# NOTES ON COMBINATORIAL APPLICATIONS OF HYPERBOLIC POLYNOMIALS 


#### Abstract

These are notes on combinatorial applications of hyperbolic polynomials, one of the topics covered in my course "Topics in Convexity" in Winter 2013.


## 1. Hyperbolic polynomials and their hyperbolicity cones

(1.1) Definition. Let $p: \mathbb{R}^{d} \longrightarrow \mathbb{R}$ be a homogeneous polynomial of some degree $m>0$, and let $u \neq 0$ be a vector. We say that $p$ is hyperbolic in the direction of $u$ if for every $x \in \mathbb{R}^{d}$ all the roots of the univariate polynomial

$$
t \longmapsto p(x-t u)
$$

are real.
(1.2) Example. Let

$$
p(x)=x_{1} \cdots x_{d} \quad \text { for } \quad x=\left(x_{1}, \ldots, x_{d}\right)
$$

and let

$$
u=(1, \ldots, 1) .
$$

Then

$$
p(x-t u)=\left(x_{1}-t\right) \cdots\left(x_{n}-t\right)
$$

and $p$ is hyperbolic in the direction of $u$ (as well as in any other direction).
(1.3) Example. Let $\mathbb{R}^{d}=S y m_{n}$, the space of real symmetric $n \times n$ matrices, let

$$
p(X)=\operatorname{det} X
$$

and let

$$
u=I, \quad \text { the identity matrix. }
$$

Then

$$
p(x-t u)=\operatorname{det}(X-t I)
$$

and the roots are of the polynomial $t \longmapsto \operatorname{det}(X-t I)$ are the eigenvalues of $X$, which are all real. Hence $\operatorname{det} X$ is hyperbolic in the direction of the identity matrix.
(1.4) Differentiation. Let $p$ be a homogeneous polynomial of degree $m>1$, hyperbolic in the direction of $u=\left(u_{1}, \ldots, u_{n}\right)$. We define a polynomial $q$ of degree $m-1$ by

$$
q(x)=\frac{\partial p}{\partial u}=\sum_{i=1}^{d} u_{i} \frac{\partial p}{\partial x_{i}}
$$

It is then easy to see that $q$ is hyperbolic in the direction of $u$. Indeed,

$$
q(x-t u)=\sum_{i=1}^{d} u_{i} \frac{\partial p(x-t u)}{\partial x_{i}}=-\frac{d}{d t} p(x-t u)
$$

and by Rolle's Theorem all the roots of the polynomial $t \longmapsto q(x-t u)$ are real and interlace the roots of $p$.
(1.5) Example. Differentiating $n-k$ times the polynomial of Example 1.2 we conclude that the elementary symmetric polynomial

$$
p(x)=\sum_{1 \leq i_{1}<i_{2}<\ldots<i_{k} \leq n} x_{i_{1}} \cdots x_{i_{k}}
$$

is hyperbolic in the direction of $u=(1, \ldots, 1)$ for any $k=1, \ldots, n$ (Exercise).
(1.6) Example. Differentiating $n-k$ times the polynomial of Example 1.3 we conclude that the polynomial

$$
p(X)=\sum_{\substack{J \subset\{1, \ldots, n\} \\|J|=k}} \operatorname{det} X_{J},
$$

where the sum is taken over all $k$-subsets $J \subset\{1, \ldots, n\}$ and $X_{J}$ is the $k \times k$ submatrix of $X$, consisting of the entries in the rows and columns indexed by the elements of $J$, is hyperbolic in the direction of $I$ (Exercise).
(1.7) Definition. Let $p: \mathbb{R}^{d} \longrightarrow \mathbb{R}$ be a polynomial hyperbolic in the direction of $u$. We define the hyperbolicity cone by

$$
K(p, u)=\left\{x \in \mathbb{R}^{d}: \text { the roots of the polynomial } t \longrightarrow p(x-t u) \text { are positive }\right\} .
$$

Strictly speaking, $K(p, u)$ is not a cone as we defined them, since $K(p, u)$ may not contain 0 . It is not hard to show that the closure $\overline{K(p, u)}$ of $K(p, u)$ can be defined as
$\overline{K(p, u)}=\left\{x \in \mathbb{R}^{d}:\right.$ the roots of the polynomial $t \longrightarrow p(x-t u)$ are non-negative $\}$
(Exercise). We obtain some familiar cones as $\overline{K(p, u)}$.
(1.8) Example. Let $p=x_{1} \cdots x_{d}$ and let $u=(1, \ldots, 1)$, as in Example 1.2. Then

$$
K(p, u)=\operatorname{int} \mathbb{R}_{+}^{d},
$$

the set of all vectors in $\mathbb{R}^{d}$ with all coordinates positive and

$$
\overline{K(p, u)}=\mathbb{R}_{+}^{d}
$$

is the non-negative orthant in $\mathbb{R}^{d}$.
(1.9) Example. Let $p(X)=\operatorname{det} X$ and let $u=I$, as in Example 1.3. Then

$$
K(p, u)=\operatorname{int} \mathcal{S}_{+},
$$

the set of all positive definite $n \times n$ symmetric matrices and

$$
\overline{K(p, u)}=\mathcal{S}_{+}
$$

is the cone of positive semidefinite matrices.
It does not look easy to describe the cones $K(p, u)$ in Example 1.5 (except when $k=1$ or $k=2$ ) and in Example 1.6 (except when $k=1$ ). It is clear though that $K(p, u) \subset K(q, u)$ if $q$ is obtained from $p$ as in Section 1.4 (Exercise).
(1.10) Dependence of roots of a polynomial on its coefficients. We will often say that the roots of a univariate polynomial depend continuously on its coefficients. More precisely, let

$$
p(z)=a_{0}+a_{1} z+\ldots+a_{n} z^{n}
$$

be a complex polynomial, such that $p \not \equiv 0$, so $\left|a_{0}\right|+\ldots+\left|a_{n}\right|>0$. Let

$$
D=\left\{z \in \mathbb{C}: \quad\left|z-z_{0}\right|<\delta\right\}
$$

be an open disk in the complex plane centered at $z_{0}$ and of radius $\delta>0$ and let $S=\partial D$ be the boundary circle of $D$. Suppose that $p$ has exactly $k$ roots, counting multiplicity, in $D$ and no roots on $S$. Then there is an $\epsilon>0$ such that if

$$
q(z)=b_{0}+b_{1} z+\ldots+b_{n} z^{n}
$$

is a polynomial satisfying

$$
\left|a_{j}-b_{j}\right|<\epsilon \quad \text { for } \quad j=0, \ldots, n
$$

then $q$ also has exactly $k$ roots, counting multiplicity, in $D$. Indeed, by Cauchy's formula the number of roots in $D$ of a polynomial $f$ with no roots in $S$ is expressed by the contour integral

$$
\frac{1}{2 \pi i} \oint_{S} \frac{f^{\prime}(z)}{f(z)} d z
$$

and the integral depends on $f$ continuously.
The following result was obtained by L. Gårding [Gå59]. We follow the exposition of J. Renegar [Re06].
(1.11) Theorem. Let $p: \mathbb{R}^{d} \longrightarrow \mathbb{R}$ be a homogeneous polynomial of degree $m>0$, hyperbolic in the direction of $u$. Suppose that $p(u) \neq 0$. Then
(1) The set $K(p, u)$ is the connected component of $\mathbb{R}^{d} \backslash\{x: p(x)=0\}$ that contains $u$;
(2) For any $v \in K(p, u)$, the polynomial $p$ is hyperbolic in the direction of $v$;
(3) For any $v \in K(p, u)$ we have $K(p, v)=K(p, u)$;
(4) The set $K(p, u)$ is convex.

Proof. We prove Part 1 first. Since $p(u-u)=0$ and $p(u) \neq 0$, the only root of the polynomial

$$
t \longrightarrow p(u-t u)=(1-t)^{m} p(u)
$$

is $t=1$. Hence $u \in K(p, u)$. Let $C$ be the connected component of $\mathbb{R}^{d} \backslash\{x: p(x)=$ $0\}$ that contains $u$. Since the roots of a polynomial depend continuously on the polynomial (Section 1.10), for all $x \in C$ the roots of the polynomial $t \longmapsto p(x-t u)$ are positive, which proves that $C \subset K(p, u)$. It remains to show that the set $K(p, u)$ is path-connected.

Let us choose any $v \in K(p, u)$ and any real $s \geq 0$. Then $v+s u \in K(p, u)$ since if $t_{0}$ is a root of the polynomial $t \longmapsto p(v+s u-t u)=p(v-(t-s) u)$ then $t_{0}-s$ is a root of the polynomial $t \longmapsto p(v-t u)$ and hence $t_{0}-s>0$. Then $t_{0}=\left(t_{0}-s\right)+s>0$.

