## Open Mapping Theorem

## 1 Definiton and statement.

Definition 1.1. A map from an open set $\Omega \subset \mathbb{C}$ to $\mathbb{C}$ is an open mapping when the image by $f$ of any open subset of $\Omega$ is open.

Proposition 1.1. A map is open if and only if for each $z \in \Omega$ the image of any open set containing $z$ contains a neighborhood of $f(z)$.

Exercise 1.1. Prove this proposition.
Examples 1.1. 1. The map $f(z)=a z+b$ with $a, b \in \mathbb{C}$ is open when $a \neq 0$ and not open when $a=0$.
2. The map

$$
x+i y \mapsto\left(\begin{array}{ll}
m_{11} & m_{12} \\
m_{21} & m_{22}
\end{array}\right) \quad(x, y)
$$

is open when the matrix $M$ is invertible and not open otherwise. The same is true of $a \bar{z}+b$.
3. If $f$ is analytic with $f^{\prime}(z) \neq 0$ at all $z$ then $f$ is locally invertible by the inverse function theorem so satisfies the criterion of Proposition 1.1.
4. The mapping $f(z)=z^{k}$ with $k \geq 1$ integer is open. To prove this it suffices to show that the image by $f$ of a small open set about $z=0$ contains a neighborhood of 0 . For that it suffices to observe that the image by $f$ of $\{|z|<r\}$ is exactly the disk of radius $r^{1 / k}$. Each point in the latter disk has $k$ preimages in the former disk located at the vertices of regular $k$-gon.
5. The map $x+i y \mapsto x^{2}+i y$ is not open. The image of the open set $\mathbb{C}$ is not open. The restriction of this map to any set $\Omega$ that does not meet the imaginary axis is an open mapping. The mapping is not analytic.

Proposition 1.2. The composition of open maps is open. Precisely, if $g$ is open on $\Omega_{1}, f$ is open on $\Omega_{2}$ and $g\left(\Omega_{1}\right) \subset \Omega_{2}$ then $f(g(z))$ is open on $\Omega_{1}$.

Exercise 1.2. Prove this proposition.
Theorem 1.3. If $f(z)$ is a nonconstant analytic on an open connected set $\Omega$, then $f$ is an open mapping.

## 2 Proof of the Open Mapping Theorem.

Proof. Verify the condition of Proposition 1.3. At $\underline{z} \in \Omega$ where $f^{\prime}(\underline{z}) \neq 0$ the map is locally invertible and the condition is automatic.
Suppose on the other hand that $\underline{z} \in \Omega$ and $f^{\prime}(\underline{z})=0$. Since $f$ is not constant there is a smallest $k \geq 2$ so that $f^{(k)}(\underline{z}) \neq 0$. Taylor's theorem yields for $z$ near $\underline{z}$

$$
f(z)-f(\underline{z})=c_{k}(z-\underline{z})^{k}+c_{k+1}(z-\underline{z})^{k+1}+\cdots \quad c_{k} \neq 0 .
$$

Factor to find

$$
f(z)=c_{k}(z-\underline{z})^{k}\left(1+a_{1}(z-\underline{z})+a_{2}(z-\underline{z})^{2}+\cdots\right):=c_{k}(z-\underline{z})^{k} h(z),
$$

with

$$
h(z):=1+a_{1}(z-\underline{z})+a_{2}(z-\underline{z})^{2}+\cdots .
$$

Then $h$ is analytic as the sum of a convergent power series.
Define $g(w)$ on a neighborhood of $w=1$ to be a local inverse of the map $w=z^{k}$ on a neighborhood of $z=1$ where the derivative $w^{\prime}(1)=k \neq 0$. Then $g^{\prime}(1)=1 / k, g(h(z))^{k}=h(z)$ for $z$ near 1 , and

$$
\begin{equation*}
f(z)-f(\underline{z})=c_{k}((z-\underline{z}) g(h(z)))^{k} . \tag{2.1}
\end{equation*}
$$

Since

$$
\left.\frac{d}{d z}((z-\underline{z}) g(h(z)))\right|_{z=\underline{z}}=g(h(\underline{z}))=1 \neq 0,
$$

is follows that the map $z \mapsto(z-\underline{z}) g(h(z))$ is open on a neighborhood of $\underline{z}$. Therefore equation (2.1) expresses $f$ as the composition of the mappings $(z-\underline{z}) g(h(z)), z^{k}$ and $z \mapsto c_{k} z+f(\underline{z})$. Thus the image by $f$ of an open set containing $\underline{z}$ contains an open neighborhood of $f(\underline{z})$ verifying the criterion of Proposition 1.3 at points where $f^{\prime}$ vanishes

Remark 2.1. Examining (2.1) one sees that the preimage of a point $w \approx$ $f(\underline{z})$ consists of $k$ points near $\underline{z}$ nearly positioned at the vertices of a regular $k$-gon centered at $\underline{z}$. In this sense the behavior of $f-f(\underline{z})$ near $\underline{z}$ is well modelled by the $k$ to one open mapping $c_{k}(z-\underline{z})^{k}$.

