

Math 623 : Hw # 3

1(a) $r = 0.01 = 1\%$

(b) $E^Q[S(t)] = S_0 e^{rT} \Rightarrow S_0 = 99.75$

(c) $E^Q[dS(t)/S(t) | S_t, Y_t] = 0.01dt$
 $Var[dS_t / S_t | S_t, Y_t] = 0 + Y_t(\sqrt{(-0.7)^2 + 0.51})dt = Y_t dt$

(d) $E^Q[dY_t | S_t, Y_t] = 2(0.04 - Y_t)dt$
 $Var[dY_t | S_t, Y_t] = (0.2 * \sqrt{Y_t})^2 dt = 0.04Y_t dt$

(e) Consider equation $dS_t / S_t = 0.01dt + \sqrt{Y_t}(-0.7dW_t + \sqrt{0.51}dZ_t)$
 since dW_t and dZ_t are independent so they can be rewrite as dN
 where $N \sim NID(0, dt)$. Thus, this equation becomes
 $dS_t / S_t = 0.01dt + \sqrt{Y_t}dN_t$, which is the typical GBM stock process.
 That's why it is make sense to have Y_t as a square of volatility level at t .

(f) First, equation $dY_t = 2(0.04 - Y_t)dt + 0.2\sqrt{Y_t}dW_t$ is the mean reversion stochastic process, which process will be reverse to the level of $Y_t = 0.04$ or volatility = 0.2. Second, this process start at $Y_t = 0.04$, which means it is starting at the reversion level.

(g)
$$\rho = \frac{Cov(dY_t, dS_t / S_t)}{\sqrt{Var(dY_t)Var(dS_t / S_t)}}$$

$$Cov(dY_t, dS_t / S_t) = E[(dY_t - E[dY_t])(dS_t / S_t - E[dS_t / S_t])]$$

$$= E[(0.2\sqrt{Y_t}dW_t)(-0.7\sqrt{Y_t}dW_t + \sqrt{0.51Y_t}dZ_t)]$$

$$= -0.14Y_t dt$$

$$\rho = \frac{-0.14Y_t dt}{\sqrt{0.04Y_t dt} \sqrt{Y_t dt}} = -0.7$$

(h) Under recession, when stock price and return on stock fall down, stock volatility tends to be higher as confirmed by several empirical researches. That's why the relationship of stock return and volatility is negative sign.
 This also can be explained by leverage issue. The drop in stock returns (negative return) lead to increase in leverage of firm, which make the stock riskier. Consequently, volatility increases.
 Another explanation based on volatility feedback suggests that if volatility is priced, an anticipated increase in volatility raises the required return on equity, leading to an immediate stock price decline (negative return).

2 (a) $\Delta t = 0, \Delta t, 2\Delta t, \dots, 30\Delta t = T$ where $\Delta t = 3/360$, $T = 0.25$

$$\begin{cases} S_{t+\Delta t} = S_t + 0.01S_t\Delta t + \sqrt{Y_t}S_t(-0.7\sqrt{\Delta t}\xi_t + \sqrt{0.51\Delta t}\eta_t) \\ S_0 = 99.75 \end{cases}$$

where $\xi_t \sim NID(0,1)$, $\eta_t \sim NID(0,1)$ and independent of each other.

$$\begin{cases} Y_{t+\Delta t} = Y_t + 2(0.04 - Y_t)\Delta t + 0.2\sqrt{Y_t}\xi_t \\ Y_0 = 0.04 \end{cases}$$

where $\xi_t \sim NID(0,1)$

(b), (c), (d), (e), (f). See code below

(e) 1. Generate MN independent $N(0,1)$'s ξ_t and MN independent $N(0,1)$'s of η_t

2. First path use $\xi_1^{(1)}t, \xi_2^{(1)}t, \xi_3^{(1)}t, \dots, \xi_M^{(1)}t$

$\eta_1^{(1)}t, \eta_2^{(1)}t, \eta_3^{(1)}t, \dots, \eta_M^{(1)}t$

Second path use $-\xi_1^{(1)}t, -\xi_2^{(1)}t, -\xi_3^{(1)}t, \dots, -\xi_M^{(1)}t$

$-\eta_1^{(1)}t, -\eta_2^{(1)}t, -\eta_3^{(1)}t, \dots, -\eta_M^{(1)}t$

And so on....

3. Use the 2N paths generated above as before.

This technique uses the symmetric of the normal distribution to reduce the variance and time saving.

HW3 # 2b, 2c

clear

format long

%set variable

dt=1/120;

T=0.25;

J=T/dt+1;

%N no. of path

N=100000;

%implement in Euler scheme

s=zeros(J,N);

y=zeros(J,N);

