

PROBLEM SET 4 – DUE FRIDAY FEBRUARY 2

See the course website for policy on collaboration.

- We review basic computations with 1-forms.
 - Let x and y be coordinates on \mathbb{R}^2 . Write $d(e^x \sin y)$ as a linear combination of dx and dy .
 - Let u, v be coordinates on \mathbb{R}^2 and let x, y, z be coordinates on \mathbb{R}^3 . Let $\phi(u, v) = (u \cos v, u \sin v, v)$. Compute $\phi^*d(x^2 + y^2)$.
- In this problem we will prove the following result: Let U be an open subset of \mathbb{R}^n and p a point of U . Suppose there is a smooth map $h : U \times [0, 1] \rightarrow U$ such that, for all $x \in U$, we have $h(x, 1) = x$ and $h(x, 0) = p$. Then any closed 1-form on U is exact.

We'll write (x_1, x_2, \dots, x_n) for the coordinates on U and t for the coordinate on $[0, 1]$. This will give us many more situations where we can say that closed is the same as exact.

- Let $\omega = \sum f_i(x_1, \dots, x_n, t)dx_i + g(x_1, \dots, x_n, t)dt$ be a closed 1-form on $U \times [0, 1]$, meaning that $\frac{\partial f_i}{\partial x_j} = \frac{\partial f_j}{\partial x_i}$ and $\frac{\partial f_i}{\partial t} = \frac{\partial g}{\partial x_i}$. Put $G(x_1, \dots, x_n) = \int_{t=0}^1 g(x_1, \dots, x_n, t)dt$. Let ω_0 and ω_1 be the 1-forms on U obtained by restricting ω to $U \times \{0\}$ and $U \times \{1\}$. Show that

$$dG = \omega_1 - \omega_0.$$

- Let $h : U \times [0, 1] \rightarrow U$ be as in the introduction to the problem. Let η be a closed 1-form on U . Show that $h^*\eta$ is closed.
 - Let $h : U \times [0, 1] \rightarrow U$ be as in the introduction to the problem and let η be a closed 1-form on U . Combine the previous parts to show that η is exact, in other words, there is some function G on U with $dG = \eta$.
 - Suppose that, U is convex and nonempty, meaning that, for any points p and q in U , the line segment between p and q is in U . Show that there is a map $h : U \times [0, 1] \rightarrow U$ as in the problem statement.
- This question applies Stokes' Theorem to prove the Fundamental Theorem of Algebra.

- Let $0 < p < q$ and let $A = \{(x, y) : p^2 \leq x^2 + y^2 \leq q^2\} \subset \mathbb{R}^2$. Let $C_1 = \{(x, y) : x^2 + y^2 = p^2\}$ and $C_2 = \{(x, y) : x^2 + y^2 = q^2\}$. Let $\phi : A \rightarrow \mathbb{R}^2 \setminus \{(0, 0)\}$ be a smooth map. Show that

$$\int_{C_1} \phi^* \left(\frac{xdy - ydx}{x^2 + y^2} \right) = \int_{C_2} \phi^* \left(\frac{xdy - ydx}{x^2 + y^2} \right).$$

- Let n be a positive integer. Show that there is no smooth map $\phi : A \rightarrow \mathbb{R}^2 \setminus \{(0, 0)\}$ such that $\phi(p \cos \theta, p \sin \theta) = (1, 0)$ and $\phi(q \cos \theta, q \sin \theta) = (\cos(n\theta), \sin(n\theta))$. (Hint: Your computations will be easier if you recall that $\frac{xdy - ydx}{x^2 + y^2} = d \tan^{-1}(y/x)$ whenever $x \neq 0$.)

Let's prove the Fundamental Theorem of Algebra! Suppose for the sake of contradiction that $f(z) = a_n z^n + \dots + a_0$ is a complex polynomial, with $a_n \neq 0$ and no complex zero. Let $F : \mathbb{R}^2 \rightarrow \mathbb{R}^2 \setminus \{(0, 0)\}$ be

$$F(x, y) = \frac{\text{Real}(f(x + iy)), \text{Im}(f(x + iy))}{(1 + \sqrt{x^2 + y^2})^n}.$$

Choose $0 < p < q$ and pick a continuous increasing function $h : (p, q) \rightarrow \mathbb{R}_{>0}$ with $\lim_{r \rightarrow p^+} h(r) = 0$ and $\lim_{r \rightarrow q^-} h(r) = \infty$. Put

$$\phi(x, y) = F(h(\sqrt{u^2 + v^2})u, h(\sqrt{u^2 + v^2})v).$$

- Show that ϕ , defined as above, extends to a continuous function $A \rightarrow \mathbb{R}^2 \setminus 0$.
- Derive a contradiction. You may gloss over the issue of the smoothness of A at the boundary.

4. This question looks at the frequent issue of how to think about double derivatives abstractly. Let V be a finite dimensional real vector space, and $g : V \rightarrow \mathbb{R}$ a smooth function. Then $y \mapsto dg_y$ is a function $V \rightarrow V^*$. We'll denote this function as Dg . We can then take D of Dg so that, at every point $y \in V$, we have a linear map $D(Dg)_y : V \rightarrow V^*$. For $y \in V$ and \vec{v}_1, \vec{v}_2 in V , we write $(D^2g)_y(\vec{v}_1, \vec{v}_2)$ to mean $D(Dg)_y(\vec{v}_1)(\vec{v}_2)$.

(a) Show that $(D^2g)_y(\vec{v}_1, \vec{v}_2) = (D^2g)_y(\vec{v}_2, \vec{v}_1)$.

Let U be another finite dimensional real vector space, and let $\phi : U \rightarrow V$ be a smooth map. Let $x \in U$ and $\vec{u}_1, \vec{u}_2 \in U$. We define $y = \phi(x)$ and $\vec{v}_1 = (D\phi)_x\vec{u}_1$, $\vec{v}_2 = (D\phi)_x\vec{u}_2$ and $f = g \circ \phi$.

(b) If ϕ is linear, show that $(D^2f)_x(\vec{u}_1, \vec{u}_2) = (D^2g)_y(\vec{v}_1, \vec{v}_2)$.

(c) Give an example to show that the previous result need not hold if ϕ is not linear. Hint: Take $\dim U = \dim V = 1$ and try almost anything.