Let us fix a $\gamma>0$ and let $v \in \mathbb{R}^{d}$ be a vector such that $\|v\| \leq \gamma$. For any $s>0$ we can write

$$
p(v+s u-t u)=s^{m} p\left(s^{-1} v+u-\left(t s^{-1}\right) u\right) .
$$

Since for any $s>0$ the only root of the polynomial

$$
t \longmapsto p\left(u-\left(t s^{-1}\right) u\right)
$$

is $t=s$ and

$$
\left\|s^{-1} v\right\| \leq \gamma / s \longrightarrow 0 \quad \text { as } \quad s \longrightarrow+\infty,
$$

by continuity (Section 1.10), we conclude that for all sufficiently large $s \geq s_{0}(\gamma)$ the roots of the polynomial

$$
t \longrightarrow p(v+s u-t u)
$$

are all positive and hence $v+s u \in K(p, u)$ for all sufficiently large $s \geq s_{0}(\gamma)$.
Now we are ready to present a path connecting any two points $v_{1}, v_{2} \in K(p, u)$. Let us choose a $\gamma>0$ such that $\left\|v_{1}\right\|,\left\|v_{2}\right\|<\gamma$. Then $\|v\|<\gamma$ for all $v \in\left[v_{1}, v_{2}\right]$ and let $s_{0}>0$ be a number such that $v+s_{0} u \in K(p, u)$ as long as $\|v\|<\gamma$. The path consists of the three intervals:

$$
\left[v_{1}, v_{1}+s_{0} u\right], \quad\left[v_{2}, v_{2}+s_{0} u\right] \quad \text { and } \quad\left[v_{1}+s_{0} u, v_{2}+s_{0} u\right],
$$

which concludes the proof of Part 1.

We prove Part 2 now. Let us choose any $x \in \mathbb{R}^{d}$ and consider the polynomial $t \longmapsto p(x-t v)$. We must show that it has real roots only. Let $i=\sqrt{-1}$ and $\alpha>0$. Fix a real $\beta>0$ and consider the polynomial

$$
\begin{equation*}
t \longmapsto p(\beta x-t v+\alpha i u) . \tag{1.11.1}
\end{equation*}
$$

We claim that if $t \in \mathbb{C}$ is a root of the polynomial (1.11.1) then $\Im t>0$ (the imaginary part of $t$ is positive). If $\beta=0$, we get the equation $p(\alpha i u-t v)=0$. We note that $t=0$ is not a root since $p(u) \neq 0$. By homogeneity, we can write the equation as $p\left(v-t^{-1} \alpha i u\right)=0$ and since $v \in K(p, u)$, for every root $t$ we must have $\alpha t^{-1} i$ real and positive, from which it follows that $t=\gamma i$ for some $\gamma>0$. Now, if $\Im t \leq 0$ for some $\beta_{0}>0$, by continuity (see Section 1.10), for some $\beta_{0}>\beta>0$ the polynomial (1.11.1) will have a real root $t$. That would mean that $-\alpha i$ is a root of the polynomial $s \longmapsto p(\beta x-t v-s u)$, which contradicts to the fact that $p$ is hyperbolic in the direction of $u$.

Choosing $\beta=1$ in (1.11.1), we conclude for all $\alpha>0$ the roots of the polynomial

$$
t \longrightarrow p(x-t v+\alpha i u)
$$

satisfy $\Im t>0$. Taking the limit as $\alpha \longrightarrow 0$, by continuity (Section 1.10), we conclude that $\Im t \geq 0$ for all roots $t$ of the polynomial $t \longmapsto p(x-t v)$, which proves that $p$ is hyperbolic in the direction of $v$, since complex roots of a real polynomial come in complex conjugate pairs $a \pm b i$.

Next, we prove Part 3. By Parts 1 and 2, both $K(p, u)$ and $K(p, v)$ are connected components of $\mathbb{R}^{d} \backslash\{x: p(x)=0\}$. Since $v \in K(p, u)$ and $v \in K(p, v)$, we must have $K(p, u)=K(p, v)$.

Finally, we prove Part 4. Let us choose any $v_{1}, v_{2} \in K(p, u)$ and let $v=\alpha v_{1}+$ $(1-\alpha) v_{2}$ for some $0 \leq \alpha \leq 1$. We have to prove $v \in K(p, u)$, that is, that the roots of the polynomial

$$
\begin{equation*}
t \longrightarrow p\left(\alpha v_{1}+(1-\alpha) v_{2}-t u\right) \tag{1.11.2}
\end{equation*}
$$

are positive. Since $v_{1} \in K(p, u)$, all roots of (1.11.2) are positive if $\alpha=1$. Since $v_{2} \in K(p, u)$, all roots of (1.11.2) are positive if $\alpha=0$. Suppose that for some $0<\alpha_{0}<1$ there is a non-positive root of (1.11.2). Since the roots of (1.11.2) are real for all real $\alpha$, by continuity (Section 1.10), there will be an $0<\alpha<1$ such that $t=0$ is a root of (1.11.2), that is,

$$
p\left(\alpha v_{1}+(1-\alpha) v_{2}\right)=0
$$

Then $s=(\alpha-1) / \alpha$ is a negative root of the polynomial

$$
\begin{equation*}
s \longmapsto p\left(v_{1}-s v_{2}\right) \tag{1.11.3}
\end{equation*}
$$

However, by Part 2, the polynomial $p$ is hyperbolic in the direction of $v_{2}$ and by Part 3, we have $K\left(p, v_{2}\right)=K(p, u)$, so $v_{1} \in K\left(p, v_{2}\right)$ and the roots of (1.11.3) are all positive.

## 2. Permanents and stable polynomials

We follow the exposition of L. Gurvits [Gu08].
(2.1) Definition. Let $A=\left(a_{i j}\right)$ be an $n \times n$ matrix and let $S_{n}$ be the symmetric group of all permutations of $\{1, \ldots, n\}$. The permanent of $A$ is defined by

$$
\operatorname{per} A=\sum_{\sigma \in S_{n}} \prod_{i=1}^{n} a_{i \sigma(i)}
$$

Another way to define per $A$ is as follows. Let $x_{1}, \ldots, x_{n}$ be variables and let us define a polynomial

$$
p\left(x_{1}, \ldots, x_{n}\right)=\prod_{i=1}^{n}\left(\sum_{j=1}^{n} a_{i j} x_{j}\right)
$$

Then

$$
\operatorname{per} A=\frac{\partial^{n}}{\partial x_{1} \cdots \partial x_{n}} p
$$

(2.2) Definition. Let $p: \mathbb{R}^{n} \longrightarrow \mathbb{R}$ be a real polynomial. We say that $p$ is stable if

$$
p\left(z_{1}, \ldots, z_{n}\right) \neq 0 \quad \text { provided } \quad \Im z_{1}, \ldots, \Im z_{n}>0
$$

(recall that $\Im z=b$ for $z=a+b i$ and $i=\sqrt{-1}$ ).
Suppose that $p$ is homogeneous. It is easy to see that $p$ is stable if and only if for any vector $u=\left(u_{1}, \ldots, u_{n}\right)$ where $u_{1}, \ldots, u_{n}>0$, the polynomial $p$ is hyperbolic in the direction of $u$. Indeed, let us choose an $x \in \mathbb{R}^{n}$, and consider the univariate polynomial

$$
\begin{equation*}
t \longmapsto p(x-t u), \tag{2.2.1}
\end{equation*}
$$

where $x=\left(x_{1}, \ldots, x_{n}\right), u=\left(u_{1}, \ldots, u_{n}\right)$ and $u_{j}>0$ for $j=1, \ldots, n$. If $p\left(z_{1}, \ldots, z_{n}\right)=0$ where $z_{j}=a_{j}+i b_{j}$ and $b_{j}>0$ for $j=1, \ldots, n$ then $t=-i$ is a root of (2.2.1) for $x_{j}=a_{j}$ and $u_{j}=b_{j}$, so $p$ is not hyperbolic in the direction of $u$. If the polynomial (2.2.1) has a root with $\Im t \neq 0$ then, since complex roots of real polynomials come in pairs of complex conjugates, $t=a+b i$ is root of (2.2.1) for some $a, b \in \mathbb{R}$ and $b<0$. Then $p\left(z_{1}, \ldots, z_{n}\right)=0$, where $z_{j}=\left(x_{j}-a u_{j}\right)-\left(b u_{j}\right) i$ for $j=1, \ldots, n$ and hence $p$ is not stable.
(2.3) Lemma. Let $p\left(x_{1}, \ldots, x_{n}\right)$ be a stable polynomial.
(1) Suppose that $p$ contains a monomial $\alpha x_{1}^{k}$ for some $\alpha \neq 0$ and $k>0$. Then the polynomial

$$
q=\frac{\partial}{\partial x_{1}} p
$$

is stable.
(2) Let $t \in \mathbb{R}$ be a number such that the polynomial

$$
r\left(x_{2}, \ldots, x_{n}\right)=p\left(t, x_{2}, \ldots, x_{n}\right)
$$

is non-constant. Then $r$ is stable.
Proof. To prove Part (1), let us fix any $z_{2}, \ldots, z_{n}$ such that $\Im z_{j}>0$ for $j=2, \ldots, n$ and consider a univariate polynomial

$$
f(z)=p\left(z, z_{2}, \ldots, z_{n}\right)
$$

Then $f$ is non-constant, and since $p$ is stable, all roots $z$ of $f$ satisfy the inequality $\Im z \leq 0$.