%set initial value

s(1,:)=99.75;

```

y(1,:)=0.04;

%generate N random variables of z and w
z=randn(J-1,N);
w=randn(J-1,N);
for j=1:J-1

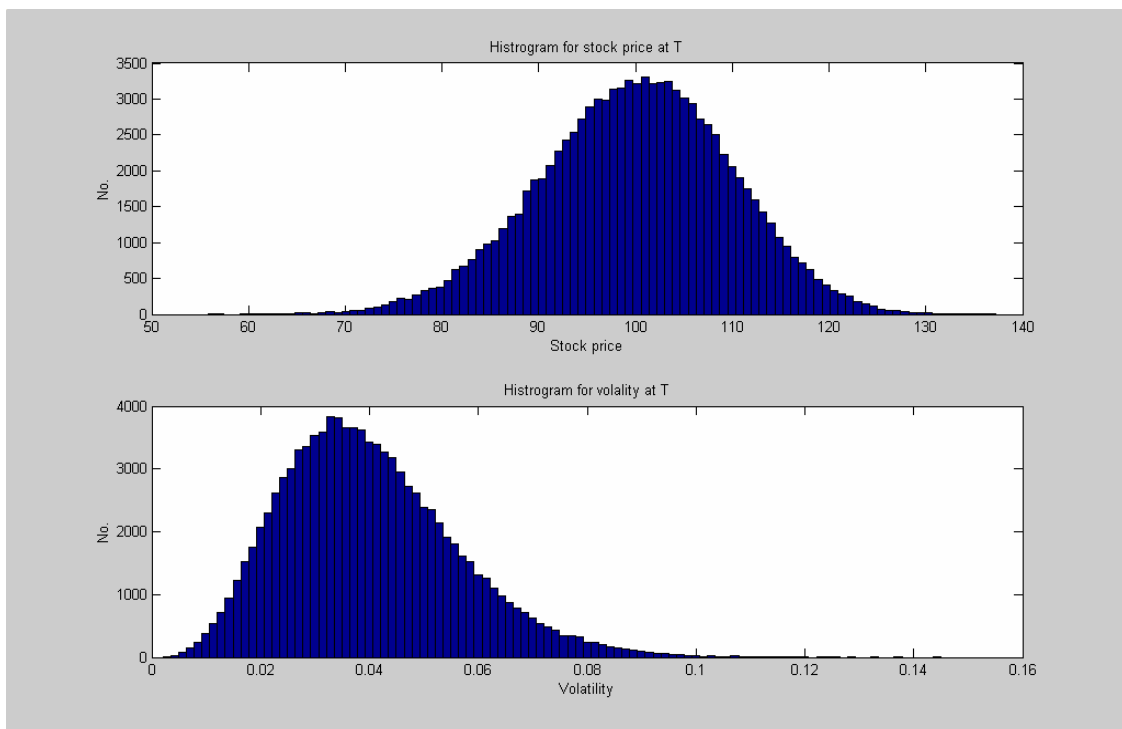
    y(j+1,:)= max(y(j,:),0) + 2*(0.04-max(y(j,:),0))*dt +
0.2*sqrt(max(y(j,:),0)*dt).*z(j,:);

    s(j+1,:)=max(s(j,:),0) + 0.01*max(s(j,:),0)*dt +
sqrt(max(y(j,:),0)).*max(s(j,:),0).*(-0.7*sqrt(dt).*z(j,:)...
+sqrt(0.51*dt).*w(j,:));
end

stock_price_at_t_025=(s(J,:));
mean(s(J,:))
volatility_at_t_025=(y(J,:));

%x=50:10:150;
subplot(2,1,1)
hist(s(J,:)',10)
subplot(2,1,2)
hist(y(J,:)',10)

```



HW3 # 2d

clear

format long

%set variable

dt=1/120;

T=0.25;

J=T/dt+1;

%N no. of path

N=100000;

%implement in Euler scheme

s=zeros(J,N);

y=zeros(J,N);

%set initial value

s(1,:)=99.75;

y(1,:)=0.04;

%error=zeros(N,1);

%verror=zeros(N,1);

%generate N random variables of z and w

z=randn(J-1,N);

w=randn(J-1,N);

for j=1:J-1

y(j+1,:)= max(y(j,:),0) + 2*(0.04-max(y(j,:),0))*dt +
0.2*sqrt(max(y(j,:),0)*dt).*z(j,:);

s(j+1,:)=max(s(j,:),0) + 0.01*max(s(j,:),0)*dt +
sqrt(max(y(j,:),0)).*max(s(j,:),0).*(-0.7*sqrt(dt).*z(j,:)...
+sqrt(0.51*dt).*w(j,:));

end

sT=s(J,:);

s_square=cumsum(sT.^2)./ [1:N];

mean_s=cumsum(sT)./ [1:N];

s_se=sqrt(1./ [1:N]).*sqrt(s_square - mean_s.^2);

vT=y(J,:);

mean_v=cumsum(vT)./ [1:N];

v_square=cumsum(vT.^2)./ [1:N];

v_se=sqrt(1./ [1:N]).*sqrt(v_square - mean_v.^2);

```

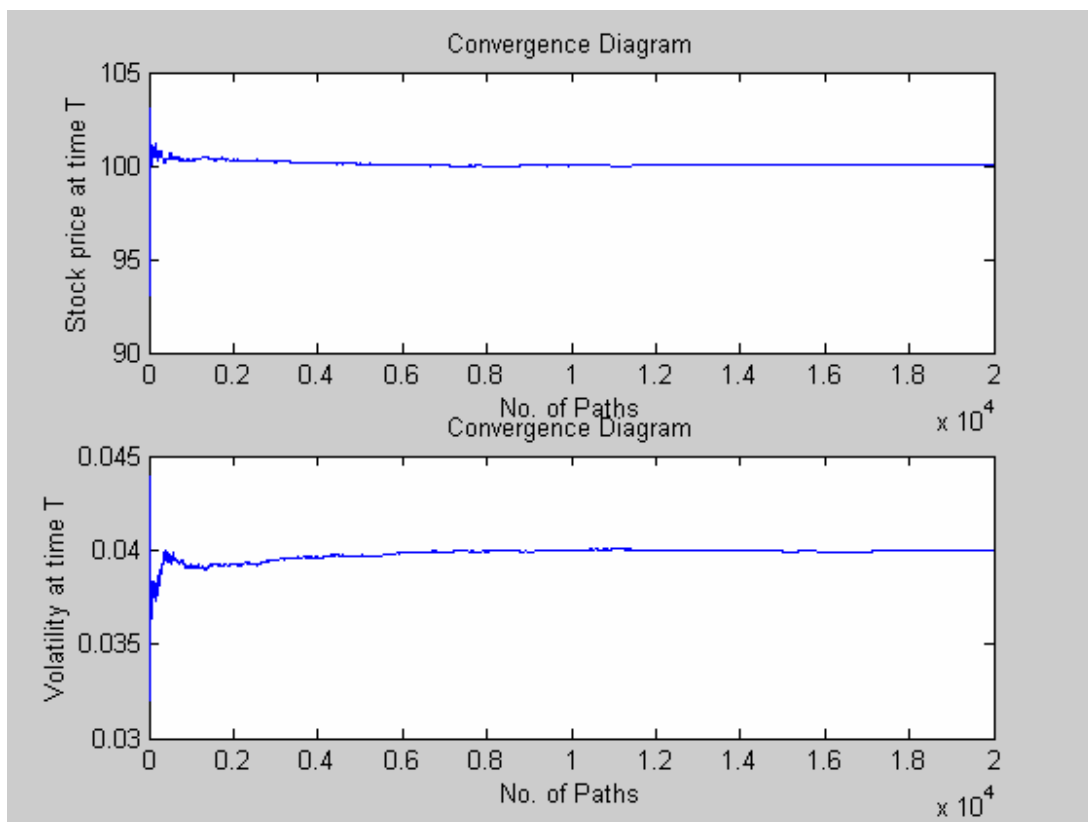
subplot(2,1,1)
plot(1:20000,mean_s(1:20000))
xlabel('No. of Paths')
ylabel('Stock price at time T')
Title('Convergence Diagram')

