## Math 395 IBL - The Spectral Theorem

William Garland, Michael Ivanitskiy, Le Hu

Friday October 13, 2017

Context: Finite Dimensional Spectral Theorem

Let H be some symmetric matrix. Then,  $\exists U \in O(n)$  such that

$$H = UXU^{-1} \qquad U \in O(n)$$

where X is a diagonal matrix; i.e.

$$X = \begin{bmatrix} \lambda_1 & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$$

Take an input H. We desire some  $U \in O(n)$  for which  $U^{-1}HU$  is diagonal. Define a function  $f: M_n \to \mathbb{R}$  by

$$f(z) = \sum r_i z_{ii}$$

for  $r_i \in \mathbb{R}$  with the property that  $r_1 < r_2 < \cdots < r_n$  and let  $g: M_n \to \mathbb{R}$  be defined by  $g(U) = f(U^{-1}HU)$ 

Example: Let

$$f(Z) = z_{11} + 2z_{22}$$
  $H = \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}$   $U = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \in O(n)$ 

Then

$$U^{-1}HU = \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$
$$= \begin{bmatrix} \cos\theta + 2\sin\theta & 2\cos\theta + 3\sin\theta \\ -\sin\theta + 2\cos\theta & -2\sin\theta + 3\cos\theta \end{bmatrix} \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$
$$= \begin{bmatrix} \cos^2\theta + 4\cos\theta\sin\theta + 3\sin^2\theta \\ \sin^2\theta - 4\cos\theta\sin\theta + 3\cos^2\theta \end{bmatrix}$$
$$f = (\cos^2\theta + 4\cos\theta\sin\theta + 3\sin^2\theta) + 2 \cdot (\sin^2\theta - 4\cos\theta\sin\theta + 3\cos^2\theta)$$

This function is minimized for a value of  $\theta$  satisfying

$$0 = \frac{d}{d\theta} \left( \left( \cos^2 \theta + 4 \cos \theta \sin \theta + 3 \sin^2 \theta \right) + 2 \left( \sin^2 \theta - 4 \cos \theta \sin \theta + 3 \cos^2 \theta \right) \right)$$
  
=  $-2 \cos \theta \sin \theta + 4 \cos(2\theta) + 6 \sin \theta \cos \theta + 4 \sin \theta \cos \theta - 8 \cos(2\theta) - 12 \cos \theta \sin \theta$   
=  $-4 \sin \theta \cos \theta - 4 \cos(2\theta)$   
=  $-2(\sin(2\theta) + 2 \cos(2\theta))$   
 $\implies \tan(2\theta) = -2 \implies \theta \approx 1.01722$ 

We wish to show that for any such symmetric matrix H,  $\exists U \in O(n)$  such that  $f(U^{-1}HU)$  is minimized, and furthermore that in this case  $U^{-1}HU$  is diagonal.

Problem 19: Show that  $\exists U_0 \in O(n) \ni g$  is minimized at some  $U_0$  on O(n).

*Proof.* Recall that  $g: O(n) \to \mathbb{R}$  is a continuous real-valued map. Therefore, it is sufficient to show that O(n) is compact. Since O(n) is a subset of a real vector space  $\mathbb{R}^{n^2}$ , we may show that it is closed and bounded.

Closed: Define a function  $h: M_n(\mathbb{R}) \to M_n(\mathbb{R})$   $(M_n$  denotes the space of  $n \times n$  matrices) by  $h(A) = A^t A$ . Note matrix multiplication is a polynomial map with respect to the entries of A, so h is continuous. Furthermore

 $O(n) = \{A \in M_n : A^t A = \mathrm{Id}\} = \{A \in M_n : h(A) = \mathrm{Id}\} = h^{-1}(\mathrm{Id})$ 

Since h is continuous and the singleton  $\{Id\}$  is closed, we conclude that O(n) is closed.

Bounded: Let  $|\cdot|_{\infty}$  denote the supremum norm on  $M_n$ . Let  $U \in O(n)$ . Note that by the standard inner product on  $\mathbb{R}^n$ , we know that U is orthogonal implies  $(Ue_1, Ue_2, \ldots, Ue_n)$  forms an orthonormal basis of  $\mathbb{R}^n$ . Furthermore note that these are the columns of U, and that if each has  $|Ue_i| = 1$  under the 2-norm, then no element of U has absolute value > 1. Therefore  $|U|_{\infty} \leq |U_{ij}| \leq 1$  for some i, j, so U is bounded by 1 for all  $U \in O(n)$ . Therefore O(n) is bounded.

Thus O(n) is compact. The image of a compact set under a continuous map is compact, so we note that  $g(O(n)) \subset \mathbb{R}$  achieves its minimum at some  $U_0 \in O(n)$ .