By the Gauss-Lucas Theorem, it follows that all roots $z$ of $f^{\prime}=q\left(z, z_{2}, \ldots, z_{n}\right)$ lie in the convex hull of the set of roots of $f$ and hence also satisfy the inequality $\Im z \leq 0$. Therefore,

$$
q\left(z_{1}, z_{2}, \ldots, z_{n}\right) \neq 0
$$

if $\Im z_{1}, \ldots, \Im z_{n}>0$, and hence $q$ is stable.
To prove Part (2), suppose that $r\left(z_{2}, \ldots, z_{n}\right)=0$ where $\Im z_{2} \ldots, \Im z_{n}>0$. Since $r$ is non-constant, for some $\left(\alpha_{2}, \ldots, \alpha_{n}\right) \in \mathbb{C}^{n-1} \backslash\{0\}$, the univariate polynomial

$$
f(z)=r\left(z_{2}+\alpha_{2} z, \ldots, z_{n}+\alpha_{n} z\right)=p\left(t, z_{2}+\alpha_{2} z, \ldots, z_{n}+\alpha_{n} z\right)
$$

is non-constant and $z=0$ is a root of $f$. By continuity (Section 1.10), for all sufficiently small $\epsilon>0$, the polynomial

$$
\tilde{f}(z)=p\left(t+i \epsilon, z_{2}+\alpha_{2} z, \ldots, z_{n}+\alpha_{n} z\right)
$$

has a root $w$ such that $\Im\left(z_{2}+\alpha w\right), \ldots, \Im\left(z_{n}+\alpha_{n} w\right)>0$, which contradicts the stability of $p$.
(2.4) Lemma. Suppose that a bivariate quadratic polynomial $p(x, y)=a x^{2}+$ $2 b x y+c y^{2}$ is stable. Then $b^{2} \geq a c$.

Proof. If $b^{2}<a c$ then the univariate polynomial $a x^{2}+2 b x+c$ has a pair of complex conjugate roots $\alpha \pm \beta i$ for some $\beta \neq 0$ (and hence we may assume that $\beta>0$ ). By continuity (Section 1.10), for a sufficiently small $\epsilon>0$, a point $y=1+\epsilon i, x=\tilde{\alpha}+\tilde{\beta} i$ with $\tilde{\beta}>0$ is a root of the polynomial $p(x, y)$, which contradicts the stability of $p$.

The following result is the consequence for permanents of the more general Alexandrov-Fenchel inequality for mixed volumes of convex bodies.
(2.5) Theorem. Let $A$ be an $n \times n$ non-negative matrix and let $a_{1}, \ldots, a_{n}$ be the columns of $A$. Then

$$
\operatorname{per}^{2}\left[a_{1}, \ldots, a_{n}\right] \geq \operatorname{per}\left[a_{1}, \ldots, a_{n-2}, a_{n-1}, a_{n-1}\right] \operatorname{per}\left[a_{1}, \ldots, a_{n-2}, a_{n}, a_{n}\right]
$$

Proof. By continuity, we may assume that the entries $a_{i j}$ of $A$ are positive. Suppose that $\Im z_{1}, \ldots, \Im z_{n}>0$ for some $z_{1}, \ldots, z_{n} \in \mathbb{C}$. Then

$$
\Im\left(\sum_{j=1}^{n} a_{i j} z_{j}\right)>0 \quad \text { and hence } \quad \sum_{j=1}^{n} a_{i j} z_{j} \neq 0
$$

Therefore,

$$
p\left(z_{1}, \ldots, z_{n}\right) \neq 0 \quad \text { for } \quad p\left(x_{1}, \ldots, x_{n}\right)=\prod_{i=1}^{n}\left(\sum_{j=1}^{n} a_{i j} x_{j}\right)
$$

and hence $p$ is a stable polynomial. Note that $p$ contains all monomials of degree $n$ with positive coefficients. Repeatedly applying Part (1) of Lemma 2.3, we conclude that the polynomial

$$
q=\frac{\partial^{n-2}}{\partial x_{1} \cdots \partial x_{n-2}} p
$$

is also stable. However, $q$ is a quadratic polynomial in $x_{n-1}$ and $x_{n-2}$ and it is not hard to see that

$$
q\left(x_{n-1}, x_{n}\right)=a x_{n-1}^{2}+2 b x_{n-1} x_{n}+c x_{n}^{2},
$$

where

$$
\begin{aligned}
a & =\frac{1}{2} \operatorname{per}\left[a_{1}, \ldots, a_{n-2}, a_{n-1}, a_{n-1}\right], \quad b=\frac{1}{2} \operatorname{per}\left[a_{1}, \ldots, a_{n}\right] \quad \text { and } \\
c & =\frac{1}{2} \operatorname{per}\left[a_{1}, \ldots, a_{n-2}, a_{n}, a_{n}\right] .
\end{aligned}
$$

The proof now follows by Lemma 2.4.

## 3. Stable polynomials and capacity

We follow L. Gurvits [Gu08].
(3.1) Definition. Let $p\left(x_{1}, \ldots, x_{n}\right)$ be a real polynomial with non-negative coefficients. The capacity of $p$ is defined as

$$
\operatorname{cap}(p)=\inf _{x_{1}, \ldots, x_{n}>0} \frac{p\left(x_{1}, \ldots, x_{n}\right)}{x_{1} \cdots x_{n}}
$$

(3.2) Lemma. Let $R(t)$ be a univariate polynomial of degree $k$ with non-negative coefficients such that all roots of $R$ are real. Then

$$
R^{\prime}(0) \geq\left(\frac{k-1}{k}\right)^{k-1} \operatorname{cap}(R)
$$

if $k>1$ and

$$
R^{\prime}(0)=\operatorname{cap}(R)
$$

if $k \leq 1$.
Proof. If $\operatorname{deg} R \leq 1$, so $R(t)=r_{0}+r_{1} t$ for some $r_{0}, r_{1} \geq 0$ then clearly

$$
\begin{equation*}
\inf _{t>0} t^{-1} R(t)=r_{1}=R^{\prime}(0) \tag{3.2.1}
\end{equation*}
$$

(the infimum is attained as $t \longrightarrow+\infty$ ) Suppose that $k \geq 2$. If $R(0)=0$, so $R(t)=r_{1} t+\ldots+r_{k} t^{k}$ for some non-negative $r_{1}, \ldots, r_{k}$, we still have (3.2.1), only that the infimum is attained as $t \longrightarrow 0$. Hence we can assume that $R(0)>0$, and, scaling $R$ if necessary, we assume that $R(0)=1$.

Since the coefficients of $R$ are non-negative, all roots are necessarily negative. Hence we can write

$$
R(t)=\prod_{i=1}^{k}\left(1+a_{i} t\right)
$$

for some $a_{1}, \ldots, a_{k}>0$. Then

$$
R^{\prime}(0)=\sum_{i=1}^{k} a_{i} .
$$

Applying the inequality between the arithmetic and geometric means, we conclude that

$$
R(t) \leq\left(1+\frac{a_{1}+\ldots+a_{k}}{k} t\right)^{k}=\left(1+\frac{R^{\prime}(0)}{k} t\right)^{k}
$$

Then

$$
\operatorname{cap}(R) \leq \inf _{t>0} g(t) \quad \text { where } \quad g(t)=t^{-1}\left(1+\frac{R^{\prime}(0)}{k} t\right)^{k}
$$

Clearly $g(t) \longrightarrow+\infty$ if $t \longrightarrow+\infty$ or if $t \longrightarrow 0$, so the infimum of $g(t)$ is attained at a critical point. Solving the equation $g^{\prime}(t)=0$, we obtain

$$
t=\frac{k}{(k-1) R^{\prime}(0)} \quad \text { and } \quad g(t)=\left(\frac{k}{k-1}\right)^{k-1} R^{\prime}(0)
$$

which proves that

$$
\operatorname{cap}(R) \leq\left(\frac{k}{k-1}\right)^{k-1} R^{\prime}(0)
$$

as desired.
(3.3) Remark. It is worth noting that

$$
g(k)=\left(\frac{k-1}{k}\right)^{k-1}
$$

is a decreasing function of $k>1$. Indeed, for

$$
f(x)=(x-1) \ln (x-1)-(x-1) \ln x
$$

we have

$$
f^{\prime}(x)=\ln \frac{x-1}{x}+\frac{1}{x}=\ln \left(1-\frac{1}{x}\right)+\frac{1}{x}<0 \quad \text { for } \quad x>1 .
$$

Therefore, in Lemma 3.2 we can write

$$
R^{\prime}(0) \geq\left(\frac{k-1}{k}\right)^{k-1} \operatorname{cap}(R) \quad \text { provided } \quad \operatorname{deg} R \leq k
$$

(3.4) Theorem. Let $p\left(x_{1}, \ldots, x_{n}\right)$ be stable polynomial of degree $n$ with nonnegative coefficients such that the coefficients of all monomials of degree $n$ are positive. Then

$$
\frac{\partial^{n}}{\partial x_{1} \cdots \partial x_{n}} p \geq \frac{n!}{n^{n}} \operatorname{cap}(p)
$$

Proof. We proceed by induction on $n$. For $n=1$ we have $p\left(x_{1}\right)=a x_{1}+b$ where $a>0, b \geq 0$ and hence $p^{\prime}=a$ and $\operatorname{cap}(p)=a$.

