

This Gårding inequality has been improved to a sharp Gårding inequality, of the form

$$(6.7) \quad \operatorname{Re} (p(x, D)u, u) \geq -C \|u\|_{L^2}^2 \quad \text{when } \operatorname{Re} p(x, \xi) \geq 0,$$

first for scalar $p(x, \xi) \in S_{1,0}^1$, by Hörmander, then for matrix-valued symbols, with $\operatorname{Re} p(x, \xi)$ standing for $(1/2)(p(x, \xi) + p(x, \xi)^*)$, by P. Lax and L. Nirenberg. Proofs and some implications can be found in Vol. 3 of [Ho5], and in [T1] and [Tre]. A very strong improvement due to C. Fefferman and D. Phong [FP] is that (6.7) holds for scalar $p(x, \xi) \in S_{1,0}^2$. See also [Ho5] and [F] for further discussion.

Exercises

1. Suppose $m > 0$ and $p(x, D) \in OPS_{1,0}^m$ has a symbol satisfying (6.1). Examine the solvability of

$$\frac{\partial u}{\partial t} = p(x, D)u,$$

for $u = u(t, x)$, $u(0, x) = f \in H^s(\mathbb{R}^n)$.

(Hint: Look ahead at §7 for some useful techniques. Solve

$$\frac{\partial u_\varepsilon}{\partial t} = J_\varepsilon p(x, D) J_\varepsilon u_\varepsilon$$

and estimate $(d/dt) \|\Lambda^s u_\varepsilon(t)\|_{L^2}^2$, making use of Gårding's inequality.)

7. Hyperbolic evolution equations

In this section we examine first-order systems of the form

$$(7.1) \quad \frac{\partial u}{\partial t} = L(t, x, D_x)u + g(t, x), \quad u(0) = f.$$

We assume $L(t, x, \xi) \in S_{1,0}^1$, with smooth dependence on t , so

$$(7.2) \quad |D_t^j D_x^\beta D_\xi^\alpha L(t, x, \xi)| \leq C_{j\alpha\beta} \langle \xi \rangle^{1-|\alpha|}.$$

Here $L(t, x, \xi)$ is a $K \times K$ matrix-valued function, and we make the hypothesis of symmetric hyperbolicity:

$$(7.3) \quad L(t, x, \xi)^* + L(t, x, \xi) \in S_{1,0}^0.$$

We suppose $f \in H^s(\mathbb{R}^n)$, $s \in \mathbb{R}$, $g \in C(\mathbb{R}, H^s(\mathbb{R}^n))$.

Our strategy will be to obtain a solution to (7.1) as a limit of solutions u_ε to

$$(7.4) \quad \frac{\partial u_\varepsilon}{\partial t} = J_\varepsilon L J_\varepsilon u_\varepsilon + g, \quad u_\varepsilon(0) = f,$$

where

$$(7.5) \quad J_\varepsilon = \varphi(\varepsilon D_x),$$

for some $\varphi(\xi) \in \mathcal{S}(\mathbb{R}^n)$, $\varphi(0) = 1$. The family of operators J_ε is called a *Friedrichs mollifier*. Note that, for any $\varepsilon > 0$, $J_\varepsilon \in OPS^{-\infty}$, while, for $\varepsilon \in (0, 1]$, J_ε is bounded in $OPS_{1,0}^0$.

For any $\varepsilon > 0$, $J_\varepsilon L J_\varepsilon$ is a bounded linear operator on each H^s , and solvability of (7.4) is elementary. Our next task is to obtain estimates on u_ε , independent of $\varepsilon \in (0, 1]$. Use the norm $\|u\|_{H^s} = \|\Lambda^s u\|_{L^2}$. We derive an estimate for

$$(7.6) \quad \frac{d}{dt} \|\Lambda^s u_\varepsilon(t)\|_{L^2}^2 = 2 \operatorname{Re} (\Lambda^s J_\varepsilon L J_\varepsilon u_\varepsilon, \Lambda^s u_\varepsilon) + 2 \operatorname{Re} (\Lambda^s g, \Lambda^s u_\varepsilon).$$

Write the first two terms on the right as the real part of

$$(7.7) \quad 2(L\Lambda^s J_\varepsilon u_\varepsilon, \Lambda^s J_\varepsilon u_\varepsilon) + 2([\Lambda^s, L]J_\varepsilon u_\varepsilon, \Lambda^s J_\varepsilon u_\varepsilon).$$