```

```

subplot(2,1,2)
plot(1:20000,mean_v(1:20000))
xlabel('No. of Paths')
ylabel('Volatility at time T')
Title('Convergence Diagram')

```



HW3 #2f

clear

format long

%set variable

dt=1/120;

T=0.25;

J=T/dt+1;

%N no. of path

N=100000;

%implement in Euler scheme

s=zeros(J,N);

y=zeros(J,N);

%set initial value

s(1,:)=99.75;

y(1,:)=0.04;

%generate N random variables of z and w

z1=randn(J-1,N/2);

z=[z1,-1*z1];

w1=randn(J-1,N/2);

w=[w1,-1*w1];

for j=1:J-1

y(j+1,:)= max(y(j,:),0) + 2*(0.04-max(y(j,:),0))*dt +
0.2*sqrt(max(y(j,:),0)*dt).*z(j,:);

s(j+1,:)=max(s(j,:),0) + 0.01*max(s(j,:),0)*dt +
sqrt(max(y(j,:),0)).*max(s(j,:),0).*(-0.7*sqrt(dt).*z(j,:)...
+sqrt(0.51*dt).*w(j,:));

end

sT=s(J,:);

s_square=cumsum(sT.^2)./[1:N];

mean_s=cumsum(sT)./[1:N];

s_se=sqrt(1./[1:N]).*sqrt(s_square - mean_s.^2);

vT=y(J,:);

mean_v=cumsum(vT)./[1:N];

v_square=cumsum(vT.^2)./[1:N];

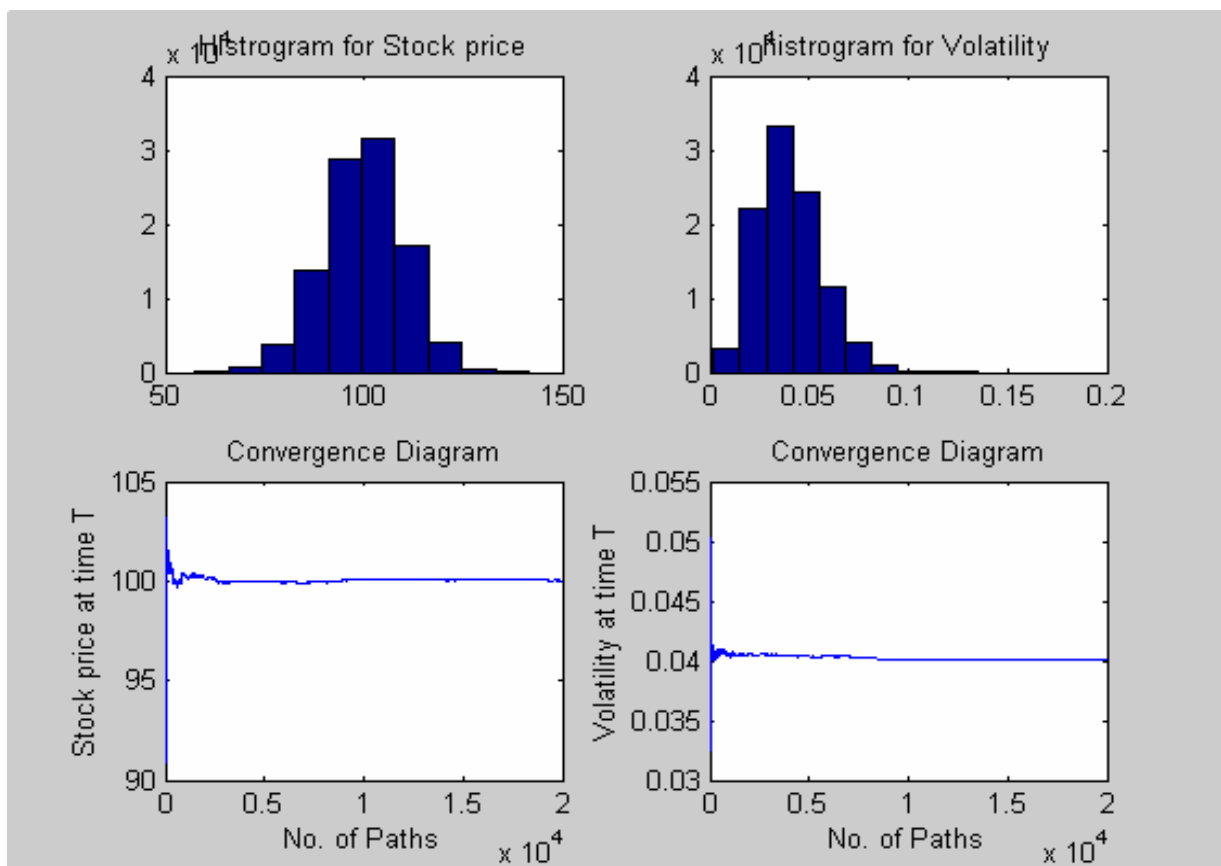
```
v_se=sqrt(1./[1:N]).*sqrt(v_square - mean_v.^2);
```

```
subplot(2,2,1)
hist(s(J,:)',10);
title('Histogram for Stock price')
```

```
subplot(2,2,2)
hist(y(J,:)',10);
title('histogram for Volatility')
```

```
subplot(2,2,3)
plot(1:20000,mean_s(1:20000))
xlabel('No. of Paths')
ylabel('Stock price at time T')
Title('Convergence Diagram')
```

```
subplot(2,2,4)
plot(1:20000,mean_v(1:20000))
xlabel('No. of Paths')
ylabel('Volatility at time T')
Title('Convergence Diagram')
```