Suppose that $n>1$. Let us fix any $x_{2}, \ldots, x_{n}>0$ and consider the univariate polynomial $R(t)=p\left(t, x_{2}, \ldots, x_{n}\right)$. Then $\operatorname{deg} R=n$ and all roots of $R$ are necessarily real, since if $R(z)=0$ for some $z$ with $\Im z \neq 0$ and complex roots come in pairs of complex conjugates, we may assume that $\Im z>0$. Then, by continuity (Section 1.10), for a sufficiently small $\epsilon>0$ the polynomial $\tilde{R}(t)=p\left(t, x_{2}+i \epsilon, \ldots, x_{n}+i \epsilon\right)$ will have a root $\tilde{z}$ with $\Im \tilde{z}>0$, which contradicts the stability of $p$. By Lemma 3.2 , we have

$$
\begin{equation*}
\inf _{t>0} \frac{R(t)}{t} \leq\left(\frac{n}{n-1}\right)^{n-1} R^{\prime}(0) \tag{3.4.1}
\end{equation*}
$$

Let us define

$$
q=\frac{\partial p}{\partial x_{1}} \quad \text { and } \quad r\left(x_{2}, \ldots, x_{n}\right)=q\left(0, x_{2}, \ldots, x_{n}\right)
$$

Hence, by (3.4.1) we can write

$$
\begin{align*}
\operatorname{cap}(p) & =\inf _{x_{1}, \ldots, x_{n}>0} \frac{p\left(x_{1}, \ldots, x_{n}\right)}{x_{1} \cdots x_{n}} \\
& \leq\left(\frac{n}{n-1}\right)^{n-1} \inf _{x_{2}, \ldots, x_{n}>0} \frac{q\left(0, x_{2}, \ldots, x_{n}\right)}{x_{2} \cdots x_{n}}  \tag{3.4.2}\\
& =\left(\frac{n}{n-1}\right)^{n-1} \operatorname{cap}(r) .
\end{align*}
$$

By Part (1) of Lemma 2.3, the polynomial $q$ is stable and by Part (2) of Lemma 2.3, the polynomial $r$ is stable of degree $n-1$ such that the coefficients of all monomial of degree $n-1$ are positive. By the induction hypothesis

$$
\begin{equation*}
\operatorname{cap}(r) \leq \frac{(n-1)^{n-1}}{(n-1)!} \frac{\partial^{n-1}}{\partial x_{2} \cdots \partial x_{n}} r=\frac{(n-1)^{n-1}}{(n-1)!} \frac{\partial^{n}}{\partial x_{1} \cdots \partial x_{n}} p \tag{3.4.3}
\end{equation*}
$$

Combining (3.4.3) and (3.4.2), we conclude

$$
\operatorname{cap}(p) \leq\left(\frac{n}{n-1}\right)^{n-1} \frac{(n-1)^{n-1}}{(n-1)!} \frac{\partial^{n}}{\partial x_{1} \cdots \partial x_{n}} p=\frac{n^{n}}{n!} \frac{\partial^{n}}{\partial x_{1} \cdots \partial x_{n}} p
$$

and the proof follows.
(3.5) Remark. Suppose that $p\left(x_{1}, \ldots, x_{n}\right)$ is a stable homogeneous polynomial of degree $n$ with non-negative coefficients and that the degree of $p$ in $x_{i}$ is $k_{i}$ for $i=1, \ldots, n$. One can show that

$$
\begin{equation*}
\frac{\partial^{n}}{\partial x_{1} \cdots \partial x_{n}} p \geq \operatorname{cap}(p) \prod_{i=1}^{n}\left(\frac{k_{i}-1}{k_{i}}\right)^{k_{i}-1} \tag{3.5.1}
\end{equation*}
$$

Indeed, $p$ is hyperbolic in any direction $u=\left(u_{1}, \ldots, u_{n}\right)$ where $u_{1}, \ldots, u_{n}>0$ (see Definition 2.2) and hence by Theorem 1.11 so is its derivative $\partial p / \partial u$. To prove (3.5.1), in the proof of Theorem 3.4, instead of taking partial derivatives $\partial p / \partial x_{i}$, we take the derivative $\partial p / \partial u_{i}$, where the $i$-th coordinate of $u_{i}$ is 1 and all other coordinates are $\epsilon$ for some small $\epsilon>0$ and notice that the coefficients of monomials of $R(t)$ of degree higher than $k_{i}$ are $O(\epsilon)$, so taking the limit as $\epsilon \longrightarrow 0$, at the $i$-th step we can replace (3.4.1) by

$$
\inf _{t>0} \frac{R(t)}{t} \leq\left(\frac{k_{i}}{k_{i}-1}\right)^{k_{i}-1} R^{\prime}(0)
$$

## 4. CAPACITY, PERMANENTS, AND DOUBLY STOCHASTIC MATRICES

We recall the definition of a convex function.
(4.1) Definition. A function $f: \mathbb{R}^{d} \longrightarrow \mathbb{R}$ is called convex if

$$
\begin{aligned}
& f(\alpha x+(1-\alpha) y) \leq \alpha f(x)+(1-\alpha) f(y) \\
& \quad \text { for all } \quad x, y \in \mathbb{R}^{d} \quad \text { and all } \quad 0 \leq \alpha \leq 1
\end{aligned}
$$

(4.2) Lemma. Let $\lambda_{1}, \ldots, \lambda_{n}$ be reals and let $\alpha_{1}, \ldots, \alpha_{n}$ be positive reals. Then the function $f: \mathbb{R} \longrightarrow \mathbb{R}$,

$$
f(t)=\ln \left(\sum_{k=1}^{n} \alpha_{k} e^{\lambda_{k} t}\right)
$$

is convex.
Proof. It suffices to check that $f^{\prime \prime}(t) \geq 0$ for all $t \in \mathbb{R}$. Writing

$$
f(t)=\ln g(t) \quad \text { where } \quad g(t)=\sum_{k=1}^{n} \alpha_{k} e^{\lambda_{k} t}
$$

we compute

$$
f^{\prime}(t)=\frac{g^{\prime}(t)}{g(t)} \quad \text { and } \quad f^{\prime \prime}(t)=\frac{g^{\prime \prime}(t) g(t)-g^{\prime}(t) g^{\prime}(t)}{g^{2}(t)}
$$

Now,

$$
\begin{aligned}
g^{\prime \prime}(t) g(t)-g^{\prime}(t) g^{\prime}(t) & =\sum_{i, j=1}^{n} \lambda_{i}^{2} \alpha_{i} \alpha_{j} e^{\left(\lambda_{i}+\lambda_{j}\right) t}-\sum_{i, j=1}^{n} \lambda_{i} \lambda_{j} \alpha_{i} \alpha_{j} e^{\left(\lambda_{i}+\lambda_{j}\right) t} \\
& =\sum_{\substack{\{i, j\} \\
i \neq j}}\left(\lambda_{i}^{2}+\lambda_{j}^{2}-2 \lambda_{i} \lambda_{j}\right) \alpha_{i} \alpha_{j} e^{\left(\lambda_{i}+\lambda_{j}\right) t} \\
& =\sum_{\substack{\{i, j\} \\
i \neq j}}\left(\lambda_{i}-\lambda_{j}\right)^{2} \alpha_{i} \alpha_{j} e^{\left(\lambda_{i}+\lambda_{j}\right) t} \geq 0
\end{aligned}
$$

and the proof follows.
(4.3) Corollary. Let $p\left(x_{1}, \ldots, x_{n}\right)$ be a real polynomial with non-negative coefficients. Then the function $f: \mathbb{R}^{n} \longrightarrow \mathbb{R}$,

$$
f\left(t_{1}, \ldots, t_{n}\right)=\ln p\left(e^{t_{1}}, \ldots, e^{t_{n}}\right)
$$

is convex.
Proof. It suffices to prove that the restriction of $f$ onto every line in $\mathbb{R}^{n}$ is convex, that is,

$$
f\left(\alpha_{1}+\beta_{1} t, \ldots, \alpha_{n}+\beta_{n} t\right)=\ln p\left(e^{\alpha_{1}} e^{\beta_{1} t}, \ldots, e^{\alpha_{n}} e^{\beta_{n} t}\right)
$$

is a convex function of $t \in \mathbb{R}$. This follows now from Lemma 4.2.
(4.4) Definition. An $n \times n$ matrix $A=\left(a_{i j}\right)$ is called doubly stochastic if

$$
\begin{aligned}
& \sum_{j=1}^{n} a_{i j}=1 \quad \text { for } \quad i=1, \ldots, n, \quad \sum_{i=1}^{n} a_{i j}=1 \quad \text { for } \quad j=1, \ldots, n \text { and } \\
& \quad a_{i j} \geq 0 \quad \text { for all } i, j .
\end{aligned}
$$