By (7.3), $L + L^* = B(t, x, D) \in OPS_{1,0}^0$, so the first term in (7.7) is equal to

$$(7.8) \quad (B(t, x, D)\Lambda^s J_\varepsilon u_\varepsilon, \Lambda^s J_\varepsilon u_\varepsilon) \leq C \|J_\varepsilon u_\varepsilon\|_{H^s}^2.$$

Meanwhile, $[\Lambda^s, L] \in OPS_{1,0}^s$, so the second term in (7.7) is also bounded by the right side of (7.8). Applying Cauchy's inequality to $2(\Lambda^s g, \Lambda^s u_\varepsilon)$, we obtain

$$(7.9) \quad \frac{d}{dt} \|\Lambda^s u_\varepsilon(t)\|_{L^2}^2 \leq C \|\Lambda^s u_\varepsilon(t)\|_{L^2}^2 + C \|g(t)\|_{H^s}^2.$$

Thus Gronwall's inequality yields an estimate

$$(7.10) \quad \|u_\varepsilon(t)\|_{H^s}^2 \leq C(t) [\|f\|_{H^s}^2 + \|g\|_{C([0,t], H^s)}^2],$$

independent of $\varepsilon \in (0, 1]$. We are now prepared to establish the following existence result.

Proposition 7.1. *If (7.1) is symmetric hyperbolic and*

$$f \in H^s(\mathbb{R}^n), \quad g \in C(\mathbb{R}, H^s(\mathbb{R}^n)), \quad s \in \mathbb{R},$$

then there is a solution u to (7.1), satisfying

$$(7.11) \quad u \in L_{loc}^\infty(\mathbb{R}, H^s(\mathbb{R}^n)) \cap Lip(\mathbb{R}, H^{s-1}(\mathbb{R}^n)).$$

Proof. Take $I = [-T, T]$. The bounded family

$$u_\varepsilon \in C(I, H^s) \cap C^1(I, H^{s-1})$$

will have a weak limit point u satisfying (7.11), and it is easy to verify that such u solves (7.1). As for the bound on $[-T, 0]$, this follows from the invariance of the class of hyperbolic equations under time reversal.

Analogous energy estimates can establish the uniqueness of such a solution u and rates of convergence of $u_\varepsilon \rightarrow u$ as $\varepsilon \rightarrow 0$. Also, (7.11) can be improved to

$$(7.12) \quad u \in C(\mathbb{R}, H^s(\mathbb{R}^n)) \cap C^1(\mathbb{R}, H^{s-1}(\mathbb{R}^n)).$$

To see this, let $f_j \in H^{s+1}$, $f_j \rightarrow f$ in H^s , and let u_j solve (7.1) with $u_j(0) = f_j$. Then each u_j belongs to $L_{\text{loc}}^\infty(\mathbb{R}, H^{s+1}) \cap \text{Lip}(\mathbb{R}, H^s)$, so in particular each $u_j \in C(\mathbb{R}, H^s)$. Now $v_j = u - u_j$ solves (7.1) with $v_j(0) = f - f_j$, and $\|f - f_j\|_{H^s} \rightarrow 0$ as $j \rightarrow \infty$, so estimates arising in the proof of Proposition 7.1 imply that $\|v_j(t)\|_{H^s} \rightarrow 0$ locally uniformly in t , giving $u \in C(\mathbb{R}, H^s)$.

There are other notions of hyperbolicity. In particular, (7.1) is said to be *symmetrizable hyperbolic* if there is a $K \times K$ matrix-valued $S(t, x, \xi) \in S_{1,0}^0$ that is positive-definite and such that $S(t, x, \xi)L(t, x, \xi) = \tilde{L}(t, x, \xi)$ satisfies (7.3). Proposition 7.1 extends to the case of symmetrizable hyperbolic systems. Again, one obtains u as a limit of solutions u_ε to (7.4). There is one extra ingredient in the energy estimates. In this case, construct $S(t) \in OPS_{1,0}^0$, positive-definite, with symbol equal to $S(t, x, \xi) \bmod S_{1,0}^{-1}$. For the energy estimates, replace the left side of (7.6) by

$$(7.13) \quad \frac{d}{dt} (\Lambda^s u_\varepsilon(t), S(t) \Lambda^s u_\varepsilon(t))_{L^2},$$

which can be estimated in a fashion similar to (7.7)–(7.9).

