## Math 471 Fall 2009 Homework 5 due: Fri Nov 13

1. Find the eigenvalues and eigenvectors of the following matrices. Do this by hand, but you may check your answers using Matlab.

a) 
$$\begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}$$
 b)  $\begin{pmatrix} 0 & 2 \\ 1 & 0 \end{pmatrix}$  c)  $\begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$  d)  $\begin{pmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{pmatrix}$  e)  $\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ 

## section 3.7, special matrices

2. Show that the following matrices are positive definite.

a) 
$$\begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}$$
 b)  $\begin{pmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{pmatrix}$ 

## section 3.8, iterative methods

3. Consider 
$$Ax = b$$
, where  $A = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$ ,  $b = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ .

a) In class we showed that the error in the Gauss-Seidel method is given by

$$e_k = \left(\frac{1}{4}\right)^k \begin{pmatrix} 2\\1 \end{pmatrix},$$

for  $k \geq 1$ , using the eigenvalues and eigenvectors of the iteration matrix  $B_{GS}$ . Following the same procedure, derive an analogous expression for the error in Jacobi's method. Assume that the starting guess is the zero vector.

b) Use Matlab to plot  $\rho(B_w)$ , the spectral radius of the SOR iteration matrix, for  $0 \le \omega \le 2$ . Use the commands **eig**, **abs**, **max** to produce the plot. Make sure to use a fine enough mesh in the variable  $\omega$  to resolve the details of the function (1000 points on the interval  $0 \le \omega \le 2$  is sufficient.) This plot is typical for the type of matrices appearing in Young's theorem. Suppose we don't know the exact value of the optimal SOR parameter - in using an approximate value for the iterative method, is it better to overestimate or underestimate the value of  $\omega_*$ ? Explain the reason behind your answer.

4. Consider the iteration  $x_{k+1} = Bx_k + c$  and assume that  $||B|| = \alpha < 1$ . We know that the error satisfies  $||x - x_{k+1}|| \le \alpha ||x - x_k||$ , which is an important theoretical error bound, but the right side cannot be computed in practice because although we know  $x_k$ , we don't know x. Here we derive an alternative error bound that can be computed in practice.

- a) Show that I B is invertible and that  $||(I B)^{-1}|| \leq \frac{1}{1-\alpha}$ .
- b) Show that  $||x x_{k+1}|| \le \frac{\alpha}{1-\alpha} ||x_{k+1} x_k||$ .

Note: this bound can be computed because we know  $x_{k+1}$  and  $x_k$ .