(4.5) Lemma. Let $A=\left(a_{i j}\right)$ be an $n \times n$ doubly stochastic matrix and let

$$
p\left(x_{1}, \ldots, x_{n}\right)=\prod_{i=1}^{n}\left(\sum_{j=1}^{n} a_{i j} x_{j}\right)
$$

Then

$$
\operatorname{cap}(p)=1
$$

Proof. Since $p$ is a homogeneous polynomial of degree $n$, we can write

$$
\operatorname{cap}(p)=\inf _{\substack{x_{1}, \ldots, x_{n}>0 \\ x_{1} \cdots x_{n}=1}} p\left(x_{1}, \ldots, x_{n}\right) .
$$

Substituting $x_{i}=e^{t_{i}}$, we conclude that

$$
\begin{aligned}
\operatorname{cap}(p)= & \exp \left\{\inf _{t_{1}+\ldots+t_{n}=0} f\left(t_{1}, \ldots, t_{n}\right)\right\} \quad \text { where } \\
& f\left(t_{1}, \ldots, t_{n}\right)=\ln p\left(e^{t_{1}}, \ldots, e^{t_{n}}\right) .
\end{aligned}
$$

We claim that $t_{1}=\ldots=t_{n}=0$ is a critical point of $f$ on the hyperplane $t_{1}+\ldots+$ $t_{n}=0$. Computing the gradient of $f$ at $t_{1}=\ldots=t_{n}=0$, we obtain

$$
\frac{\partial f}{\partial t_{j}}=\sum_{i=1}^{n} \frac{a_{i j} e^{t_{j}}}{\sum_{j=1}^{n} a_{i j} e^{t_{j}}}
$$

and hence

$$
\left.\frac{\partial f}{\partial t_{j}}\right|_{t_{1}=\ldots=t_{n}=0}=\sum_{i=1}^{n} a_{i j}=1
$$

where in the first equality we used that the column sums of $A$ are 1's and in the second equality we used that the row sums of $A$ are 1's.

Hence the gradient of $f$ at $t_{1}=\ldots=t_{n}=0$ is orthogonal to the hyperplane $t_{1}+\ldots+t_{n}=0$ and so $t_{1}=\ldots=t_{n}=0$ is a critical point of $f(t)$ on the hyperplane. Since by Corollary 4.3 the function $f$ is convex, we conclude that $t_{1}=\ldots=t_{n}=0$ is the minimum point of $f$ on the hyperplane. Since $f(0, \ldots, 0)=0$, the proof follows.

Now we are ready to prove the famous van der Waerden inequality for permanents.
(4.6) Theorem. Let $A$ be an $n \times n$ doubly stochastic matrix. Then

$$
\operatorname{per} A \geq \frac{n!}{n^{n}}
$$

Proof. By continuity, without loss of generality we may assume that $a_{i j}>0$ for all $i, j$. We define the polynomial $p\left(x_{1}, \ldots, x_{n}\right)$ as in Lemma 4.5. As in the proof of Theorem 2.5, we establish that $p$ is stable. By Lemma 4.5 , we have $\operatorname{cap}(p)=1$, so by Theorem 3.4,

$$
\operatorname{per} A=\frac{\partial^{n}}{\partial x_{1} \cdots \partial x_{n}} p \geq \frac{n!}{n^{n}} \operatorname{cap}(p)=\frac{n!}{n^{n}} .
$$

(4.7) Remark. Suppose that $A$ is doubly stochastic and contains not more than $k$ non-zero entries in every column. Then the degree of $p$ in every variable $x_{1}, \ldots, x_{n}$ does not exceed $k$. Replacing every zero entry $a_{i j}$ by a small $\epsilon>0$, and running the proof of Theorem 3.4, we observe that in (3.4.1), the coefficients of $R(t)$ of degree $k+1$ and higher are all $O(\epsilon)$. Therefore, as $\epsilon \longrightarrow 0$, we can replace $\left(\frac{n}{n-1}\right)^{n-1}$ in (3.4.1) by $\left(\frac{k}{k-1}\right)^{k-1}$. Hence we get the inequality

$$
\operatorname{per} A \geq\left(\frac{k-1}{k}\right)^{(k-1) n}
$$

(A. Schrijver's bound), see also Remark 3.5.

## 5. Matrix scaling and permanents

(5.1) Theorem. Let $A=\left(a_{i j}\right)$ be an $n \times n$ matrix such that $a_{i j}>0$ for all $i, j$. Then there exists a doubly stochastic matrix $B=\left(b_{i j}\right)$ and positive $\lambda_{1}, \ldots, \lambda_{n}$ and $\mu_{1}, \ldots, \mu_{n}$ such that

$$
a_{i j}=b_{i j} \lambda_{i} \mu_{j} \quad \text { for all } \quad i, j .
$$

Proof. As in the proof of Lemma 4.5 , we define a function $f: \mathbb{R}^{n} \longrightarrow \mathbb{R}$ by

$$
f\left(t_{1}, \ldots, t_{n}\right)=\sum_{i=1}^{n} \ln \left(\sum_{j=1}^{n} a_{i j} e^{t_{j}}\right)
$$

and consider its minimum on the hyperplane $H \subset \mathbb{R}^{n}$ defined by the equation $t_{1}+\ldots+t_{n}=0$. First, we claim that the minimum of $f$ on $H$ is attained at some point. Let

$$
M=\max _{i, j} \ln \frac{f(0, \ldots, 0)}{a_{i j}}
$$

If $t_{j}>M$ for some $j$, we have $f\left(t_{1}, \ldots, t_{n}\right)>f(0, \ldots, 0)$. On the other hand, since $t_{1}+\ldots+t_{n}=0$, if $t_{j}<-n M$ for some $j$ then $t_{k}>M$ for some $k \neq j$. Hence the minimum of $f$ on the compact set

$$
\left\{\left(t_{1}, \ldots, t_{n}\right): \quad\left|t_{j}\right| \leq n M \quad \text { for } \quad j=1, \ldots, n\right\} \cap H
$$

is the minimum of $f$ on $H$.
Let $t^{*}=\left(t_{1}^{*}, \ldots, t_{n}^{*}\right)$ be the minimum point. Then the gradient of $f$ at $t^{*}$ should be proportional to the normal vector to $H$ and hence for some $\alpha$

$$
\begin{equation*}
\left.\frac{\partial f}{\partial t_{j}}\right|_{t=t^{*}}=\sum_{i=1}^{n} \frac{a_{i j} e^{t_{j}^{*}}}{\sum_{k=1}^{n} a_{i k} e^{t_{k}^{*}}}=\alpha \quad \text { for } \quad j=1, \ldots, n \tag{5.1.1}
\end{equation*}
$$

Since

$$
\sum_{j=1}^{n} \sum_{i=1}^{n} \frac{a_{i j} e^{t_{j}^{*}}}{\sum_{k=1}^{n} a_{i k} e^{t_{k}^{*}}}=n
$$

we conclude that $\alpha=1$.
Let us define

$$
\lambda_{i}=\sum_{k=1}^{n} a_{i k} e^{t_{k}^{*}} \quad \text { and } \quad \mu_{j}=e^{-t_{j}^{*}} \quad \text { for all } \quad i, j
$$

Then

$$
a_{i j}=b_{i j} \lambda_{i} \mu_{j} \quad \text { where } \quad b_{i j}=\frac{a_{i j} e^{t_{j}^{*}}}{\sum_{k=1}^{n} a_{i k} e^{t_{k}^{*}}}
$$

Clearly, $B=\left(b_{i j}\right)$ us a non-negative matrix and

$$
\sum_{j=1}^{n} b_{i j}=1 \quad \text { for } \quad i=1, \ldots, n
$$

From (5.1.1) with $\alpha=1$ we get

$$
\sum_{i=1}^{n} b_{i j}=1 \quad \text { for } \quad j=1, \ldots, n
$$

(5.2) Scaling and permanents. Given a positive $n \times n$ matrix $A$, let us compute the numbers $\lambda_{1}, \ldots, \lambda_{n}$ and $\mu_{1}, \ldots, \mu_{n}$ as in Theorem 5.1. Then

$$
\operatorname{per} A=\left(\prod_{i=1}^{n} \lambda_{i}\right)\left(\prod_{j=1}^{n} \mu_{j}\right) \operatorname{per} B
$$

and

$$
\frac{n!}{n^{n}} \leq \operatorname{per} B \leq 1
$$

This allows us to estimate per $A$ within a factor of $n!/ n^{n} \approx e^{-n}$.

