Spaces of linear maps, dual spaces, transpose

Overview of today: We are going to introduce a notion of the "dual" to a vector space. The difference between the original vectors and the dual vectors can be thought of like the difference between column vectors and row vectors. Keeping track of the difference between vectors and dual vectors may seem fiddly at first, but I hope it will eventually be clarifying.

Let V and W be vector spaces over a field F. We'll write $\operatorname{Hom}(V, W)$ for the space of linear transformations $V \to W$.

Let V and W be vector spaces over a field F. We'll write Hom(V, W) for the space of linear transformations $V \to W$. Hom(V, W) is a vector space. To be clear: If $f: V \to W$ and $g: V \to W$ are linear transformations and c is a scalar, then $(f+g)(\vec{v}) = f(\vec{v}) + g(\vec{v})$ and $(cf)(\vec{v}) = cf(\vec{v})$. Let V and W be vector spaces over a field F. We'll write Hom(V, W) for the space of linear transformations $V \to W$. Hom(V, W) is a vector space. To be clear: If $f: V \to W$ and $g: V \to W$ are linear transformations and c is a scalar, then $(f+g)(\vec{v}) = f(\vec{v}) + g(\vec{v})$ and $(cf)(\vec{v}) = cf(\vec{v})$.

Question: If dim V = m and dim W = n, what is dim Hom(V, W)?

It is mn. Concretely, think of V as F^m and W as F^n . Then Hom(V, W) is $n \times m$ matrices, and an $n \times m$ matrix is uniquely determined by its mn entries.

It is mn. Concretely, think of V as F^m and W as F^n . Then Hom(V, W) is $n \times m$ matrices, and an $n \times m$ matrix is uniquely determined by its mn entries.

Abstractly, let \vec{e}_i be a basis of V and let \vec{f}_j be a basis of W. Let h_{ji} be the linear transformation

$$h_{ji}\left(\sum a_i \vec{e}_i\right) = a_i \vec{f}_j.$$

It is mn. Concretely, think of V as F^m and W as F^n . Then Hom(V, W) is $n \times m$ matrices, and an $n \times m$ matrix is uniquely determined by its mn entries.

Abstractly, let $\vec{e_i}$ be a basis of V and let $\vec{f_j}$ be a basis of W. Let h_{ji} be the linear transformation

$$h_{ji}\left(\sum a_i \vec{e}_i\right) = a_i \vec{f}_j.$$

Every linear transformation is a unique linear combination of the h_{ji} .

It is mn. Concretely, think of V as F^m and W as F^n . Then Hom(V, W) is $n \times m$ matrices, and an $n \times m$ matrix is uniquely determined by its mn entries.

Abstractly, let $\vec{e_i}$ be a basis of V and let $\vec{f_j}$ be a basis of W. Let h_{ji} be the linear transformation

$$h_{ji}\left(\sum a_i \vec{e}_i\right) = a_i \vec{f}_j.$$

Every linear transformation is a unique linear combination of the h_{ji} . If $T(\vec{e}_i) = \sum c_{ji} \vec{f}_j$ then $T = \sum c_{ji} h_{ji}$.

It is mn. Concretely, think of V as F^m and W as F^n . Then Hom(V, W) is $n \times m$ matrices, and an $n \times m$ matrix is uniquely determined by its mn entries.

Abstractly, let \vec{e}_i be a basis of V and let \vec{f}_j be a basis of W. Let h_{ji} be the linear transformation

$$h_{ji}\left(\sum a_i \vec{e}_i\right) = a_i \vec{f}_j.$$

Every linear transformation is a unique linear combination of the h_{ji} . If $T(\vec{e_i}) = \sum c_{ji} \vec{f_j}$ then $T = \sum c_{ji} h_{ji}$.

Again, this is mn basis vectors. \Box

We want to spend today focused on a special case: n = 1. We are looking at Hom(V, F). We call this "the dual space to V" and write V^* . To repeat: An element of Hom(V, F) is a linear transformation $V \to F$. We want to spend today focused on a special case: n = 1. We are looking at Hom(V, F). We call this "the dual space to V" and write V^* . To repeat: An element of Hom(V, F) is a linear transformation $V \to F$.

If e_1, e_2, \ldots is a basis of V, then we define e_i^* in V^* by

$$e_i^*\left(\sum c_j e_j\right) = c_i.$$

We want to spend today focused on a special case: n = 1. We are looking at Hom(V, F). We call this "the dual space to V" and write V^* . To repeat: An element of Hom(V, F) is a linear transformation $V \to F$.

If e_1, e_2, \ldots is a basis of V, then we define e_i^* in V^* by

$$e_i^*\left(\sum c_j e_j\right) = c_i$$

If V is finite dimensional, with basis e_1, e_2, \ldots, e_n , then e_i^* is a basis of V. So dim $V = \dim V^*$ in the finite dimensional case. Think of elements of V as column vectors and elements of V^* as row vectors.

