

1 Cones and near-cones

1.1 Cone points

Definition I. Let X be an abstract simplicial complex. A vertex v_0 of X is a *cone point* or *apex* of X if, for every simplex σ of X , the set $\{v_0\} \cup \sigma$ is a simplex of X . If X has a cone point, we call it a *cone*.

Equivalently, v_0 is a cone point of X if $X = \text{Star}_X(v_0)$. This implies (by Worksheet #12 Exercise 11)

$$X = v_0 \star \text{Lk}_X(v_0) = \text{Cone}(\text{Lk}_X(v_0)).$$

Notably, a complex with a cone point is contractible.

Exercise 1. (Bonus) Suppose that X has a cone point v_0 . Construct an explicit deformation retraction from X to v_0 , and verify that it is continuous.

Exercise 2. (Bonus) Show that every vertex of a simplex Δ^n is a cone point. In particular, a complex may have more than one distinct cone points.

Exercise 3. (Bonus) Let V be an infinite set, and let X be the ‘infinite simplex’ on V , i.e., the abstract simplicial complex for which all finite nonempty subsets $\sigma \subseteq V$ are simplices. Verify that X is contractible.

Exercise 4. Let X be a Δ -complex, and consider the analogous definition: Let v_0 be a vertex of X with the property that, for any simplex σ of X , either v_0 is vertex of σ , or $v_0 \star \sigma$ is a simplex of X . Show by example that X is not necessarily contractible.

1.2 Near-cones

The definition of a near-cone, and description of its homotopy type, are (mildly modified) from Björner–Kalai “An extended Euler–Poincaré theorem”.

Definition II. Let X be an abstract simplicial complex with vertex set $V(X)$, and let $v_0 \in V(X)$ be a distinguished vertex. The complex X is a *near-cone* if for every simplex σ , if $v_0 \notin \sigma$, then for any vertex $w \in \sigma$ the set $(\sigma \setminus \{w\}) \cup \{v_0\}$ is a simplex of X . For a near-cone X define the notation

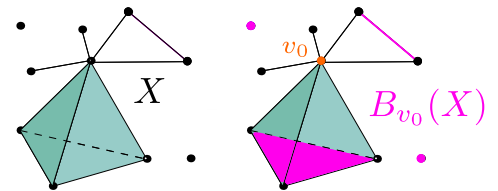
$$B_{v_0}(X) = \{\sigma \in S(X) \mid \sigma \cup \{v_0\} \notin S(X)\}$$

for the set of simplices of X not contained in $\text{Star}_X(v_0)$.

In other words, X is constructed by gluing each simplex in $B_{v_0}(X)$ to $\text{Star}_X(v_0)$ along its (entire) boundary. Since

$$X \simeq X/\text{Star}_X(v_0)$$

by Worksheet #3 Corollary VIII, we can deduce that X is homotopy equivalent to a wedge of spheres (of potentially different dimensions). A 2-dimensional near-cone X is shown.



Theorem III. Let X be a simplicial complex. If X is a near-cone with v_0 and $B_{v_0}(X)$ as in Definition II, then

$$X \simeq \bigvee_{\substack{\sigma \in B_{v_0}(X) \\ \dim(\sigma)=p}} S^p$$

In particular, the Betti numbers of X are determined by the formula

$$\text{rank} \left(\tilde{H}_p(X) \right) = \#\{\sigma \in B_{v_0}(X) \mid \dim(\sigma) = p\}.$$

Exercise 5. Let X be a near-cone. Show that every simplex of $B_{v_0}(X)$ is a maximal simplex (under inclusion) of X .

Exercise 6. (a) Prove [Theorem III](#). *Hint:* First verify $X = B^{v_0}(X) \cup (\{v_0\} * C)$ for a suitably-defined subcomplex C .

(b) Write down a formula for the Euler characteristics of X .

By Worksheet #7 Exercise 5 we know that the k -skeleton of an n -simplex is either contractible or homotopy equivalent to a wedge of k -spheres. The concept of a near-cone gives a convenient framework to compute its homotopy type: to reprove this fact, and determine the number of spheres.

Exercise 7. Let $n \geq 0$ and $0 \leq k \leq n$. Let $\Delta^{n,k} := (\Delta^n)^{(k)}$ denote the k -skeleton of an n -simplex.

(a) Determine the homotopy type of $\Delta^{n,k}$.

(b) Describe a basis for $H_k(\Delta^{n,k})$ of simplicial k -cycles.

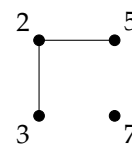
(c) **(Bonus)** The action of the symmetric group on the vertex set $[n + 1]$ of Δ^n extends to a simplicial action on its k -skeleton $\Delta^{n,k}$. What can you say about the homology group $H_k(\Delta^{n,k})$ —or the rational homology group $H_k(\Delta^{n,k}; \mathbb{Q})$ —as an S_{n+1} -representation?

Exercise 8. (Bonus) Let $n \geq 0$ and $0 \leq k \leq n$.

(a) Let X be a k -skeleton $(\text{sd}(\Delta^n))^{(k)}$ of the barycentric subdivision $\text{sd}(\Delta^n)$ of Δ^n . Is X a near-cone?

(b) Let X be the barycentric subdivision $\text{sd}(\Delta^{n,k})$ of the k -skeleton $\Delta^{n,k}$ of Δ^n . Is X a near-cone?

Björner gives another application of this concept in “A cell complex in number theory” (Theorem 3.1). Fix $n \geq 0$, and recall from Worksheet #11 Section 1.4 that Δ_n is the abstract simplicial complex with vertices the set of positive primes $p \leq n$, and with simplices $\{p_0, p_1, \dots, p_k \mid p_0 p_1 \cdots p_k \leq n\}$. We can identify $\text{sd}(\Delta_n)$ with the order complex of the poset of squarefree integers $\leq n$ ordered by divisibility. The complex Δ_{10} is shown.



Björner relates the Euler characteristics of the complexes Δ_n to deep results and conjectures in number theory, including the Prime Number Theorem and the Riemann Hypothesis.

Exercise 9. (Bonus) Draw Δ_{15} , Δ_{20} , and Δ_{30} .

Exercise 10. Give a description of the homotopy type and the Euler characteristic of Δ_n .