if they differ by a permutation of the coordinates. Furthermore, the Euclidean norm of $f(z_1, \dots, z_m)$ is simply r_1 , the largest of the norms of the z_j 's. Thus, except for sets of measure zero, the polydisk $B_2(r)^m$ is mapped onto $B_{2m}(r)$.

It remains to check that f locally preserves volumes. For this purpose, it is convenient to use the coordinates $s_j = \frac{1}{2}r_j^2$ and α_j . In these coordinates, the volume form on \mathbb{C}^m is simply $\prod_{j=1}^m ds_j d\alpha_j$. Furthermore, the transformation f , when expressed in these coordinates, is linear on each connected component of its domain D . Its matrix is the product of an even permutation matrix (for the initial re-ordering of coordinates) and a triangular matrix with all diagonal entries equal to 1. So its determinant is 1 and the volume is preserved.

A slight modification of the definition of f makes its behavior even nicer. Begin by re-ordering the input tuple as above, but then define the output of f to be

$$\left(\sqrt{r_1^2 - r_2^2} e^{i\alpha_1}, \sqrt{r_2^2 - r_3^2} e^{i(\alpha_1 + \alpha_2)}, \dots, \sqrt{r_{m-1}^2 - r_m^2} e^{i \sum_{j=1}^{m-1} \alpha_j}, r_m e^{i \sum_{j=1}^m \alpha_j} \right).$$

The proofs above concerning the old f apply equally well to the new. Unlike the old f , the new one is well-defined and continuous everywhere (but differentiable

only on D). For example, the input $(1, i)$ now produces output $(0, i)$ no matter which of the two re-orderings is chosen.

In addition, the new f preserves the symplectic structure in the regions where it is smooth. That is, the 2-form $\sum_j dx_j dy_j = \sum_j ds_j d\alpha_j$ (where $x_j + iy_j = z_j$) is unchanged when pulled back along f . This property of f is stronger than preserving the volume; the volume form is, up to a constant factor, the m th exterior power of the symplectic 2-form. (We thank André Joyal for suggesting that we try to improve our result from “volume-preserving” to “symplectic.”)

Finally, let us indicate a larger picture into which our example fits as one piece of a puzzle. As in [1], we call a subset of Euclidean space *semi-algebraic* if it can be defined by a finite combination, using propositional connectives, of polynomial equations and inequalities over \mathbb{R} . (By the well-known quantifier elimination for real-closed fields, this is equivalent to requiring the set to be definable by a first-order formula (with parameters) over the structure $(\mathbb{R}, +, \cdot)$.) Call a function semi-algebraic if its graph is. The problem of classifying semi-algebraic sets up to semi-algebraic isomorphism was treated in [1], along with the analogous problem for other categories like the piecewise linear category. If we are interested in volumes, then it is natural to consider only volume-preserving maps and to ignore lower-dimensional pieces of their domains and codomains. Thus, we arrive at the natural question: Given two semi-algebraic sets A and B with the same dimension d and the same d -dimensional volume, when do there exist lower-dimensional semi-algebraic sets A_0 and B_0 and a measure-preserving, semi-algebraic bijection from $A - A_0$ to $B - B_0$? The answer to the analogous question for piecewise linear sets and maps is “always,” by a triangulation and subdivision argument. In the semi-algebraic case, the answer is certainly not “always”; consider the circumference of the unit circle and a straight line segment of the same length 2π . On the other hand, when A is the surface of a sphere in \mathbb{R}^3 and B is the curved surface of a circumscribed cylinder, the existence of such an area-preserving map, namely the projection perpendicular to the cylinder’s axis, has been known since antiquity. Our example provides such a map when A is a fundamental domain $\{(z_1, \dots, z_m) \mid r \geq |z_1| > \dots > |z_m|\}$ for the action of the symmetric group on a polydisk and B is the ball $B_{2m}(r)$. It seems to be unknown whether such a map exists when A is the disk $B_2(1)$ and B is a $1 \times \pi$ rectangle (semi-algebraic circle-squaring). The general problem, to classify semi-algebraic sets up to semi-algebraic volume-preserving bijections modulo lower-dimensional sets, seems quite intractable.

REFERENCES

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