## Exercises.

Prove that the numbers $\lambda_{1}, \ldots, \lambda_{n}$ and $\mu_{1}, \ldots, \mu_{n}$ in Theorem 5.1 are unique up to an obvious rescaling:

$$
\lambda_{i}:=\lambda_{i} \tau, \quad \mu_{j}=\mu_{j} \tau^{-1} \quad \text { for all } \quad i, j .
$$

This allows us to define a function $F$ on positive $n \times n$ matrices by

$$
F(A)=\left(\prod_{i=1}^{n} \lambda_{i}\right)\left(\prod_{j=1}^{n} \mu_{j}\right)
$$

Prove that $F$ is log-concave:

$$
F\left(\frac{1}{2} A+\frac{1}{2} B\right) \geq \sqrt{F(A) F(B)}
$$

for any two positive $n \times n$ matrices $A$ and $B$.

## 6. Ramifications: mixed discriminants

We follow mostly L. Gurvits and A. Samorodnitsky [GS02] and L. Gurvits [Gu08].
(6.1) Definition. Let $Q_{1}, \ldots, Q_{n}$ be $n \times n$ real symmetric matrices. Then

$$
p\left(x_{1}, \ldots, x_{n}\right)=\operatorname{det}\left(x_{1} Q_{1}+\ldots+x_{n} Q_{n}\right)
$$

is a homogeneous polynomial of degree $n$ and the mixed term

$$
\frac{\partial^{n}}{\partial x_{1} \cdots \partial x_{n}} p=D\left(Q_{1}, \ldots, Q_{n}\right)
$$

is called the mixed discriminant of $Q_{1}, \ldots, Q_{n}$.
(6.2) Lemma. Suppose that the matrices $Q_{1}, \ldots, Q_{n}$ are positive semidefinite. Then

$$
D\left(Q_{1}, \ldots, Q_{n}\right) \geq 0
$$

Proof. Since $D\left(Q_{1}, \ldots, Q_{n}\right)$ is a continuous function of $Q_{1}, \ldots, Q_{n}$, without loss of generality we may assume that $Q_{i} \succ 0$ for $i=1, \ldots, n$. We proceed by induction on $n$. Clearly, the statement is true for $n=1$. Suppose that $n>1$. Since $Q_{1} \succ 0$, we can write $Q_{1}=T T^{*}$ for some invertible $n \times n$ matrix $T$ and then

$$
D\left(Q_{1}, \ldots, Q_{n}\right)=(\operatorname{det} T)^{2} D\left(I, T^{-1} Q_{2}\left(T^{*}\right)^{-1}, \ldots, T^{-1} Q_{n}\left(T^{*}\right)^{-1}\right)
$$

where $I$ is an $n \times n$ identity matrix and the matrices $Q_{i}^{\prime}=T^{-1} Q_{i}\left(T^{*}\right)^{-1}$ are positive semidefinite. Thus is suffices to prove that

$$
D\left(I, Q_{2}, \ldots, Q_{n}\right)>0 \quad \text { whenever } \quad Q_{2}, \ldots, Q_{n} \succ 0
$$

It is not hard to see that

$$
D\left(I, Q_{2}, \ldots, Q_{n}\right)=\sum_{\substack{J \subset\{1, \ldots, n\} \\|J|=n-1}} D\left(Q_{2}(J), \ldots, Q_{n}(J)\right),
$$

where the sum is taken over all $(n-1)$-subsets of $\{1, \ldots, n\}$ and $Q_{i}(J)$ is the $(n-1) \times(n-1)$ submatrix of $Q_{i}$ consisting of the entries with the row and column in $J$. Since $Q_{i}(J) \succ 0$ provided $Q_{i} \succ 0$, the proof follows.

## Exercises.

1. Let $u_{1}, \ldots, u_{n}$ be vectors from $\mathbb{R}^{n}$. Prove that

$$
D\left(u_{1} \otimes u_{1}, \ldots, u_{n} \otimes u_{n}\right)=\left(\operatorname{det}\left[u_{1}, \ldots, u_{n}\right]\right)^{2}
$$

where $\left[u_{1}, \ldots, u_{n}\right]$ is the $n \times n$ matrix with columns $u_{1}, \ldots, u_{n}$.
2. Let $G$ be a connected graph with $n$ vertices and $m$ edges, colored with $n-1$ different colors. We introduce an arbitrary orientation on the edges of $G$ and define the incidence matrix of $G$ as an $n \times m$ matrix $A=\left(a_{i j}\right)$ where

$$
a_{i j}= \begin{cases}1 & \text { if vertex } i \text { is the beginning of edge } j \\ -1 & \text { if vertex } i \text { is the end of edge } j \\ 0 & \text { elsewhere }\end{cases}
$$

Let us remove an arbitrary row of $A$ and let $a_{1}, \ldots, a_{m}$ be the columns of the resulting matrix, interpreted as vectors from $\mathbb{R}^{n-1}$. For $k=1, \ldots, n-1$, let $J_{k} \subset\{1, \ldots, n\}$ be the set of edges of $G$ colored with the $k$-th color and let

$$
Q_{k}=\sum_{j \in J_{k}} a_{j} \otimes a_{j}
$$

Prove that $D\left(Q_{1}, \ldots, Q_{n-1}\right)$ is the number of spanning trees in $G$ having exactly 1 edge of each color.
(6.3) Lemma. Suppose that $Q_{1}, \ldots, Q_{n} \succ 0$. Then the polynomial

$$
p\left(x_{1}, \ldots, x_{n}\right)=\operatorname{det}\left(x_{1} Q_{1}+\ldots+x_{n} Q_{n}\right)
$$

is a stable homogeneous polynomial of degree $n$ and the coefficient of every monomial of $p$ of degree $n$ is positive.

Proof. Let us choose any $z_{1}, \ldots, z_{n}$ such that $\Im z_{j}>0$ for $j=1, \ldots, n$ and suppose that $p\left(z_{1} Q_{1}+\ldots+z_{n} Q_{n}\right)=0$. Then the matrix

$$
Q=\sum_{j=1}^{n} z_{j} Q_{j}
$$

is not invertible and hence there is a vector $x \in \mathbb{C}^{n} \backslash\{0\}$ such that $Q x=0$. Let us consider the standard inner product

$$
\langle x, y\rangle=\sum_{i=1}^{n} x_{i} \overline{y_{i}}
$$

in $\mathbb{C}^{n}$. Then

$$
0=\langle Q x, x\rangle=\sum_{i=1}^{n} z_{i}\left\langle Q_{i} x, x\right\rangle .
$$

On the other hand, $\left\langle Q_{i} x, x\right\rangle$ are positive real numbers and we obtain a contradiction.
The coefficient of $x_{1}^{\alpha_{1}} \cdots x_{n}^{\alpha_{n}}$ in $p\left(x_{1}, \ldots, x_{n}\right)$ is

$$
D(\underbrace{Q_{1}, \ldots, Q_{1}}_{\alpha_{1} \text { times }}, \ldots, \underbrace{Q_{n}, \ldots, Q_{n}}_{\alpha_{n} \text { times }})
$$

and hence by Lemma 6.2 is positive.
(6.4) Lemma. Let $Q_{1}, \ldots, Q_{n}$ be $n \times n$ positive definite matrices such that

$$
\sum_{i=1}^{n} Q_{i}=I \quad \text { and } \quad \operatorname{tr} Q_{i}=1 \quad \text { for } \quad i=1, \ldots, n
$$

Then, for

$$
p\left(x_{1}, \ldots, x_{n}\right)=\operatorname{det}\left(x_{1} Q_{1}+\ldots+x_{n} Q_{n}\right)
$$

we have

$$
\operatorname{cap}(p)=1
$$

Proof. Let us define $f: \mathbb{R}^{n} \longrightarrow \mathbb{R}$ by

$$
f\left(t_{1}, \ldots, t_{n}\right)=\ln \operatorname{det}\left(\sum_{i=1}^{n} e^{t_{i}} Q_{i}\right)
$$

and let $H \subset \mathbb{R}^{n}$ be the hyperplane defined by the equation $t_{1}+\ldots+t_{n}=0$. By Lemma 6.2 and Corollary 4.3, the function $f$ is convex. It suffices to prove that the minimum of $f$ on $H$ is attained at $t_{1}=\ldots, t_{n}=0$, for which it suffices to prove
that the gradient of $f$ at $t_{1}=\ldots=t_{n}=0$ is proportional to the vector $(1, \ldots, 1)$. Since

$$
\nabla(\ln \operatorname{det} X)=\left(X^{T}\right)^{-1}
$$

denoting

$$
S(t)=\sum_{i=1}^{n} e^{t_{i}} Q_{i}
$$

we conclude that

$$
\begin{equation*}
\frac{\partial f}{\partial t_{i}}=\left\langle e^{t_{i}} Q_{i}, S^{-1}(t)\right\rangle=e^{t_{i}} \operatorname{tr}\left(Q_{i} S^{-1}(t)\right) . \tag{6.4.1}
\end{equation*}
$$