We showed on a previous homework that if g achieves its minimum at  $U_0$ , then  $[Dg]_{U_0}[v] = 0$ for all  $v \in T_{U_0}O(n)$ . But for any  $U \in O(n)$ , how do we describe  $T_UO_n$ ? Recall that since  $U \in O(n)$  which is a smooth manifold, then the function  $U \exp : P \to B$  (where P is an open subset of  $\mathfrak{so}(n)$ ) is a coordinate patch from  $\mathfrak{so}(n)$  to O(n) near U. Therefore,

$$T_U O(n) = [D(U \exp)]_U[\mathfrak{so}(n)] = [D(U)]_{\mathrm{Id}}[D \exp]_0[\mathfrak{so}(n)]$$

Note U as a map from  $A \to UA$  is linear, so  $[D(U)]_{Id} = UId = U$ . As we have previously shown,  $[D \exp]_0 = Id$ , so consequently we conclude

$$T_U O(n) = U \operatorname{Id}[\mathfrak{so}(n)] = U \cdot \mathfrak{so}(n)$$

Thus if  $A \in T_U O(n)$ , then A = UJ for some  $J \in \mathfrak{so}(n)$ .

However, we can also define  $T_UO(n)$  in a different way, as the set of derivatives of paths through O(n) at U. Under this definition, if  $UJ \in T_U$ , let  $\gamma(t) : (-\delta, \delta) \to O(n)$  by  $\gamma(t) = U \exp(tJ)$  and note  $\gamma(0) = U \exp(0) = U$  and  $\gamma'(0) = UJ \exp(0) = UJ$ . By the Chain Rule, it follows that

$$\begin{split} [Dg]_U[UJ] &= \left. \frac{d}{dt} \right|_{t=0} g(\gamma(t)) \\ &= \left. \frac{d}{dt} \right|_{t=0} f((U \exp(tJ))^{-1} H(U \exp(tJ))) \\ &= \left. \frac{d}{dt} \right|_{t=0} f(\exp(tJ)^{-1} U_0^{-1} HU \exp(tJ)) \\ &= \left. \frac{d}{dt} \right|_{t=0} f(\exp(-tJ) X \exp(tJ)) \end{split}$$

where  $X = U^{-1}HU$  does not depend on J or t. Since f is linear, [Df] = f, so we conclude

$$[Dg]_U[UJ] = f\left(\frac{d}{dt}\bigg|_{t=0} \exp(-tJ)X\exp(tJ)\right) = f(-JX + XJ)$$

for any  $UJ \in T_UO(n)$ .

Now that we have computed [Dg], we are ready to tackle Problem 20.

Problem 20: Show  $U^{-1}HU$  is diagonal if and only if g(U) is minimized.

First, suppose  $U \in O(n)$  such that  $X := U^{-1}HU$  is diagonal. Therefore  $\forall J \in \mathfrak{so}(n)(n)$ , the diagonal entries of J must all be zero, so note

$$-JX + XJ = \begin{bmatrix} 0 & * \\ & \ddots & \\ -* & 0 \end{bmatrix} \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} + \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} \begin{bmatrix} 0 & -* \\ & \ddots & \\ * & 0 \end{bmatrix}$$

 $\operatorname{So}$ 

$$[Dg]_U [UJ] = \sum r_k [-JX_0 + X_0 J]_k k = 0$$

for all  $UJ \in T_UO(n)$ . Thus g(U) is minimized.

Now, let  $U \in O(n)$  and define  $X = U^{-1}HU$  such that

$$[Dg]_U[UJ] = \sum r_k (-JX + XJ)_{kk} = 0$$

We need to show that X is diagonal.

Notice

$$X^{t} = (U^{-1}HU)^{t} = U^{t}H^{t}(U^{-1})^{t} = U^{-1}HU = X$$

so X is symmetric. Suppose X is not diagonal. Then  $\exists i, j$  with  $i \neq j$  such that

$$X_{ij} = X_{ji} = a \neq 0$$

Define  $J \in \mathfrak{so}(n)$  such that  $J_{ij} = 1$ ,  $J_{ji} = -1$ , and  $J_{rs} = 0$  for all  $(r, s) \neq (i, j)$ . Then note

$$JX_{ii} = J_{ij}X_{ji} = X_{ji} = a$$
  $JX_{jj} = J_{ji}X_{ij} = -X_{ij} = -a$ 

$$XJ_{ii} = X_{ij}J_{ji} = -X_{ij} = -a \qquad XJ_{jj} = X_{ji}J_{ij} = X_{ji} = a$$

and for  $r \neq i, j$ ,

$$JX_{rr} = XJ_{rr} = 0$$

Therefore,

$$0 = f(-JX + XJ) = \sum r_k (-JX + XJ)_{kk}$$
  
=  $r_i (-JX_{ii} + XJ_{ii}) + r_j (-JX_{jj} + XJ_{jj})$   
=  $r_i (-a + -a) + r_j (a + a) = 2(r_j - r_i)a$ 

But  $r_j \neq r_i$  by construction (since  $j \neq i$ ), so it follows that a = 0, a contradiction. Therefore it must be the case that  $X = U^{-1}HU$  is diagonal.

## Problem 21: Prove the Spectral Theorem.

The result is immediate: if H is a symmetric matrix, then by Problem 19  $\exists U_0 \in O(n)$  such that  $g(U_0)$  is minimized. Define  $X_0 = U_0^{-1}HU_0$ . Since g attains a local minimum on O(n) at  $U_0$ , it follows that  $\forall U_0 J \in T_{U_0}O(n)$ ,

$$[Dg]_{U_0}[U_0J] = f(-JX_0 + X_0J) = 0$$

Therefore by Problem 20, we conclude that  $X_0$  is diagonal. Thus for every symmetric matrix  $H \exists U_0 \in O(n)$  such that  $U_0^{-1}HU_0$  is diagonal.