

PROBLEM SET 6 – DUE FRIDAY MARCH 16

See the course website for policy on collaboration.

1. Let  $X$  and  $Y$  be smooth manifolds of dimension  $n$  and let  $\phi : X \rightarrow Y$  be a smooth map.
  - (a) Let  $x \in X$ . Suppose that the linear map  $(D\phi)_x : T_x X \rightarrow T_{\phi(x)} Y$  is an isomorphism. Show that there are open neighborhoods  $U$  of  $x$  and  $V$  of  $\phi(x)$  such that  $\phi$  maps  $U \rightarrow V$  bijectively and there is a smooth inverse  $V \rightarrow U$ . (Yes, this is the inverse function theorem. The point is to write down the details of doing this with patches, on manifolds.)
  - (b) Suppose that  $\phi$  is a bijection and that, for all  $x \in X$ , the linear map  $D\phi_x : T_x X \rightarrow T_{\phi(x)} Y$  is an isomorphism. Show that  $\phi^{-1} : Y \rightarrow X$  is smooth.
2. Let  $X$  and  $Y$  be smooth manifolds, with smooth atlases  $\{(f_i, P_i, U_i)\}$  and  $\{(g_j, Q_j, V_j)\}$ .
  - (a) Define a smooth atlas on  $X \times Y$ , and prove that the transition maps in your atlas are smooth.
  - (b) For  $x \in X$  and  $y \in Y$ , give a natural isomorphism between the vector spaces  $T_{(x,y)}(X \times Y)$  and  $T_x X \oplus T_y Y$ .

3. In this problem, you may use the previous problem even if you haven't done it. Let  $G$  be a smooth manifold and let  $\mu : G \times G \rightarrow G$  be a smooth map making  $G$  into a group with identity element  $e$ . Put  $\mathfrak{g} = T_e G$ .

So we have a map  $D\mu_e : T_{(e,e)}(G \times G) \rightarrow \mathfrak{g}$  and, by the previous problem, we have a natural isomorphism  $\mathfrak{g} \oplus \mathfrak{g} \rightarrow T_{(e,e)}(G \times G)$ . Composing these gives a linear map  $\mathfrak{g} \oplus \mathfrak{g} \rightarrow \mathfrak{g}$  which, by slight abuse of notation, we will also denote  $D\mu_e$ .

- (a) Show that  $D\mu_e(X, Y) = X + Y$ .  
 For  $g \in G$ , let  $L_g : G \rightarrow G$  be the map  $L_g(h) = gh$  and let  $R_g : G \rightarrow G$  be the map  $R_g(h) = hg$ .
- (b) Show that  $DL_g : \mathfrak{g} \rightarrow T_g G$  and  $DR_g : \mathfrak{g} \rightarrow T_g G$  are isomorphisms.
- (c) When  $g$  is  $GL_n$  (so  $\mathfrak{g}$  is the vector space of  $n \times n$  matrices), give simpler formulas for  $DL_g X$  and  $DR_g X$ .
- (d) For  $g$  and  $h \in G$ , and  $X \in T_g G$ ,  $Y \in T_h Y$ , show that

$$D\mu_{(g,h)}(X, Y) = DL_g(DR_h(DL_g^{-1}X + DR_h^{-1}Y)).$$

4. This question demonstrates why the next question is phrased the way it is.
  - (a) Give an example of a manifold  $X$ , and open set  $V \subset X$  and a smooth function  $\phi : V \rightarrow \mathbb{R}$  such that there is **no** smooth function  $\hat{\phi} : X \rightarrow \mathbb{R}$  such that  $\hat{\phi}(y) = \phi(y)$  for  $y \in V$ .
  - (b) Define a smooth premanifold to be like a smooth manifold, but without the Hausdorff condition. Give an example of a premanifold  $X$ , a point  $x \in X$  with open neighborhood  $V$ , and a smooth function  $\phi : V \rightarrow \mathbb{R}$ , such that there does **not** exist any pair  $(\hat{\phi}, W)$ , where  $\hat{\phi} : X \rightarrow \mathbb{R}$  is a smooth function,  $W$  is an open neighborhood of  $x$ , and  $\hat{\phi}(y) = \phi(y)$  for  $y \in W$ . (Hint: Take  $X$  to be the doubled line as a topological space, but use an unusual map  $\mathbb{R} \rightarrow X$  as a chart around one of the two zeroes.)

One more problem on back.

5. The point of this question is to prove the following lemma: Let  $X$  be a smooth manifold; remember that this includes being Hausdorff. Let  $V \subset X$  be open, let  $\phi : V \rightarrow \mathbb{R}$  be smooth and let  $x \in V$ . Then there exists a smooth function  $\widehat{\phi} : X \rightarrow \mathbb{R}$ , and an open neighborhood  $W \ni x$ , such that  $\widehat{\phi}(y) = \phi(y)$  for  $y \in W$ .

Choose a patch  $f : P \rightarrow U$  with  $f(p) = x$  for some  $p \in P$ . Choose  $0 < r_1 < r_2 < r_3$  such that  $\overline{B_p}(r_3) \subset P$  and  $f(\overline{B_p}(r_3)) \subset V$ . (Here  $B_p(r)$  is the open ball of radius  $r$  around  $x$ , and  $\overline{B_p}(r)$  is the closed ball.)

Let  $h : \overline{B_p}(r_3) \rightarrow \mathbb{R}$  be a smooth function with  $h(x) = 1$  for  $x \in \overline{B_p}(r_1)$  and  $h(x) = 0$  for  $x \in \overline{B_p}(r_3) \setminus B_p(r_2)$ . Put

$$\widehat{\phi}(y) = \begin{cases} h(f^{-1}(y)) \phi(y) & y \in f(B_p(r_3)) \\ 0 & y \notin f(\overline{B_p}(r_2)) \end{cases}.$$

Note that if  $y \in f(B_p(r_3)) \setminus f(\overline{B_p}(r_2))$ , then  $h(f^{-1}(y)) = 0$ , so this makes sense.

- (a) Check that  $\widehat{\phi}$  is smooth. (Hint: You will need the Hausdorff hypothesis!)
- (b) Put  $W = f(B_p(r_1))$ . Check that  $W$  is open in  $X$ , and  $\widehat{\phi}(y) = \phi(y)$  for  $y \in W$ .