Hence

$$
\left.\frac{\partial f}{\partial t_{i}}\right|_{t_{1}=\ldots=t_{n}=0}=1
$$

and the proof follows.
The following result confirms a conjecture of Bapat.
(6.5) Theorem. Let $Q_{1}, \ldots, Q_{n}$ be $n \times n$ positive semidefinite matrices such that

$$
\sum_{i=1}^{n} Q_{i}=I \quad \text { and } \quad \operatorname{tr} Q_{i}=1 \quad \text { for } \quad i=1, \ldots, n
$$

Then

$$
D\left(Q_{1}, \ldots, Q_{n}\right) \geq \frac{n!}{n^{n}}
$$

Proof. Without loss of generality we assume that $Q_{1}, \ldots, Q_{n} \succ 0$. The proof follows by Lemma 6.3, Theorem 3.4 and Lemma 6.4.

Here is a version of scaling for mixed discriminants.
(6.6) Theorem. Let $Q_{1}, \ldots, Q_{n}$ be $n \times n$ positive definite matrices. Then there are $n \times n$ positive definite matrices $B_{1}, \ldots, B_{n}$, an invertible $n \times n$ matrix $T$ and positive reals $\lambda_{1}, \ldots, \lambda_{n}$ such that

$$
\sum_{i=1}^{n} B_{i}=I, \quad \operatorname{tr} B_{i}=1 \quad \text { and } \quad Q_{i}=\lambda_{i} T B_{i} T^{*} \quad \text { for } \quad i=1, \ldots, n
$$

Proof. As in the proof of Lemma 6.4, we define a convex function

$$
f\left(t_{1}, \ldots, t_{n}\right)=\ln \operatorname{det}\left(\sum_{i=1}^{n} e^{t_{i}} Q_{i}\right)
$$

and the hyperplane $H$ defined by the equation $t_{1}+\ldots+t_{n}=0$. It is not hard to see (cf. the proof of Theorem 5.1) that $f$ attains its minimum on $H$ at some point $t_{1}^{*}, \ldots, t_{n}^{*}$, at which point the gradient of $f$ is proportional to the vector $(1, \ldots, 1)$. By (6.4.1), we obtain that for some $\alpha$ and

$$
S=\sum_{i=1}^{n} e^{t_{i}^{*}} Q_{i}
$$

we have

$$
\begin{equation*}
e^{t_{i}^{*}} \operatorname{tr}\left(Q_{i} S^{-1}\right)=\alpha \quad \text { for } \quad i=1, \ldots, n \tag{6.6.1}
\end{equation*}
$$

Since

$$
n \alpha=\sum_{i=1}^{n} e^{t_{i}^{*}} \operatorname{tr}\left(Q_{i} S^{-1}\right)=\operatorname{tr}\left(\sum_{i=1}^{n} e^{t_{i}^{*}} Q_{i} S^{-1}\right)=\operatorname{tr}\left(S S^{-1}\right)=n
$$

we conclude that

$$
\begin{equation*}
\alpha=1 \tag{6.6.2}
\end{equation*}
$$

Since $S \succ 0$, we can write $S=T T^{*}$ for an invertible $n \times n$ matrix $T$. Then

$$
\begin{equation*}
\operatorname{tr}\left(Q_{i} S^{-1}\right)=\operatorname{tr}\left(Q_{i}\left(T^{-1}\right)^{*} T^{-1}\right)=\left(T^{-1} Q_{i}\left(T^{-1}\right)^{*}\right) \tag{6.6.3}
\end{equation*}
$$

and we define

$$
B_{i}=e^{t_{i}^{*}} T^{-1} Q_{i}\left(T^{-1}\right)^{*} \quad \text { and } \quad \lambda_{i}=e^{-t_{i}^{*}} \quad \text { for } \quad i=1, \ldots, n
$$

Clearly, $B_{1}, \ldots, B_{n}$ are positive definite matrices and

$$
Q_{i}=\lambda_{i} T B_{i} T^{*} \quad \text { for } \quad i=1, \ldots, n
$$

By (6.6.1)-(6.6.3) we have

$$
\operatorname{tr} B_{i}=1 \quad \text { for } \quad i=1, \ldots, n
$$

Finally,

$$
\sum_{i=1}^{n} B_{i}=\sum_{i=1}^{n} e^{t_{i}^{*}} T^{-1} Q_{i}\left(T^{-1}\right)^{*}=T^{-1}\left(\sum_{i=1}^{n} e^{t_{i}^{*}} Q_{i}\right)\left(T^{-1}\right)^{*}=T^{-1} S\left(T^{*}\right)^{-1}=I
$$

We note that

$$
D\left(Q_{1}, \ldots, Q_{n}\right)=(\operatorname{det} T)^{2}\left(\prod_{i=1}^{n} \lambda_{i}\right) D\left(Q_{1}, \ldots, Q_{n}\right)
$$

## Exercise.

Prove that $D\left(Q_{1}, \ldots, Q_{n}\right) \leq 1$, where $Q_{1}, \ldots, Q_{n}$ are positive semidefinite matrices such that $Q_{1}+\ldots+Q_{n}=I$.

## 7. Upper bounds for permanents

Our goal is to prove the following inequality conjectured by Minc and proved by Bregman.
(7.1) Theorem. Let $A=\left(a_{i j}\right)$ be an $n \times n$ matrix such that $a_{i j} \in\{0,1\}$ for all $i$ and $j$ and let

$$
r_{i}=\sum_{j=1}^{n} a_{i j} \quad \text { for } \quad i=1, \ldots, n
$$

Then

$$
\operatorname{per} A \leq \prod_{i=1}^{n}\left(r_{i}!\right)^{1 / r_{i}}
$$

If all $r_{i}$ are equal, the inequality is sharp, as the example of a block-diagonal matrix with $n / r$ diagonal $r \times r$ blocks filled by 1's demonstrates.

The following corollary is due to A. Samorodnitsky.
(7.2) Corollary. Suppose that $A=\left(a_{i j}\right)$ is a stochastic $n \times n$ matrix, that is $a_{i j} \geq 0$ for all $i, j$ and

$$
\begin{equation*}
\sum_{j=1}^{n} a_{i j}=1 \quad \text { for all } \quad i=1, \ldots n \tag{7.2.1}
\end{equation*}
$$

Suppose further that

$$
\begin{equation*}
a_{i j} \leq \frac{1}{b_{i}} \quad \text { for } \quad j=1, \ldots, n \tag{7.2.2}
\end{equation*}
$$

and some positive integer $b_{1}, \ldots, b_{n}$. Then

$$
\operatorname{per} A \leq \prod_{i=1}^{n} \frac{\left(b_{i}!\right)^{1 / b_{i}}}{b_{i}}
$$

Proof. Let us fix all but the $i$-th row of an $n \times n$ matrix $A$. Then per $A$ is a linear function in $a_{i}=\left(a_{i 1}, \ldots, a_{i n}\right)$. Let us consider the polytope $P_{i}$ of all $n$-vectors $a_{i}=\left(a_{i 1}, \ldots, a_{i n}\right)$ such that (7.2.1) and (7.2.2) hold. Then the maximum of per $A$ on $P_{i}$ is attained at an extreme point of $P_{i}$, which necessarily has $a_{i j} \in\left\{0,1 / b_{i j}\right\}$ for all $j$. Indeed, if $0<a_{i j_{1}}<1 / b_{i}$ for some $j_{1}$ then there will be another $j_{2} \neq j_{1}$ such that $0<a_{i j_{2}}<1 / b_{i}$ (we use that $b_{i}$ is an integer) and the perturbation $a_{i j_{1}}:=a_{i j_{1}} \pm \epsilon, a_{i j_{2}}:=a_{i j_{2}} \mp \epsilon$ shows that $a_{i}$ is not an extreme point of $P_{i}$. Hence the maximum point of per $A$ on the matrices satisfying (7.2.1) and (7.2.2) is attained at a matrix $A$ where $a_{i j} \in\left\{0,1 / b_{i j}\right\}$ for all $i$ and $j$. Let $B$ be the matrix obtained from $A$ by multiplying the $i$-th row by $b_{i}$. Then

$$
\text { per } A=\left(\prod_{i=1}^{n} \frac{1}{b_{i}}\right) \text { per } B \quad \text { and } \quad \text { per } B \leq \prod_{i=1}^{n}\left(b_{i}!\right)^{1 / b_{i}}
$$

by Theorem 7.1.