A $K \times K$ system of the form (7.1) with $L(t, x, \xi) \in S_{cl}^1$ is said to be *strictly hyperbolic* if its principal symbol $L_1(t, x, \xi)$, homogeneous of degree 1 in ξ , has K distinct, purely imaginary eigenvalues, for each x and each $\xi \neq 0$. The results above apply in this case, in view of:

Proposition 7.2. *Whenever (7.1) is strictly hyperbolic, it is symmetrizable.*

Proof. If we denote the eigenvalues of $L_1(t, x, \xi)$ by $i\lambda_\nu(t, x, \xi)$, ordered so that $\lambda_1(t, x, \xi) < \dots < \lambda_K(t, x, \xi)$, then λ_ν are well-defined C^∞ -functions of (t, x, ξ) , homogeneous of degree 1 in ξ . If $P_\nu(t, x, \xi)$ are the projections onto the $i\lambda_\nu$ -eigenspaces of L_1 ,

$$(7.14) \quad P_\nu(t, x, \xi) = \frac{1}{2\pi i} \int_{\gamma_\nu} (\zeta - L_1(t, x, \xi))^{-1} d\zeta,$$

where γ_ν is a small circle about $i\lambda_\nu(t, x, \xi)$, then P_ν is smooth and homogeneous of degree 0 in ξ . Then

$$(7.15) \quad S(t, x, \xi) = \sum_j P_j(t, x, \xi)^* P_j(t, x, \xi)$$

gives the desired symmetrizer.

Higher-order, strictly hyperbolic PDE can be reduced to strictly hyperbolic, first-order systems of this nature. Thus one has an analysis of solutions to such higher-order hyperbolic equations.

Exercises

1. Carry out the reduction of a strictly hyperbolic PDE of order m to a first-order system of the form (7.1). Starting with

$$Lu = \frac{\partial^m u}{\partial y^m} + \sum_{j=0}^{m-1} A_j(y, x, D_x) \frac{\partial^j u}{\partial y^j},$$

where $A_j(y, x, D)$ has order $\leq m - j$, form $v = (v_1, \dots, v_m)^t$ with

$$v_1 = \Lambda^{m-1} u, \dots, v_j = \partial_y^{j-1} \Lambda^{m-j} u, \dots, v_m = \partial_y^{m-1} u,$$

to pass from $Lu = f$ to

$$\frac{\partial v}{\partial y} = K(y, x, D_x)v + F,$$

with $F = (0, \dots, 0, f)^t$. Give an appropriate definition of strict hyperbolicity in this context, and show that this first-order system is strictly hyperbolic provided L is.

2. Fix $r > 0$. Let $\gamma_r \in \mathcal{E}'(\mathbb{R}^2)$ denote the unit mass density on the circle of radius r :

$$\langle u, \gamma_r \rangle = \frac{1}{2\pi} \int_{-\pi}^{\pi} u(r \cos \theta, r \sin \theta) d\theta.$$

Let $\Gamma_r u = \gamma_r * u$. Show that there exist $A_r(\xi) \in S^{-1/2}(\mathbb{R}^2)$ and $B_r(\xi) \in S^{1/2}(\mathbb{R}^2)$, such that

$$(7.16) \quad \Gamma_r = A_r(D) \cos r\sqrt{-\Delta} + B_r(D) \frac{\sin r\sqrt{-\Delta}}{\sqrt{-\Delta}}.$$

(Hint: See Exercise 1 in §7 of Chap. 6.)

8. Egorov's theorem

We want to examine the behavior of operators obtained by conjugating a pseudodifferential operator $P_0 \in OPS_{1,0}^m$ by the solution operator to a scalar hyperbolic equation of the form

$$(8.1) \quad \frac{\partial u}{\partial t} = iA(t, x, D_x)u,$$

where we assume $A = A_1 + A_0$ with

$$(8.2) \quad A_1(t, x, \xi) \in S_{cl}^1 \text{ real}, \quad A_0(t, x, \xi) \in S_{cl}^0.$$

We suppose $A_1(t, x, \xi)$ is homogeneous in ξ , for $|\xi| \geq 1$. Denote by $S(t, s)$ the solution operator to (8.1), taking $u(s)$ to $u(t)$. This is a bounded operator on each Sobolev space H^σ , with inverse $S(s, t)$. Set

$$(8.3) \quad P(t) = S(t, 0)P_0S(0, t).$$

We aim to prove the following result of Y. Egorov.