3(a) $C_{BS}(S_0=99.75, r=1\%, K=100, T=0.25, \sigma=0.2) = \$ 3.978$

(b) Steps

1. Using the Euler scheme as in 2(a) and set of generated $S_{0.25}$ in 2(b) (suppose we use N paths)

2. At each $S_{T=0.25}$, calculate $C_{T=0.25} = (S_{T=0.25} - K)^+$

3. Discounted C_T to $C_{t=0}$ by equation $C_{t=0} = e^{-rT} C_{T=0.25}$

4. Calculate Monte Carlo estimate, $\bar{C} = \frac{1}{N} \sum C_{t=0}$

5. Standard Error = $\frac{1}{N} \sqrt{\frac{1}{N-1} \sum (C_{t=0} - \bar{C})^2}$

(c), (d). See code

HW3# 3b,3d

clear

format long

%set variable

dt=1/120;

T=0.25;

J=T/dt+1;

K=100;

%N no. of path

N=100000;

%implement in Euler scheme

s=zeros(J,N);

y=zeros(J,N);

%set initial value

s(1,:)=99.75;

y(1,:)=0.04;

%error=zeros(N,1);

%verror=zeros(N,1);

%generate N random variables of z and w

z=randn(J-1,N);

w=randn(J-1,N);

for j=1:J-1


```

y(j+1,:)= max(y(j,:),0) + 2*(0.04-max(y(j,:),0))*dt +
0.2*sqrt(max(y(j,:),0)*dt).*z(j,:);

```

```

s(j+1,:)=max(s(j,:),0) + 0.01*max(s(j,:),0)*dt +
sqrt(max(y(j,:),0)).*max(s(j,:),0).*(-0.7*sqrt(dt).*z(j,...
+sqrt(0.51*dt).*w(j,:));
end

```

```

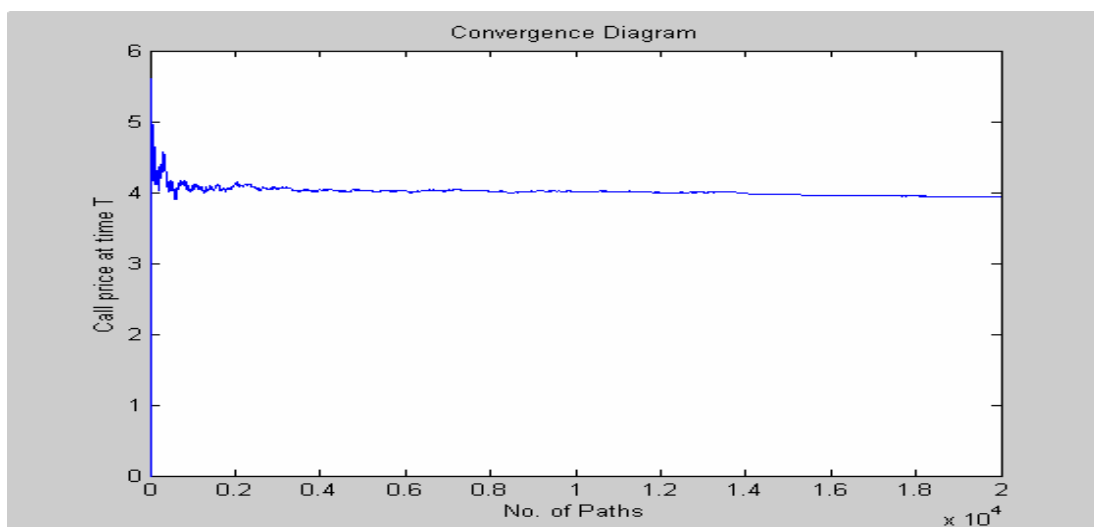
sT=s(J,:);
call=max(sT-K,0);
mean_c=cumsum(call)./1:N];
c_square=cumsum(call.^2)./1:N];
c_se=sqrt(1./1:N]).*sqrt(c_square - mean_c.^2);

```

```

plot(1:N,mean_c)
xlabel('No. of Paths')
ylabel('Call price at time T')
Title('Convergence Diagram')

```



HW3#3c,3d

clear

format long

%set variable

dt=1/120;

T=0.25;

J=T/dt+1;

K=100;

%N no. of path

N=100000;

%implement in Euler scheme

s=zeros(J,N);

y=zeros(J,N);