## (7.3) Permanents of doubly stochastic matrices with small entries.

Together with the van der Waerden bound (Theorem 4.6), the Bregman-Minc bound (Theorem 7.1) implies that per $A$ does not vary much if $A$ is a doubly stochastic matrix with small entries. Indeed, suppose that $A$ is an $n \times n$ doubly stochastic matrix. Then, by Theorem 4.6, we have

$$
\ln \text { per } A \geq \ln \frac{n!}{n}=-n+O(\ln n) \quad \text { as } \quad n \longrightarrow+\infty
$$

by Stirling's formula. Suppose additionally that

$$
a_{i j} \leq \frac{1}{b} \quad \text { for all } \quad i, j
$$

and some positive integer $b$. Then, by Corollary 7.2,

$$
\ln \text { per } A \leq \frac{n}{b} \ln b!-n \ln b=-n+O\left(\frac{n \ln b}{b}\right) \quad \text { as } \quad b \longrightarrow+\infty
$$

In other words, the permanent of an $n \times n$ doubly stochastic matrix with uniformly small entries is close to $e^{-n}$.

We present A. Schriver's proof of Theorem 7.1 [Sc78].
(7.4) Lemma. For positive $t_{1}, \ldots, t_{r}$ we have

$$
\left(\sum_{i=1}^{r} t_{r}\right)^{\sum_{i=1}^{r} t_{r}} \leq\left(r^{\sum_{i=1}^{r} t_{r}}\right) \prod_{i=1}^{r} t_{i}^{t_{i}}
$$

Proof. We observe that $f(x)=x \ln x$ is convex for $x>0$. Indeed, $f^{\prime}(x)=\ln x+1$ and $f^{\prime \prime}(x)=1 / x>0$. Therefore,

$$
f\left(\frac{1}{r} \sum_{i=1}^{r} t_{i}\right) \leq \frac{1}{r} \sum_{i=1}^{r} f\left(t_{i}\right)
$$

Exponentiating both sides of the inequality, we get the desired result.
We will also use the following obvious row-expansion formula for the permanent.
(7.5) Lemma. Let $A=\left(a_{i j}\right)$ be an $n \times n$ matrix. For $1 \leq i, k \leq n$, let $A_{i k}$ be the $(n-1) \times(n-1)$ matrix obtained from $A$ by crossing out the $i$-th row and $k$-th column. Then, for any $1 \leq i \leq n$, we have

$$
\operatorname{per} A=\sum_{k=1}^{n} a_{i k} \operatorname{per} A_{i k} .
$$

(7.6) Proof of Theorem 7.1. We proceed by induction on $n$. The case of $n=1$ is clear. Suppose that $n>1$. Without loss of generality, we may assume that $\operatorname{per} A>0$. We bound the expression

$$
\begin{equation*}
(\operatorname{per} A)^{n \operatorname{per} A}=\prod_{i=1}^{n}(\operatorname{per} A)^{\operatorname{per} A} \tag{7.6.1}
\end{equation*}
$$

To bound the $i$-th factor in the product, we use the $i$-th row expansion together with Lemma 7.4. Since $a_{i k} \in\{0,1\}$, from Lemma 7.5 , we can write

$$
\operatorname{per} A=\sum_{k: a_{i k}=1} \operatorname{per} A_{i k} .
$$

Letting $t_{k}=$ per $A_{i k}$, from Lemma 7.4 we obtain

$$
\begin{equation*}
(\operatorname{per} A)^{\operatorname{per} A} \leq r_{i}^{\operatorname{per} A} \prod_{k: a_{i k}=1}\left(\operatorname{per} A_{i k}\right)^{\operatorname{per} A_{i k}} \tag{7.6.2}
\end{equation*}
$$

Let $S_{n}$ be the symmetric group of all permutations of the set $\{1, \ldots, n\}$ and let

$$
S=\left\{\sigma \in S_{n}: \quad a_{i \sigma(i)}=1 \quad \text { for } \quad i=1, \ldots, n\right\}
$$

be the set of all permutations contributing to per $A$. Then

$$
|S|=\operatorname{per} A \quad \text { and } \quad|\{\sigma \in S: \quad \sigma(i)=k\}|= \begin{cases}\operatorname{per} A_{i k} & \text { if } a_{i k}=1  \tag{7.6.3}\\ 0 & \text { if } a_{i k}=0\end{cases}
$$

It follows from (7.6.3) that

$$
\begin{equation*}
\prod_{\sigma \in S}\left(\prod_{i=1}^{n} r_{i} \operatorname{per} A_{i \sigma(i)}\right)=r_{i}^{\text {per } A} \prod_{k: a_{i k}=1}\left(\operatorname{per} A_{i k}\right)^{\operatorname{per} A_{i k}} \tag{7.6.4}
\end{equation*}
$$

Now we apply the induction hypothesis to each of the $(n-1) \times(n-1)$ matrix $A_{i \sigma(i)}$. The rows of $A_{i \sigma(i)}$ are obtained from the rows of $A$ by crossing out the $(j, \sigma(i))$-th entry of $A$ for $j \neq i$ and crossing out the $i$-th row entirely. Hence, applying the induction hypothesis, we obtain

$$
\left.\operatorname{per} A_{i \sigma(i)} \leq \prod_{\substack{j: j \neq i \\ a_{j \sigma(i)}=0}}\left(r_{j}!\right)^{1 / r_{j}} \prod_{\substack{j: j \neq i \\ a_{j \sigma(i)}=1}}\left(r_{j}-1\right)\right)^{1 /\left(r_{j}-1\right)}
$$

Let us fix any permutation $\sigma \in S$. Then

$$
\begin{equation*}
\left(\prod_{i=1}^{n} r_{i} \operatorname{per} A_{i \sigma(i)}\right) \leq \prod_{i=1}^{n}\left(r_{i} \prod_{\substack{j: j \neq i \\ a j \sigma(i)=0}}^{23}<~\left(r_{j}!\right)^{1 / r_{j}} \prod_{\substack{j: j \neq i \\ a_{j \sigma(i)}=1}}\left(r_{j}-1\right)!^{1 /\left(r_{j}-1\right)}\right) \tag{7.6.5}
\end{equation*}
$$

Now, for any $j=1, \ldots, n$ the number of indices $i \neq j$ such that $a_{j \sigma(i)}=0$ is precisely $n-r_{j}$ whereas the number of indices $i \neq j$ such that $a_{j \sigma(i)}=1$ is precisely $r_{j}-1$. Hence, for any $\sigma \in S$ we have

$$
\begin{align*}
& \prod_{i=1}^{n}\left(\begin{array}{rl}
r_{i} \prod_{\substack{j: j \neq i \\
a_{j \sigma(i)}=0}}\left(r_{j}!\right)^{1 / r_{j}} \prod_{\substack{j: j \neq i \\
a_{j \sigma(i)}=1}}\left(r_{j}-1\right)!^{1 /\left(r_{j}-1\right)}
\end{array}\right)  \tag{7.6.6}\\
= & \prod_{j=1}^{n}\left(r_{j}\left(r_{j}!\right)^{\left(n-r_{j}\right) / r_{j}}\left(r_{j}-1\right)!\right)=\prod_{j=1}^{n}\left(r_{j}!\right)^{n / r_{j}} .
\end{align*}
$$

Combining (7.6.1)-(7.6.6), we obtain

$$
(\operatorname{per} A)^{n \operatorname{per} A} \leq \prod_{\sigma \in S}\left(\prod_{j=1}^{n}\left(r_{j}!\right)^{n / r_{j}}\right)=\left(\prod_{j=1}^{n}\left(r_{j}!\right)^{1 / r_{j}}\right)^{n \operatorname{per} A}
$$

and the proof follows.

## References

[Gå59] L. Gårding, An inequality for hyperbolic polynomials, J. Math. Mech. 8 (1959), 957-965.
[Gu08] L. Gurvits, Van der Waerden/Schrijver-Valiant like conjectures and stable (aka hyperbolic) homogeneous polynomials: one theorem for all. With a corrigendum, Research Paper 66, 26 pp, Electron. J. Combin. 15 (2008).
[GS02] L. Gurvits and A. Samorodnitsky, A deterministic algorithm for approximating the mixed discriminant and mixed volume, and a combinatorial corollary, Discrete Comput. Geom. 27 (2002), 531-550.
[Re06] J. Renegar, Hyperbolic programs, and their derivative relaxations, Found. Comput. Math. 6 (2006), 59-79.
[Sc78] A. Schrijver, A short proof of Minc's conjecture, J. Combinatorial Theory Ser. A 25 (1978), 80-83.

