The Cayley-Hamilton theorem

We've seen a lot of concepts:

- Eigenvectors and eigenvalues
- Eigenbasis
- Characteristic polynomial
- Minimal polynomial

We've seen a lot of concepts:

• Eigenvectors and eigenvalues

A vector \vec{v} with $A\vec{v} = \lambda \vec{v}$ is called an eigenvector. We call λ the eigenvalue.

• Eigenbasis

A basis $\vec{v}_1, \vec{v}_2, \ldots, \vec{v}_n$ of eigenvectors. If $\vec{v}_1, \vec{v}_2, \ldots, \vec{v}_n$ are nonzero eigenvectors with distinct eigenvalues, they must be an eigenbasis.

- Characteristic polynomial The polynomial $\chi_A(x) = \det(x \operatorname{Id} - A)$. Its roots are the eigenvalues.
- Minimal polynomial

The lowest degree polynomial m(x) with m(A) = 0. If f(x) is any other polynomial with f(A) = 0, then m(x) divides f(x). Let V be a finite dimensional vector space, $A: V \to V$ a linear transformation, $\chi_A(x)$ the characteristic polynomial and $m_A(x)$ the minimal polynomial.

Theorem: Let λ be a scalar. Then the following are equivalent:

- (1) λ is an eigenvalue of A.
- (2) λ is a root of $\chi_A(x)$.
- (3) λ is a root of $m_A(x)$.

Question: Which parts have we already proved? How did we prove them?

Theorem: Let λ be a scalar. Then the following are equivalent:

- (1) λ is an eigenvalue of A.
- (2) λ is a root of $\chi_A(x)$.
- (3) λ is a root of $m_A(x)$.

(1) \iff (2): We have $\chi_A(\lambda) = 0$ if and only if $\det(A - \lambda \operatorname{Id}) \neq 0$ if and only if there is a vector \vec{v} with $(A - \lambda \operatorname{Id})\vec{v} = \vec{0}$ if and only if there is a vector \vec{v} with $A\vec{v} = \lambda\vec{v}$. **Theorem:** Let λ be a scalar. Then the following are equivalent:

- (1) λ is an eigenvalue of A.
- (2) λ is a root of $\chi_A(x)$.
- (3) λ is a root of $m_A(x)$.

(1) \iff (2): We have $\chi_A(\lambda) = 0$ if and only if det $(A - \lambda \text{Id}) \neq 0$ if and only if there is a vector \vec{v} with $(A - \lambda \text{Id})\vec{v} = \vec{0}$ if and only if there is a vector \vec{v} with $A\vec{v} = \lambda\vec{v}$.

(1) \implies (3): Let \vec{v} be a nonzero λ -eigenvector. For any polynomial f(x), we have $f(A)\vec{v} = f(\lambda)\vec{v}$. In particular, $m_A(A)\vec{v} = m_A(\lambda)\vec{v}$. But $m_A(A)\vec{v} = 0\vec{v} = \vec{0}$, so $m_A(\lambda) = 0$.

(3) \implies (1): Since λ is a root of $m_A(x)$, we can write $m_A(x) = (x - \lambda)f(x)$. Suppose that λ is not an eigenvalue of A. Then $A - \lambda$ Id is invertible. We have $m_A(A) = (A - \lambda \text{Id})f(A) = 0$. So $f(A) = (A - \lambda \text{Id})^{-1}0 = 0$. But deg $f < \text{deg } m_A$, a contradiction. **Theorem:** Let λ be a scalar. Then the following are equivalent:

- (1) λ is an eigenvalue of A.
- (2) λ is a root of $\chi_A(x)$.
- (3) λ is a root of $m_A(x)$.

So $m_A(x)$ and $\chi_A(x)$ have the same roots, but maybe with different multiplicities. Our main result for today improves (3) \implies (2):

The Cayley-Hamilton theorem We have $\chi_A(A) = 0$ and, therefore, $m_A(x)$ divides $\chi_A(x)$. The Cayley-Hamilton theorem We have $\chi_A(A) = 0$ and, therefore, $m_A(x)$ divides $\chi_A(x)$. The Cayley-Hamilton theorem We have $\chi_A(A) = 0$ and, therefore, $m_A(x)$ divides $\chi_A(x)$.

Let's start with an example, to make it clear what we are proving. Let $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$. The characteristic polynomial is $(x-1)(x-4) - 2 \cdot 3 = x^2 - 5x + 4 - 6 = x^2 - 5x - 2$.