%set initial value

s(1,:)=99.75;

y(1,:)=0.04;

%error=zeros(N,1);

%verror=zeros(N,1);

%generate N random variables of z and w

z1=randn(J-1,N/2);

z=[z1,-1*z1];

w1=randn(J-1,N/2);

w=[w1,-1*w1];

for j=1:J-1

y(j+1,:)= max(y(j,:),0) + 2*(0.04-max(y(j,:),0))*dt +
0.2*sqrt(max(y(j,:),0)*dt).*z(j,:);

s(j+1,:)=max(s(j,:),0) + 0.01*max(s(j,:),0)*dt +
sqrt(max(y(j,:),0)).*max(s(j,:),0).*(-0.7*sqrt(dt).*z(j,:)...
+sqrt(0.51*dt).*w(j,:));

end

sT=s(J,:);

call=max(sT-K,0);

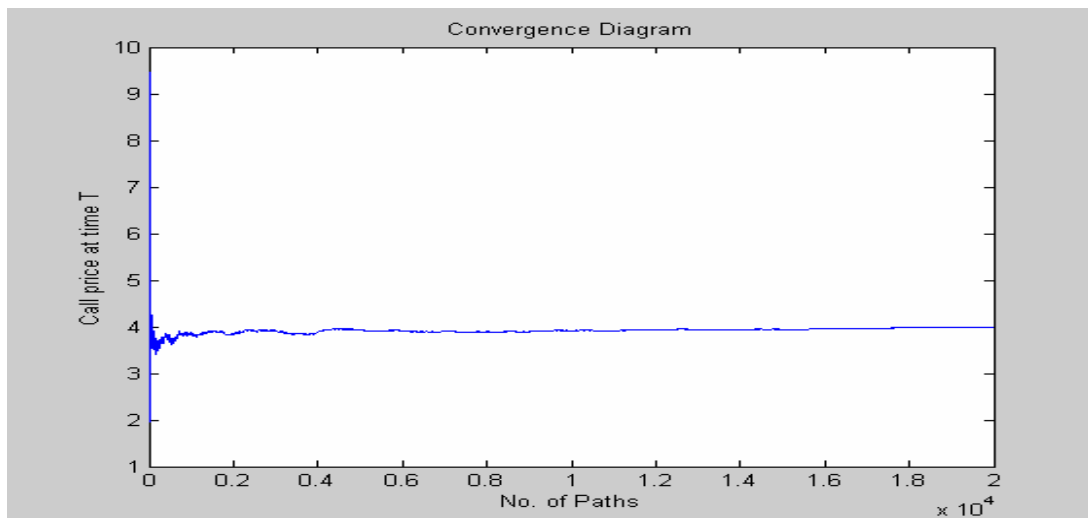
mean_c=cumsum(call)./ [1:N];

c_square=cumsum(call.^2)./ [1:N];

```
c_se=sqrt(1./[1:N]).*sqrt(c_square - mean_c.^2);
```

```
plot(1:N,mean_c)  
xlabel('No. of Paths')  
ylabel('Call price at time T')  
Title('Convergence Diagram')
```

```
implied_vol=blsimpv(S0,K,r,T,mean_c(N),1000)
```



$$4 \text{ (a)} \quad \frac{\partial C}{\partial t} + \frac{1}{2} Y S^2 \frac{\partial^2 C}{\partial S^2} + \rho \beta Y S \frac{\partial C}{\partial S \partial Y} + \frac{1}{2} \beta^2 Y \frac{\partial^2 C}{\partial Y^2} + r S \frac{\partial C}{\partial S} + K(\theta - Y) \frac{\partial C}{\partial Y} - rC = 0$$

where $K=2, \theta=0.04, \beta=0.2, \rho=-0.7, r=0.01$

Note: here K, θ, β are parameters from (Heston) stochastic volatility model

Terminal Condition

$$C(S, Y, T) = (S - \text{Strike})^+, \text{Strike} = 100$$

(b) Boundary Condition

$$S=0$$

$$C(S=0, Y, t) \approx 0$$

since it is likely that the stock will be in the money if $s=0$

$$S=S_{\max}=400$$

$$C(S=400, Y, t) = 400 - 100e^{-r(T-t)}$$

$Y=0$ use implicit boundary condition

$$\frac{\partial C}{\partial t} + rS \frac{\partial C}{\partial S} + K\theta \frac{\partial C}{\partial Y} - rC = 0$$

$Y=Y_{\max}=0.2$ use implicit boundary condition: full PDE

$$\frac{\partial C}{\partial t} + \frac{1}{2} Y_{\max} S^2 \frac{\partial^2 C}{\partial S^2} + \rho \beta Y_{\max} S \frac{\partial C}{\partial S \partial Y} + \frac{1}{2} \beta^2 Y_{\max} \frac{\partial^2 C}{\partial Y^2} + rS \frac{\partial C}{\partial S} + K(\theta - Y_{\max}) \frac{\partial C}{\partial Y} - rC = 0$$