We will avoid infinite dimensional issues in this lecture.

 $F^*(w^*)(\vec{v}) := w^*(F(\vec{v})).$

 $F^*(w^*)(\vec{v}) := w^*(F(\vec{v})).$

Example: Let $V = \mathbb{R}^2$ and $W = \mathbb{R}^3$. Let $F = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$.

 $F^*(w^*)(\vec{v}) := w^*(F(\vec{v})).$

Example: Let $V = \mathbb{R}^2$ and $W = \mathbb{R}^3$. Let $F = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$.

Notation check: What is $F(e_1)$? What is $F(e_2)$?

 $F^*(w^*)(\vec{v}) := w^*(F(\vec{v})).$

Example: Let $V = \mathbb{R}^2$ and $W = \mathbb{R}^3$. Let $F = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$.

We have $F(e_1) = f_1 + 3f_2 + 5f_3$ and $F(e_2) = 2f_1 + 4f_2 + 6f_3$.

 $F^*(w^*)(\vec{v}) := w^*(F(\vec{v})).$

Example: Let $V = \mathbb{R}^2$ and $W = \mathbb{R}^3$. Let $F = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$.

We have $F(e_1) = f_1 + 3f_2 + 5f_3$ and $F(e_2) = 2f_1 + 4f_2 + 6f_3$. What is $F^*(f_1^*)$?

 $F^*(w^*)(\vec{v}) := w^*(F(\vec{v})).$

Example: Let $V = \mathbb{R}^2$ and $W = \mathbb{R}^3$. Let $F = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$.

We have $F(e_1) = f_1 + 3f_2 + 5f_3$ and $F(e_2) = 2f_1 + 4f_2 + 6f_3$. $F^*(f_1^*)(e_1) = f_1^*(F(e_1)) = f_1^*(f_1 + 3f_2 + 5f_3) = 1$. $F^*(f_1^*)(e_2) = f_1^*(F(e_2)) = f_1^*(2f_1 + 4f_2 + 6f_3) = 2$.

 $F^*(f_1^*) = e_1^* + 2e_2^*.$

 $F^*(w^*)(\vec{v}) := w^*(F(\vec{v})).$

Example: Let $V = \mathbb{R}^2$ and $W = \mathbb{R}^3$. Let $F = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$.

We have $F(e_1) = f_1 + 3f_2 + 5f_3$ and $F(e_2) = 2f_1 + 4f_2 + 6f_3$.

$$F^*(f_1^*)(e_1) = f_1^*(F(e_1)) = f_1^*(f_1 + 3f_2 + 5f_3) = 1.$$

$$F^*(f_1^*)(e_2) = f_1^*(F(e_2)) = f_1^*(2f_1 + 4f_2 + 6f_3) = 2.$$

More generally,

 $F^*(f_1^*) = e_1^* + 2e_2^*$ $F^*(f_2^*) = 3e_1^* + 4e_2^*$ $F^*(f_3^*) = 5e_1^* + 6e_2^*$.

 $F^*(w^*)(\vec{v}) := w^*(F(\vec{v})).$

Example: Let $V = \mathbb{R}^2$ and $W = \mathbb{R}^3$. Let $F = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$.

We have $F(e_1) = f_1 + 3f_2 + 5f_3$ and $F(e_2) = 2f_1 + 4f_2 + 6f_3$.

$$F^*(f_1^*)(e_1) = f_1^*(F(e_1)) = f_1^*(f_1 + 3f_2 + 5f_3) = 1.$$

$$F^*(f_1^*)(e_2) = f_1^*(F(e_2)) = f_1^*(2f_1 + 4f_2 + 6f_3) = 2.$$

More generally,

 $F^*(f_1^*) = e_1^* + 2e_2^*$ $F^*(f_2^*) = 3e_1^* + 4e_2^*$ $F^*(f_3^*) = 5e_1^* + 6e_2^*$.

 $F^*(w^*)(\vec{v}) := w^*(F(\vec{v})).$

Example: Let $V = \mathbb{R}^2$ and $W = \mathbb{R}^3$. Let $F = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$.

We have $F(e_1) = f_1 + 3f_2 + 5f_3$ and $F(e_2) = 2f_1 + 4f_2 + 6f_3$.

$$F^*(f_1^*)(e_1) = f_1^*(F(e_1)) = f_1^*(f_1 + 3f_2 + 5f_3) = 1.$$

$$F^*(f_1^*)(e_2) = f_1^*(F(e_2)) = f_1^*(2f_1 + 4f_2 + 6f_3) = 2.$$

More generally,

 $F^*(f_1^*) = e_1^* + 2e_2^*$ $F^*(f_2^*) = 3e_1^* + 4e_2^*$ $F^*(f_3^*) = 5e_1^* + 6e_2^*.$ So the matrix of F is the transpose matrix, $\begin{bmatrix} 1 & 3 & 5 \\ 2 & 4 & 6 \end{bmatrix}$.