We have

 $\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}^2 - 5\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} - 2\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 7 & 10 \\ 15 & 22 \end{bmatrix} - \begin{bmatrix} 5 & 10 \\ 15 & 20 \end{bmatrix} - \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}.$

For diagonalizable matrices:

Suppose that $A = \begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & \ddots & \end{bmatrix}$.

Then $\chi_A(x) = \det(x \operatorname{Id} - A) = (x - \lambda_1)(x - \lambda_2) \cdots (x - \lambda_n).$

For each eigenvector $\vec{v_i}$, we have $(A - \lambda_1)(A - \lambda_2) \cdots (A - \lambda_n)\vec{v_i} = (\lambda_i - \lambda_1)(\lambda_i - \lambda_2) \cdots (\lambda_i - \lambda_i) \cdots (\lambda_i - \lambda_n)\vec{v_i} = 0\vec{v_i} = \vec{0}$. So $\chi_A(A)\vec{v_i} = \vec{0}$

Another important case

Suppose that there is a vector \vec{v} such that \vec{v} , $A\vec{v}$, $A^2\vec{v}$, ..., $A^{n-1}\vec{v}$ is a basis of V. In this case, we must have

$$A^{n}\vec{v} = c_{0}\vec{v} + c_{1}A\vec{v} + c_{2}A^{2}\vec{v} + \dots + c_{n-1}A^{n-1}\vec{v}.$$

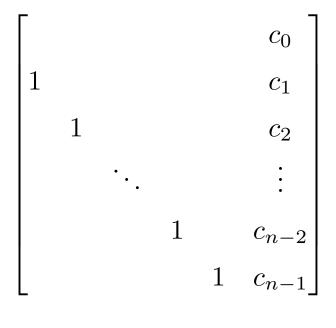
Question: What is the matrix of A in the basis \vec{v} , $A\vec{v}$, $A^2\vec{v}$, ..., $A^{n-1}\vec{v}$?

Another important case

Suppose that there is a vector \vec{v} such that \vec{v} , $A\vec{v}$, $A^2\vec{v}$, ..., $A^{n-1}\vec{v}$ is a basis of V. In this case, we must have

$$A^{n}\vec{v} = c_{0}\vec{v} + c_{1}A\vec{v} + c_{2}A^{2}\vec{v} + \dots + c_{n-1}A^{n-1}\vec{v}.$$

Question: What is the matrix of A in the basis \vec{v} , $A\vec{v}$, $A^2\vec{v}$, ..., $A^{n-1}\vec{v}$?



What is the characteristic polynomial?

We expand along the top row:

$$\det \begin{bmatrix} x & & -c_0 \\ -1 & x & & -c_1 \\ & -1 & x & & -c_2 \\ & \ddots & \ddots & & \vdots \\ & & -1 & x & -c_{n-2} \\ & & & -1 & x - c_{n-1} \end{bmatrix} =$$

$$x \det \begin{bmatrix} x & -c_1 \\ -1 x & -c_2 \\ \vdots & \vdots \\ -1 x - c_{n-2} \\ & -1 x - c_{n-1} \end{bmatrix} + (-1)^n c_0 \det \begin{bmatrix} -1 x \\ -1 x \\ \vdots \\ & \vdots \\ & -1 x \\ & -1 x \end{bmatrix} =$$

$$x \det \begin{bmatrix} x & -c_1 \\ -1 x & -c_2 \\ \vdots & \vdots \\ -1 x - c_{n-2} \\ & -1 x - c_{n-1} \end{bmatrix} - c_0.$$

What is the characteristic polynomial?

$$\det \begin{bmatrix} x & & -c_{0} \\ -1 & x & & -c_{1} \\ & -1 & x & -c_{2} \\ & & \ddots & \vdots \\ & -1 & x & -c_{n-2} \\ & -1 & x & -c_{2} \\ & & & \ddots & \vdots \\ & & -1 & x & -c_{n-2} \\ & & -1 & x & -c_{n-1} \end{bmatrix} + (-1)^{n} c_{0} \det \begin{bmatrix} -1 & x \\ & -1 & x \\ & & -1 & x \\ & & & -1 & x \\ & & & & -1 \end{bmatrix} = x \det \begin{bmatrix} x & & -c_{1} \\ & -1 & x \\ & & & -1 \end{bmatrix} = x \det \begin{bmatrix} x & & -c_{1} \\ -1 & x & -c_{2} \\ & & \ddots & & \vdots \\ & & -1 & x & -c_{n-2} \\ & & & & -1 & x -c_{n-2} \\ & & & & & -1 & x -c_{n-1} \end{bmatrix} - c_{0}.$$