(c) Grid: $t = 0, \Delta t, 2\Delta t, \dots, M\Delta t = T = 0.25$

$$S = 0, \Delta S, 2\Delta S, \dots, N\Delta S = S_{\max} = 400$$

$$Y = 0, \Delta Y, 2\Delta Y, \dots, J\Delta Y = Y_{\max} = 0.2$$

Approximation $C(n\Delta S, j\Delta Y, m\Delta t) \approx C_{n,j}^m$

Explicit Scheme

$$\begin{aligned} & \frac{C_{n,j}^m - C_{n,j}^{m-1}}{\Delta t} + \frac{1}{2} (j\Delta Y)(n\Delta S)^2 \frac{C_{n+1,j}^m - 2C_{n,j}^m - C_{n-1,j}^m}{2\Delta S} \\ & + \rho\beta(j\Delta Y)(n\Delta S) \frac{C_{n+1,j+1}^m - C_{n+1,j-1}^m - C_{n-1,j+1}^m + C_{n-1,j-1}^m}{4\Delta S \Delta Y} \\ & + \frac{1}{2} \beta^2 (j\Delta Y) \frac{C_{n,j+1}^m - 2C_{n,j}^m + C_{n,j-1}^m}{(\Delta Y)^2} + r(n\Delta S) \frac{C_{n+1,j}^m - C_{n-1,j}^m}{2\Delta S} + K(\theta - j\Delta Y) \frac{C_{n,j+1}^m - C_{n,j-1}^m}{2\Delta Y} \\ & - rC_{n,j}^m = 0 \end{aligned}$$

$$\Rightarrow C_{n,j}^{m-1} = p_1 C_{n+1,j-1}^m + p_2 C_{n,j-1}^m + p_3 C_{n-1,j-1}^m + p_4 C_{n+1,j}^m + p_5 C_{n,j}^m + p_6 C_{n-1,j}^m$$

$$p_7 C_{n+1,j+1}^m + p_8 C_{n,j+1}^m + p_9 C_{n-1,j+1}^m$$

$$\text{where } p_1 = \frac{-\rho\beta j_{\Delta t}}{4}, p_2 = \frac{\beta^2 j_{\Delta t} - K\theta_{\Delta t} + Kj_{\Delta Y}\Delta t}{2_{\Delta Y}}, p_3 = -p_1$$

$$p_4 = \frac{j_{\Delta Y}n^2_{\Delta t} + \Delta trn}{2}, p_5 = \frac{-j(\Delta Yn)^2_{\Delta t} - \beta^2 j_{\Delta t} - r_{\Delta Y}\Delta t + \Delta Y}{\Delta Y}$$

$$p_6 = \frac{j_{\Delta Y}n^2_{\Delta t} - \Delta trn}{2}, p_7 = p_3, p_8 = \frac{\beta^2 j_{\Delta t} + K\theta_{\Delta t} - Kj_{\Delta Y}\Delta t}{2_{\Delta t}}, p_9 = p_1$$

Boundary Condition

Y=0

$$\frac{C_{n,0}^m - C_{n,0}^{m-1}}{\Delta t} + r(n_{\Delta S}) \frac{C_{n+1,0}^m - C_{n-1,0}^m}{2_{\Delta S}} + K\theta \frac{3C_{n,0}^m - 4C_{n,1}^m + C_{n,2}^m}{2_{\Delta Y}} - rC_{n,0}^m = 0$$

$$\Rightarrow C_{n,0}^{m-1} = a_1 C_{n+1,0}^m + a_2 C_{n,0}^m + a_3 C_{n-1,0}^m + a_4 C_{n,1}^m + a_5 C_{n,2}^m$$

where

$$a_1 = \frac{rn_{\Delta t}}{2}, a_2 = \frac{2_{\Delta Y} - 3K\theta_{\Delta t} - 2r_{\Delta t}\Delta Y}{2_{\Delta Y}}, a_3 = -\frac{rn_{\Delta t}}{2}, a_4 = \frac{2K\theta_{\Delta t}}{\Delta Y}, a_5 = -\frac{K\theta_{\Delta t}}{2_{\Delta Y}}$$

Y=Ymax=0.2

$$\frac{C_{n,J}^m - C_{n,J}^{m-1}}{\Delta t} + \frac{1}{2}(J_{\Delta Y})(n_{\Delta S})^2 \frac{C_{n+1,J}^m - 2C_{n,J}^m - C_{n-1,J}^m}{2_{\Delta S}} + \rho\beta(J_{\Delta Y})(n_{\Delta S}) \frac{3(C_{n+1,J}^m - C_{n-1,J}^m) - 4(C_{n+1,J-1}^m - C_{n-1,J-1}^m) + (C_{n+1,J2}^m - C_{n-1,J-2}^m)}{4_{\Delta S}\Delta Y}$$

$$+ \frac{1}{2}\beta^2(J_{\Delta Y}) \frac{2C_{n,J}^m - 5C_{n,J-1}^m + 4C_{n,J-2}^m - C_{n,J-3}^m}{(\Delta Y)^2} + r(n_{\Delta S}) \frac{C_{n+1,J}^m - C_{n-1,J}^m}{2_{\Delta S}}$$

$$+ K(\theta - J_{\Delta Y}) \frac{3C_{n,J}^m - 4C_{n,J-1}^m + C_{n,J-2}^m}{2_{\Delta Y}} - rC_{n,J}^m = 0$$

$$\Rightarrow C_{n,J}^{m-1} = b_1 C_{n+1,J}^m + b_2 C_{n,J}^m + b_3 C_{n-1,J}^m + b_4 C_{n+1,J-1}^m + b_5 C_{n,J-1}^m + b_6 C_{n-1,J-1}^m$$

$$b_7 C_{n+1,J-2}^m + b_8 C_{n,J-2}^m + b_9 C_{n-1,J-2}^m + b_{10} C_{n,J-3}^m$$

where

$$b_1 = \frac{2_{\Delta t}J_{\Delta Y}n^2 + 3\rho\beta Jn_{\Delta t} + 2rn_{\Delta t}}{4}$$

$$b_2 = \frac{2_{\Delta Y} - 2_{\Delta t}J(\Delta Yn)^2 + 2\beta^2 J_{\Delta t} + 3K(\theta - J_{\Delta Y})_{\Delta t} - 2r_{\Delta t}\Delta Y}{2_{\Delta Y}}, b_3 = \frac{2_{\Delta t}J_{\Delta Y}n^2 - 3\rho\beta Jn_{\Delta t} - 2rn_{\Delta t}}{4}$$

$$b_4 = -\rho\beta Jn_{\Delta t}, b_5 = \frac{-5\beta^2 J_{\Delta t} - 4K(\theta - J_{\Delta Y})_{\Delta t}}{2_{\Delta Y}}, b_6 = \rho\beta Jn_{\Delta t}, b_7 = \frac{\rho\beta Jn_{\Delta t}}{4}$$

$$b_8 = \frac{4\beta^2 J_{\Delta t} - K(\theta - J_{\Delta Y})_{\Delta t}}{2_{\Delta Y}}, b_9 = -b_7, b_{10} = \frac{-\beta^2 J_{\Delta t}}{2_{\Delta Y}}$$