You may recall the identity $(AB)^T = B^T A^T$. We can prove this without coordinates, the claim is that $(FG)^* = G^*F^*$, for $G: U \to V$ and $F: V \to W$.

You may recall the identity $(AB)^T = B^T A^T$. We can prove this without coordinates, the claim is that $(FG)^* = G^*F^*$, for $G: U \to V$ and $F: V \to W$.

 $((FG)^*w^*)(\vec{u}) = w^*(FG(\vec{u})).$ $(G^*F^*w^*)(\vec{u}) = (F^*w^*)(G\vec{u}) = w^*(F(G(\vec{u}))).$

You may recall the identity $(AB)^T = B^T A^T$. We can prove this without coordinates, the claim is that $(FG)^* = G^*F^*$, for $G: U \to V$ and $F: V \to W$.

$$((FG)^*w^*)(\vec{u}) = w^*(FG(\vec{u})).$$
$$(G^*F^*w^*)(\vec{u}) = (F^*w^*)(G\vec{u}) = w^*(F(G(\vec{u})))$$

If you have ever felt unsatisifed by transpose, here is where it comes from.

Reminder: "Surjective" means "image is everything"; "injective" means "kernel is zero".

In finite dimensions, this says "if a matrix is surjective, then its transpose is injective".

Proof: Suppose for $F^*(w^*)$ is the 0-function, so $(F^*(w^*))(\vec{v})$ for all vectors \vec{v} in V.

Proof: Suppose for $F^*(w^*)$ is the 0-function, so $(F^*(w^*))(\vec{v})$ for all vectors \vec{v} in V. In other words, $w^*(F(\vec{v})) = 0$ for all \vec{v} . So w^* is 0 for inputs in Image(F).

Proof: Suppose for $F^*(w^*)$ is the 0-function, so $(F^*(w^*))(\vec{v})$ for all vectors \vec{v} in V. In other words, $w^*(F(\vec{v})) = 0$ for all \vec{v} . So w^* is 0 for inputs in Image(F).

But our assumption is that Image(F) is everything. So this shows that w^* is 0 for every input, and $w^* = 0$, as desired. \Box

What about the reverse direction? If $F: V \to W$ is injective, is $W^* \to V^*$ surjective?

Another way to put this is: If v^* is any linear functional $V \to F$, and V embeds as a subspace of W, can we extend v^* to a linear functional on W? What about the reverse direction? If $F: V \to W$ is injective, is $W^* \to V^*$ surjective?

Another way to put this is: If v^* is any linear functional $V \to F$, and V embeds as a subspace of W, can we extend v^* to a linear functional on W?

Theorem: If V and W are finite dimensional, and $F: V \to W$ is injective, then $W^* \to V^*$ is surjective.

Proof: Let $\vec{v}_1, \vec{v}_2, \ldots, \vec{v}_k$ be a basis of V, so that $F(\vec{v}_1), F(\vec{v}_2), \ldots, F(\vec{v}_k)$ is a basis of F(V). Then extend $F(\vec{v}_1), F(\vec{v}_2), \ldots, F(\vec{v}_k)$ to a basis $F(\vec{v}_1), F(\vec{v}_2), \ldots, F(\vec{v}_k), \vec{w}_1, \vec{w}_2, \ldots, \vec{w}_{n-k}$ of W. Put $U = \operatorname{Span}(\vec{w}_1, \vec{w}_2, \ldots, \vec{w}_{n-k})$. Then $W = U \oplus F(V)$. So every vector $\vec{w} \in W$ can be written uniquely as $\vec{u} + F(\vec{v})$. Then define $w^*(\vec{w})$ to be $v^*(\vec{v})$. \Box

What about the reverse direction? If $F: V \to W$ is injective, is $W^* \to V^*$ surjective?

Another way to put this is: If v^* is any linear functional $V \to F$, and V embeds as a subspace of W, can we extend v^* to a linear functional on W?

Theorem: If V and W are finite dimensional, and $F: V \to W$ is injective, then $W^* \to V^*$ is surjective.

The infinite dimensional case is not obvious! For example, consider $\mathbb{R}_{\text{finite}}^{\infty} \subset \mathbb{R}^{\infty}$. We have a linear functional $(a_1, a_2, \ldots) \mapsto \sum a_i$ on $\mathbb{R}_{\text{finite}}^{\infty}$. If we can extend this to \mathbb{R}^{∞} , this means that we can define a notion of sum for every sequence, no matter how divergent. More later ...