Continuing:

$$x^{2} \det \begin{bmatrix} x & -c_{2} \\ \vdots & \vdots \\ -1 & x & -c_{n-2} \end{bmatrix} - c_{1}x - c_{0} = \cdots$$
$$= x^{n} - c_{n-1}x^{n-1} - \cdots - c_{2}x^{2} - c_{1}x - c_{0}.$$

To summarize the previous computation: If there is a vector \vec{v} such that $\vec{v}, A\vec{v}, A^2\vec{v}, \ldots, A^{n-1}\vec{v}$ is a basis of V, and

$$A^{n}\vec{v} = c_{0}\vec{v} + c_{1}A\vec{v} + c_{2}A^{2}\vec{v} + \dots + c_{n-1}A^{n-1}\vec{v}$$

then the characteristic polynomial of A is

$$x^{n} - c_{n-1}x^{n-1} - \dots - c_{2}x^{2} - c_{1}x - c_{0}.$$

To summarize the previous computation: If there is a vector \vec{v} such that $\vec{v}, A\vec{v}, A^2\vec{v}, \ldots, A^{n-1}\vec{v}$ is a basis of V, and

$$A^{n}\vec{v} = c_{0}\vec{v} + c_{1}A\vec{v} + c_{2}A^{2}\vec{v} + \dots + c_{n-1}A^{n-1}\vec{v}$$

then the characteristic polynomial of A is

$$x^{n} - c_{n-1}x^{n-1} - \dots - c_{2}x^{2} - c_{1}x - c_{0}.$$

So we want to show that

$$A^{n} - c_{n-1}A^{n-1} - \dots - c_{2}A^{2} - c_{1}A - c_{0} = 0.$$

To summarize the previous computation: If there is a vector \vec{v} such that $\vec{v}, A\vec{v}, A^2\vec{v}, \ldots, A^{n-1}\vec{v}$ is a basis of V, and

$$A^{n}\vec{v} = c_{0}\vec{v} + c_{1}A\vec{v} + c_{2}A^{2}\vec{v} + \dots + c_{n-1}A^{n-1}\vec{v}$$

then the characteristic polynomial of A is

$$x^{n} - c_{n-1}x^{n-1} - \dots - c_{2}x^{2} - c_{1}x - c_{0}.$$

So we want to show that

$$A^{n} - c_{n-1}A^{n-1} - \dots - c_{2}A^{2} - c_{1}A - c_{0} = 0.$$

We just need to check that $A^n - c_{n-1}A^{n-1} - \cdots - c_2A^2 - c_1A - c_0$ kills each basis vector. We certainly have

$$(A^n - c_{n-1}A^{n-1} - \dots - c_2A^2 - c_1A - c_0) \vec{v} = A^n \vec{v} - c_{n-1}A^{n-1} \vec{v} - \dots - c_2A^2 \vec{v} - c_1A \vec{v} - c_0 \vec{v} = \vec{0}.$$

We just need to check that $A^n - c_{n-1}A^{n-1} - \cdots - c_2A^2 - c_1A - c_0$ kills each basis vector. We certainly have

$$(A^n - c_{n-1}A^{n-1} - \dots - c_2A^2 - c_1A - c_0) \vec{v} = A^n \vec{v} - c_{n-1}A^{n-1} \vec{v} - \dots - c_2A^2 \vec{v} - c_1A \vec{v} - c_0 \vec{v} = \vec{0}.$$

Working a bit harder,

$$(A^n - c_{n-1}A^{n-1} - \dots - c_2A^2 - c_1A - c_0) (A^j \vec{v}) = A^j (A^n - c_{n-1}A^{n-1} - \dots - c_2A^2 - c_1A - c_0) \vec{v} = A^j \vec{0} = \vec{0}.$$

Why did we spend so long on this special case? Because it is going to be the heart of our proof of the general case. We now prove the Cayley-Hamilton theorem by induction on n. We now prove the Cayley-Hamilton theorem by induction on n. The base case is n = 1, so A = [a], the characteristic polynomial is x - a, and we have $A - a \operatorname{Id} = 0$ as desired. We now prove the Cayley-Hamilton theorem by induction on n. The base case is n = 1, so A = [a], the characteristic polynomial is x - a, and we have $A - a \operatorname{Id} = 0$ as desired.