Terminal Condition

$$C_{n,j}^M = (n\Delta S - \text{Strike})^+$$

Procedure

- Compute C^M from Terminal Condition
- Successively compute $C^{M-1}, C^{M-2}, \dots, C^0$
- Compute C^{m-1} from C^m explicitly

HW3#4c-g

format long
clear

% variables

Smax=400;

ymax=0.2;

T=0.25;

r=0.01;

theta=0.04;

k=2;

B=0.2;

strike=100;

rho=-0.7;

%pick deltas arbitrary while deltay and deltat has to be picked carefully

ds= 5;

dy= 0.001;%round((ds*B^2*ymax)/(Smax*(ymax-r)+k*ymax-
ds*k*theta)*10000)/10000;

dt= 0.0001;%((dy*ds)^2)/(ymax*(dy*Smax)^2+(B*ds)^2*ymax+r*(dy*ds)^2);

%Grid

J=ymax/dy;

N=Smax/ds;

M=T/dt;

c=zeros(N+1,J+1,M+1);

s=[0:ds:Smax];

ss=s'*ones(1,J+1);

%Terminal Condition

c(:,J,M+1)= max(ss-strike,0);

%Boundary condition

%at s=0

c(1, :, :)=0;

```

%at s=400
t=[0:dt:T];
c(N+1,,:)=ones(J+1,1)*(Smax-strike.*exp(-r.*(T-t)));

nvec=[0:N]';
nmat=[0:N]'*ones(1,J+1);
jmat=ones(1,N+1)'*[0:J];

%coefficients for implicit boundary y=0
a1=r*nvec*dt/2;
a2=(2*dy-3*k*theta*dt-2*r*dt*dy)/(2*dy)*ones(N+1,1);
a3=-a1;
a4=(2*k*theta*dt)/(dy)*ones(N+1,1);
a5=(-k*theta*dt)/(2*dy)*ones(N+1,1);

%coefficients for implicit boundary y=ymax
b1=(2*dt*J*dy*nvec.^2+3*rho*B*J*nvec*dt+2*r*nvec*dt)/4;
b2=(2*dy-2*dt*J*(nvec*dy).^2+2*B^2*J*dt+3*k*(theta-J*dy)*dt-2*r*dt*dy)/(2*dy);
b3=(2*dt*J*dy*nvec.^2-3*rho*B*J*nvec*dt-2*r*nvec*dt)/4;
b4=-rho*B*J*nvec*dt;
b5=(-5*B^2*J*dt-4*k*(theta-J*dy)*dt)/(2*dy)*ones(N+1,1);
b6=-b4;
b7=b6/4;
b8=(4*B^2*J*dt+k*(theta-J*dy)*dt)/(2*dy)*ones(N+1,1);
b9=-b7;
b10=(-B^2*J*dt)/(2*dy)*ones(N+1,1);

%coefficients for explicit method
p1=-rho*B*jmat.*nmat*dt/4;
p2=((B^2)*jmat.*dt-k*theta*dt+k*jmat.*dy*dt)/(2*dy);
p3=rho*B*jmat.*nmat*dt/4;
p4=(jmat.*dy.*(nmat.^2)*dt+dt*r*nmat)/2;
p5=(-jmat.*((dy*nmat).^2)*dt-(B^2)*jmat*dt-r*dy*dt+dy)/dy;
p6=(jmat.*(nmat.^2)*dy*dt-dt*r*nmat)/2;
p7=p3;
p8=((B^2)*jmat*dt+k*theta*dt-k*jmat*dy*dt)/(2*dy);
p9=p1;

%calculate backward in time with implicit boundary condition
for m=M:-1:1

    %explicit method
    c(2:N,2:J,m)=p1(2:N,2:J).*c(3:N+1,1:J-1,m+1) + p2(2:N,2:J).*c(2:N,1:J-1,m+1)
    + p3(2:N,2:J).*c(1:N-1,1:J-1,m+1) + ...

```

```

        p4(2:N,2:J).*c(3:N+1,2:J,m+1) + p5(2:N,2:J).*c(2:N,2:J,m+1) +
p6(2:N,2:J).*c(1:N-1,2:J,m+1) + ...
        p7(2:N,2:J).*c(3:N+1,3:J+1,m+1) + p8(2:N,2:J).*c(2:N,3:J+1,m+1) +
p9(2:N,2:J).*c(1:N-1,3:J+1,m+1);

```

```

%implicit boundary for y=0

```

```

    c(2:N,1,m)=a1(2:N).*c(3:N+1,1,m+1) + a2(2:N).*c(2:N,1,m+1) +
a3(2:N).*c(1:N-1,1,m+1) + ...
        a4(2:N).*c(2:N,2,m+1) + a5(2:N).*c(2:N,3,m+1);