Theorem 8.1. *If $P_0 = p_0(x, D) \in OPS_{1,0}^m$, then for each t , $P(t) \in OPS_{1,0}^m$, modulo a smoothing operator. The principal symbol of $P(t)$ (mod $S_{1,0}^{m-1}$) at a point (x_0, ξ_0) is equal to $p_0(y_0, \eta_0)$, where (y_0, η_0) is obtained from (x_0, ξ_0) by following the flow $\mathcal{C}(t)$ generated by the (time-dependent) Hamiltonian vector field*

$$(8.4) \quad H_{A_1(t,x,\xi)} = \sum_{j=1}^n \left(\frac{\partial A_1}{\partial \xi_j} \frac{\partial}{\partial x_j} - \frac{\partial A_1}{\partial x_j} \frac{\partial}{\partial \xi_j} \right).$$

To start the proof, differentiating (8.3) with respect to t yields

$$(8.5) \quad P'(t) = i[A(t, x, D), P(t)], \quad P(0) = P_0.$$

We will construct an approximate solution $Q(t)$ to (8.5) and then show that $Q(t) - P(t)$ is a smoothing operator.

So we are looking for $Q(t) = q(t, x, D) \in OPS_{1,0}^m$, solving

$$(8.6) \quad Q'(t) = i[A(t, x, D), Q(t)] + R(t), \quad Q(0) = P_0,$$

where $R(t)$ is a smooth family of operators in $OPS^{-\infty}$. We do this by constructing the symbol $q(t, x, \xi)$ in the form

$$(8.7) \quad q(t, x, \xi) \sim q_0(t, x, \xi) + q_1(t, x, \xi) + \dots.$$

Now the symbol of $i[A, Q(t)]$ is of the form

$$(8.8) \quad H_{A_1}q + \{A_0, q\} + i \sum_{|\alpha| \geq 2} \frac{i^{|\alpha|}}{\alpha!} \left(A^{(\alpha)} q^{(\alpha)} - q^{(\alpha)} A^{(\alpha)} \right),$$

where $A^{(\alpha)} = D_\xi^\alpha A$, $A_{(\alpha)} = D_x^\alpha A$, and so on. Since we want the difference between this and $\partial q / \partial t$ to have order $-\infty$, this suggests defining $q_0(t, x, \xi)$ by

$$(8.9) \quad \left(\frac{\partial}{\partial t} - H_{A_1} \right) q_0(t, x, \xi) = 0, \quad q_0(0, x, \xi) = p_0(x, \xi).$$

Thus $q_0(t, x_0, \xi_0) = p_0(y_0, \eta_0)$, as in the statement of the theorem; we have $q_0(t, x, \xi) \in S_{1,0}^m$. Equation (8.9) is called a *transport equation*. Recursively, we obtain transport equations

$$(8.10) \quad \left(\frac{\partial}{\partial t} - H_{A_1} \right) q_j(t, x, \xi) = b_j(t, x, \xi), \quad q_j(0, x, \xi) = 0,$$

for $j \geq 1$, with solutions in $S_{1,0}^{m-j}$, leading to a solution to (8.6).

Finally, we show that $P(t) - Q(t)$ is a smoothing operator. Equivalently, we show that, for any $f \in H^\sigma(\mathbb{R}^n)$,

$$(8.11) \quad v(t) - w(t) = S(t, 0)P_0f - Q(t)S(t, 0)f \in H^\infty(\mathbb{R}^n),$$

where $H^\infty(\mathbb{R}^n) = \cap_s H^s(\mathbb{R}^n)$. Note that

$$(8.12) \quad \frac{\partial v}{\partial t} = iA(t, x, D)v, \quad v(0) = P_0f,$$

while use of (8.6) gives

$$(8.13) \quad \frac{\partial w}{\partial t} = iA(t, x, D)w + g, \quad w(0) = P_0f,$$

where

$$(8.14) \quad g = R(t)S(t, 0)w \in C^\infty(\mathbb{R}, H^\infty(\mathbb{R}^n)).$$

Hence

$$(8.15) \quad \frac{\partial}{\partial t}(v - w) = iA(t, x, D)(v - w) - g, \quad v(0) - w(0) = 0.$$

Thus energy estimates for hyperbolic equations yield $v(t) - w(t) \in H^\infty$, for any $f \in H^\sigma(\mathbb{R}^n)$, completing the proof.