Now, choose any nonzero vector \vec{v} and start computing \vec{v} , $A\vec{v}$, $A^2\vec{v}$ until the first point where we have a linear dependency

 $A^{m}\vec{v} = c_{m-1}A^{m-1}\vec{v} + \dots + c_{2}A^{2}\vec{v} + c_{1}A\vec{v} + c_{0}\vec{v}.$

Completing $\vec{v}, A\vec{v}, A^2\vec{v}, \ldots, A^{m-1}\vec{v}$ to a basis, the operator A looks like

$$\begin{bmatrix} P & Q \\ 0 & R \end{bmatrix} \text{ where } P = \begin{bmatrix} 1 & & c_0 \\ 1 & & c_1 \\ & 1 & & c_2 \\ & \ddots & & \vdots \\ & & 1 & c_{m-2} \\ & & & 1 & c_{m-1} \end{bmatrix}$$

$$A = \begin{bmatrix} P & Q \\ 0 & R \end{bmatrix} \text{ where } P = \begin{bmatrix} 1 & & c_0 \\ 1 & & c_2 \\ & \ddots & & \vdots \\ & & 1 & c_{m-2} \\ & & & 1 & c_{m-1} \end{bmatrix}$$

By our previous computation, $\chi_P(P) = 0$. If P is the whole matrix A, we are done.

$$A = \begin{bmatrix} P & Q \\ 0 & R \end{bmatrix} \text{ where } P = \begin{bmatrix} 1 & & c_0 \\ 1 & & c_1 \\ 1 & & c_2 \\ & \ddots & & \vdots \\ & & 1 & c_{m-2} \\ & & & 1 & c_{m-1} \end{bmatrix}$$

By our previous computation, $\chi_P(P) = 0$. If P is the whole matrix A, we are done.

If not, by induction, we also have $\chi_R(R) = 0$. And we have $\chi_A(x) = \chi_P(x)\chi_R(x)$. So

$$\chi_A(A) = \chi_A\left(\begin{bmatrix} P & Q \\ 0 & R \end{bmatrix}\right) = \chi_P\left(\begin{bmatrix} P & Q \\ 0 & R \end{bmatrix}\right)\chi_R\left(\begin{bmatrix} P & Q \\ 0 & R \end{bmatrix}\right) = \begin{bmatrix}\chi_P(P) * \\ 0 & *\end{bmatrix}\begin{bmatrix}* & * \\ 0 & \chi_R(R)\end{bmatrix} = \begin{bmatrix}0 * \\ 0 *\end{bmatrix}\begin{bmatrix}* * \\ 0 & 0\end{bmatrix} = \begin{bmatrix}0 & 0 \\ 0 & 0\end{bmatrix}$$

$$A = \begin{bmatrix} P & Q \\ 0 & R \end{bmatrix} \text{ where } P = \begin{bmatrix} 1 & & c_0 \\ 1 & & c_1 \\ 1 & & c_2 \\ & \ddots & & \vdots \\ & & 1 & c_{m-2} \\ & & & 1 & c_{m-1} \end{bmatrix}$$

By our previous computation, $\chi_P(P) = 0$. If P is the whole matrix A, we are done.

If not, by induction, we also have $\chi_R(R) = 0$. And we have $\chi_A(x) = \chi_P(x)\chi_R(x)$. So

$$\chi_A(A) = \chi_A\left(\begin{bmatrix} P & Q \\ 0 & R \end{bmatrix}\right) = \chi_P\left(\begin{bmatrix} P & Q \\ 0 & R \end{bmatrix}\right)\chi_R\left(\begin{bmatrix} P & Q \\ 0 & R \end{bmatrix}\right) = \begin{bmatrix}\chi_P(P) * \\ 0 & *\end{bmatrix}\begin{bmatrix}* & * \\ 0 & \chi_R(R)\end{bmatrix} = \begin{bmatrix}0 * \\ 0 *\end{bmatrix}\begin{bmatrix}* * \\ 0 & *\end{bmatrix} = \begin{bmatrix}0 & 0 \\ 0 & 0\end{bmatrix}$$

QED