```

```

%implicit boundary for y=ymax

```

```

    c(2:N,J+1,m)=b1(2:N).*c(3:N+1,J+1,m+1) + b2(2:N).*c(2:N,J+1,m+1) +
b3(2:N).*c(1:N-1,J+1,m+1) +...
        b4(2:N).*c(3:N+1,J,m+1) + b5(2:N).*c(2:N,J,m+1) +
b6(2:N).*c(1:N-1,J,m+1) +...
        b7(2:N).*c(3:N+1,J-1,m+1) + b8(2:N).*c(2:N,J-1,m+1) +
b9(2:N).*c(1:N-1,J-1,m+1) +...
        b10(2:N).*c(2:N,J-2,m+1);

```

```

end

```

```

%call_price=c(100/ds+1,0.04/dy+1,1)

```

```

%4e

```

```

%mesh([0:dy:yymax]',[0:ds:Smax]','c(:,1))

```

```

%4f

```

```

%plot([0:ds:Smax]','c(:,0.04/dy+1,1),'r')

```

```

%hold

```

```

%plot([0:ds:Smax]','CBS(0.2,strike,[0:ds:Smax]','T,r),'--b')

```

```

4(g)

```

```

for i=1:N+1

```

```

    implied_vol(i)=blsimpv(ds*(i-1),strike,r,T,c(i,0.04/dy+1,1),100);

```

```

end

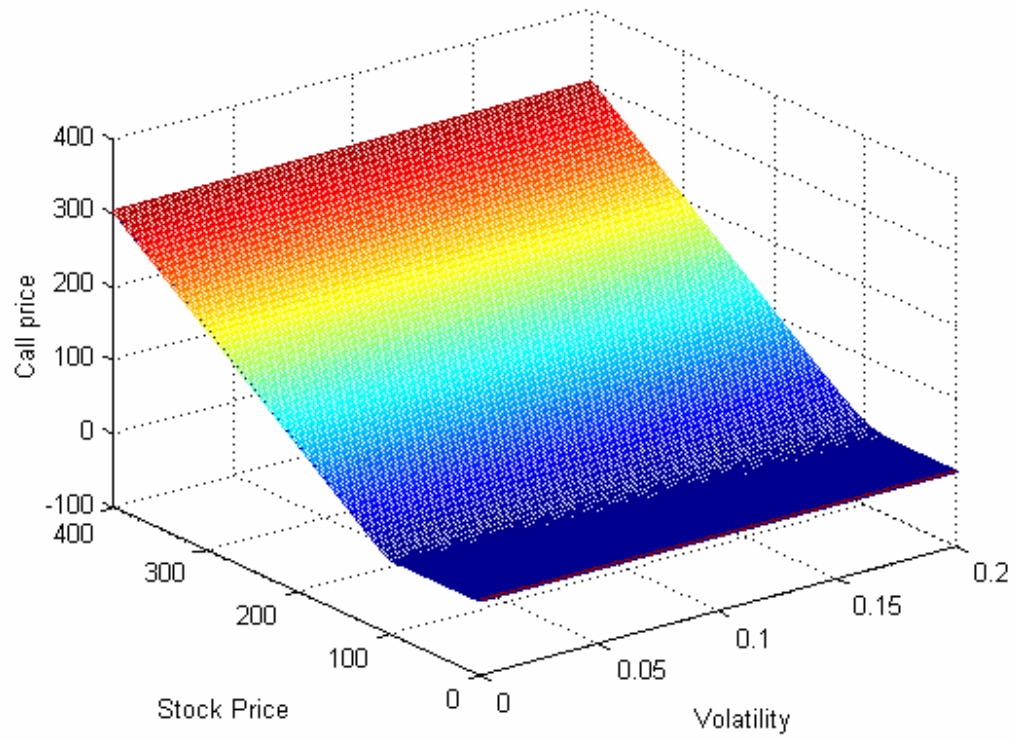
```

```

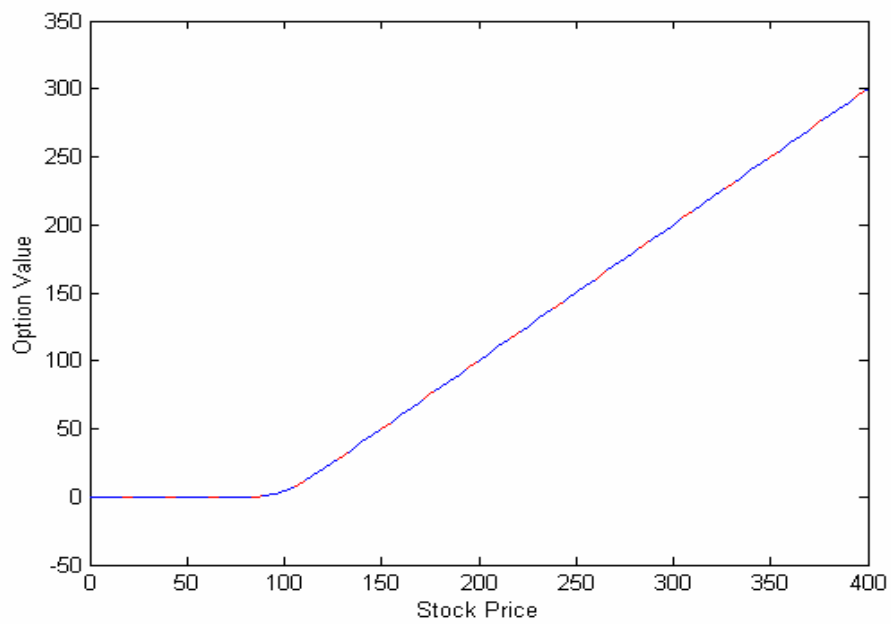
plot([0:ds:Smax]','implied_vol)

```


4(e)



4(f)



4(g)

