Row operations, invertible matrices, row reduced echelon form

Last time: Let A be a matrix and let B be the matrix where we take A and double the first row:

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \qquad B = \begin{bmatrix} 2a & 2b \\ c & d \end{bmatrix}$$

Then A and B have the same kernel. The image of B is the set of vectors  $\begin{bmatrix} 2x \\ y \end{bmatrix}$  for  $\begin{bmatrix} x \\ y \end{bmatrix}$  in the image of A.

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Then A and B have the same kernel. The image of B is the set of vectors  $\begin{bmatrix} 2x \\ y \end{bmatrix}$  for  $\begin{bmatrix} x \\ y \end{bmatrix}$  in the image of B.

We can write this more clearly in terms of the matrix  $D = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$ . So B = DA.

Our statements are

$$\operatorname{Ker}(DA) = \operatorname{Ker}(A)$$
 and  $\operatorname{Im}(DA) = D\operatorname{Im}(A)$ .

The key property of D is that it is *invertible*. This means that there is a matrix C, called the *inverse* of D, with

CD = Id and DC = Id.

We write  $C = D^{-1}$ .

In this case where  $D = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$ , the inverse matrix is  $\begin{bmatrix} 1/2 & 0 \\ 0 & 1 \end{bmatrix}$ . We'll see soon that only square matrices can have inverses.

Can you show? **Theorem** If A and B are invertible, then AB is invertible. **Theorem** A matrix U can only have one inverse. In other words, if UV = UW = Id and VU = WU = Id, then V = W.

**Theorem** If A and B are invertible, then AB is invertible. **Proof:** We claim that  $B^{-1}A^{-1}$  is the inverse of AB. Indeed:  $(AB)(B^{-1}A^{-1}) = A(BB^{-1})A^{-1} = A\mathrm{Id}A^{-1} = AA^{-1} = \mathrm{Id}$  and  $(B^{-1}A^{-1})(AB) = B^{-1}(A^{-1}A)B = B^{-1}\mathrm{Id}B = B^{-1}B = \mathrm{Id}.$ 

The inverse of "put on your socks, put on your shoes" is "take off your shoes, take off your socks". **Theorem** A matrix U can only have one inverse. In other words, if UV = UW = Id and VU = WU = Id, then V = W.

**Proof:** Consider VUW. We have VUW = (VU)W = IdW = Wbut also VUW = V(UW) = VId = V so W = V.  $\Box$  Now, back to our main point:

**Theorem** Let *E* be an invertible  $m \times m$  matrix and let *A* be any  $m \times n$  matrix. Then Ker(EA) = Ker(A) and Im(EA) = EIm(A).

In other words,  $EA\vec{x} = \vec{0}$  if and only if  $A\vec{x} = \vec{0}$ . For  $\vec{y}$  in  $\mathbb{R}^m$ , there is an  $\vec{x}$  with  $A\vec{x} = \vec{y}$  if and only if there is a  $\vec{w}$  with  $EA\vec{w} = E\vec{y}$ .

**Theorem** Let E be an invertible  $m \times m$  matrix and let A be any  $m \times n$  matrix. Then  $\operatorname{Ker}(EA) = \operatorname{Ker}(A)$  and  $\operatorname{Im}(EA) = E\operatorname{Im}(A)$ . In other words,  $EA\vec{x} = \vec{0}$  if and only if  $A\vec{x} = \vec{0}$ . For  $\vec{y}$  in  $\mathbb{R}^m$ , there is an  $\vec{x}$  with  $A\vec{x} = \vec{y}$  if and only if there is a  $\vec{w}$  with  $EA\vec{w} = E\vec{y}$ . **Proof:** If  $A\vec{x} = \vec{0}$  then  $EA\vec{x} = E\vec{0} = \vec{0}$ . On the other hand, if  $EA\vec{x} = \vec{0}$ , then  $E^{-1}EA\vec{x} = \operatorname{Id}A\vec{x} = A\vec{x}$  so  $A\vec{x} = E^{-1}\vec{0} = \vec{0}$ . If  $A\vec{x} = \vec{y}$  then  $EA\vec{x} = E\vec{y}$ . Conversely, if  $EA\vec{x} = E\vec{y}$  then  $E^{-1}EA\vec{x} = E^{-1}E\vec{y}$ , meaning that  $A\vec{x} = \vec{y}$ . **Theorem** Let *E* be an invertible  $m \times m$  matrix and let *A* be any  $m \times n$  matrix. Then Ker(EA) = Ker(A) and Im(EA) = EIm(A).

Take

$$E = \begin{bmatrix} 1 & & & & \\ 1 & & & & \\ & \ddots & & & \\ & & c & & \\ & & & \ddots & \\ & & & & & 1 \end{bmatrix} \qquad c \neq 0.$$

We get the row operation of multiplying a single row by a nonzero scalar.

This is one of three row operations:

- 1. Multiply a row by a nonzero scalar.
- 2. Switch two rows.
- 3. Add a multiple of one row to another row.

All of the row operations are multiplication by invertible matrices:

1. Multiply a row by a nonzero scalar.



2. Switch two rows.



3. Add a multiple of one row to another row.

$$\begin{bmatrix} 1 & & & \\ & \ddots & \\ & & 1 & \\ & & \ddots & \\ -a & & & 1 \end{bmatrix}$$

Thus, if we get from one matrix A to another matrix B by row operations, then Ker(A) = Ker(B) and the images of A and B are related in a natural way. There will be an invertible matrix U with B = UA. Thus, if we get from one matrix A to another matrix B by row operations, then Ker(A) = Ker(B) and the images of A and B are related in a natural way. There will be an invertible matrix U with B = UA.

This raises the natural question: How nice can we make a matrix, using row operations? The answer is row reduced echelon form.

## Row reduced echelon form

- Either row is either all 0's, or else its first nonzero entry is a 1. This 1 is called a *pivot*.
- In a column which contains a pivot, called a *pivot column*, all the other entries are 0.
- The nonzero rows are at the top of the matrix; they are ordered so that the pivots go from left to right as we go down the rows.

$$\begin{bmatrix} 1 & 3 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

Putting a matrix into row reduced echelon form

To make a matrix into row reduced echelon form (rref), we work from left to right. Look at the leftmost column which is not yet a pivot column, and which has a nonzero in a non-pivot row.

• Rescale that entry to be 1.

• Subtract appropriate multiples of the row with the 1 from other rows to make the other entries of that column be 0.

• Switch rows, if needed, to put that row immediately below the already existing pivot rows.

$$\begin{bmatrix} 3 & 6 & 3 & 12 \\ 1 & 2 & 4 & 13 \\ 2 & 4 & 4 & 14 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 2 & 1 & 4 \\ 1 & 2 & 4 & 13 \\ 2 & 4 & 4 & 14 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 2 & 1 & 4 \\ 0 & 0 & 3 & 9 \\ 0 & 0 & 2 & 6 \end{bmatrix}$$
$$\rightsquigarrow \begin{bmatrix} 1 & 2 & 1 & 4 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 2 & 6 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Vocabulary related to rref

- The initial leading 1's are called *pivots*. The columns that contain them are called *pivot columns*; the corresponding variables in our system of equations are called *pivot variables*.
- The columns/variables which are not pivot columns/variables are called *free columns/variables*.
- The number of pivots is called the *rank*.