A check of the proof shows that

$$(8.16) \quad P_0 \in OPS_{cl}^m \implies P(t) \in OPS_{cl}^m.$$

Also, the proof readily extends to yield the following:

Proposition 8.2. *With $A(t, x, D)$ as before,*

$$(8.17) \quad P_0 \in OPS_{\rho, \delta}^m \implies P(t) \in OPS_{\rho, \delta}^m$$

provided

$$(8.18) \quad \rho > \frac{1}{2}, \quad \delta = 1 - \rho.$$

One needs $\delta = 1 - \rho$ to ensure that $p(\mathcal{C}(t)(x, \xi)) \in S_{\rho, \delta}^m$, and one needs $\rho > \delta$ to ensure that the transport equations generate $q_j(t, x, \xi)$ of progressively lower order.

Exercises

- Let $\chi : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a diffeomorphism that is a linear map outside some compact set. Define $\chi^* : C^\infty(\mathbb{R}^n) \rightarrow C^\infty(\mathbb{R}^n)$ by $\chi^* f(x) = f(\chi(x))$. Show that

$$(8.19) \quad P \in OPS_{1,0}^m \implies (\chi^*)^{-1} P \chi^* \in OPS_{1,0}^m.$$

(Hint: Reduce to the case where χ is homotopic to a linear map through diffeomorphisms, and show that the result in that case is a special case of Theorem 8.1, where $A(t, x, D)$ is a t -dependent family of real vector fields on \mathbb{R}^n .)

- Let $a \in C_0^\infty(\mathbb{R}^n)$, $\varphi \in C^\infty(\mathbb{R}^n)$ be real-valued, and $\nabla\varphi \neq 0$ on $\text{supp } a$. If $P \in OPS^m$, show that

$$(8.20) \quad P(a e^{i\lambda\varphi}) = b(x, \lambda) e^{i\lambda\varphi(x)},$$

where

$$(8.21) \quad b(x, \lambda) \sim \lambda^m [b_0^\pm(x) + b_1^\pm(x)\lambda^{-1} + \dots], \quad \lambda \rightarrow \pm\infty.$$

(Hint: Using a partition of unity and Exercise 1, reduce to the case $\varphi(x) = x \cdot \xi$, for some $\xi \in \mathbb{R}^n \setminus 0$.)

- If a and φ are as in Exercise 2 above and Γ_r is as in Exercise 2 of §7, show that, mod $O(\lambda^{-\infty})$,

$$(8.22) \quad \Gamma_r(a e^{i\lambda\varphi}) = \cos r\sqrt{-\Delta}(A_r(x, \lambda)e^{i\lambda\varphi}) + \frac{\sin r\sqrt{-\Delta}}{\sqrt{-\Delta}}(B_r(x, \lambda)e^{i\lambda\varphi}),$$

where

$$\begin{aligned} A_r(x, \lambda) &\sim \lambda^{-1/2} [a_{0r}^\pm(x) + a_{1r}^\pm(x)\lambda^{-1} + \dots], \\ B_r(x, \lambda) &\sim \lambda^{1/2} [b_{0r}^\pm(x) + b_{1r}^\pm(x)\lambda^{-1} + \dots], \end{aligned}$$

as $\lambda \rightarrow \pm\infty$.

9. Microlocal regularity

We define the notion of wave front set of a distribution $u \in H^{-\infty}(\mathbb{R}^n) = \cup_s H^s(\mathbb{R}^n)$, which refines the notion of singular support. If $p(x, \xi) \in S^m$ has principal symbol $p_m(x, \xi)$, homogeneous in ξ , then the characteristic set of $P = p(x, D)$ is given by

$$(9.1) \quad \text{Char } P = \{(x, \xi) \in \mathbb{R}^n \times (\mathbb{R}^n \setminus 0) : p_m(x, \xi) = 0\}.$$