

NOTES FOR 25 JANUARY 2011

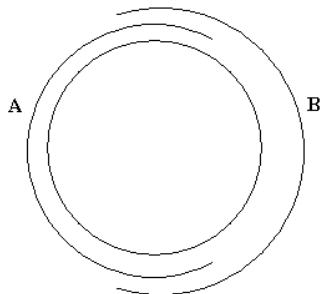
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1. SHEAF COHOMOLOGY EXAMPLES

Basic point: Sheaf cohomology depends on the space and the sheaf. In basic topology, for X a space, A an abelian group, we have groups $H^k(X, A)$; the coefficients A matter. For “reasonable” spaces (e.g. finite simplicial complexes),

$$H^k(X, \text{locally constant } A\text{-valued functions}) = H_{\text{top}}^k(X, A).$$

On S^1 , look at the sheaf $\mathcal{L}\mathcal{C}$ (sheaf of locally constant real-valued functions). Take the open cover $A \cup B$ illustrated below. To use Čech cohomology, we need to know higher cohomology vanishes on each intersection. Here, each intersection is contractible, hence higher cohomology vanishes.



Then since A and B are connected but $A \cap B$ has two connected components,

$$(1) \quad 0 \longrightarrow \mathcal{L}\mathcal{C}(A) \oplus \mathcal{L}\mathcal{C}(B) \longrightarrow \mathcal{L}\mathcal{C}(A \cap B) \longrightarrow 0$$

$$0 \longrightarrow \mathbb{R} \oplus \mathbb{R} \xrightarrow{M} \mathbb{R}^{\oplus 2} \longrightarrow 0$$

where M is the matrix

$$M = \begin{pmatrix} 1 & -1 \\ 1 & -1 \end{pmatrix}$$

(our matrices act on the left, so we think of these as column vectors). Hence

$$H^0(S^1, \mathcal{L}\mathcal{C}) = \ker M = \mathbb{R} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

and

$$H^1(S^1, \mathcal{L}\mathcal{C}) = \text{coker } M \cong \mathbb{R}.$$

For a larger example, we could think of S^2 as a cube, with an open cover consisting of open sets around each facet. We get the Čech complex

$$0 \rightarrow \mathbb{R}^6 \rightarrow \mathbb{R}^{12} \rightarrow \mathbb{R}^8 \rightarrow 0$$

with cohomology

$$\begin{aligned} H^0(S^2, \mathcal{L}\mathcal{C}) &= \mathbb{R} \\ H^1(S^2, \mathcal{L}\mathcal{C}) &= 0 \\ H^2(S^2, \mathcal{L}\mathcal{C}) &= \mathbb{R}. \end{aligned}$$

We will now work through the de Rham isomorphism for the circle (doing it for the sphere is a good exercise). On the circle, we have an exact sequence of sheaves

$$0 \rightarrow \mathcal{L}\mathcal{C} \rightarrow C^\infty \rightarrow \Omega^1 \rightarrow 0$$

In general the third term would be Z^1 (closed 1-forms), but on a one dimensional manifold, every 1-form is closed. The long exact sequence is

$$0 \rightarrow \mathcal{L}\mathcal{C}(S^1) \rightarrow C^\infty(S^1) \rightarrow \Omega^1(S^1) \rightarrow H^1(S^1, \mathcal{L}\mathcal{C}) \rightarrow 0$$

where the last 0 is because the sheaf C^∞ has partitions of unity, and hence higher cohomology vanishes.

We have the commutative diagram

$$\begin{array}{ccccccc} & & 0 & & 0 & & \\ & & \downarrow & & \downarrow & & \\ 0 & \longrightarrow & \mathbb{R} \oplus \mathbb{R} & \xrightarrow{\begin{pmatrix} 1 & -1 \\ 1 & -1 \end{pmatrix}} & \mathbb{R}^{\oplus 2} & \longrightarrow & 0 \\ & & \downarrow & & \downarrow & & \\ 0 & \longrightarrow & C^\infty(A) \oplus C^\infty(B) & \longrightarrow & C^\infty(A \cap B) & \longrightarrow & 0 \\ & & \downarrow & & \downarrow & & \\ 0 & \longrightarrow & \Omega^1(A) \oplus \Omega^1(B) & \longrightarrow & \Omega^1(A \cap B) & \longrightarrow & 0 \\ & & \downarrow & & \downarrow & & \\ & & 0 & & 0 & & \end{array}$$

where the first row is the exact sequence (1), and columns are exact by the Poincaré lemma.

Given $\omega \in \Omega^1(S^1)$, consider it as $(\omega_1, \omega_2) \in \Omega^1(A) \oplus \Omega^1(B)$ by restricting to each interval. From our diagram, we can lift this up to $(f_1, f_2) \in C^\infty(A) \oplus C^\infty(B)$ such that $df_i = \omega_i$; i.e.,

$$\begin{aligned} f_1(\theta) &= \int_P^\theta \omega_1 \\ f_2(\theta) &= \int_P^\theta \omega_2 \end{aligned}$$

where P is a point in one of the connected components of $A \cap B$, and the integrals are computed in A and B respectively (so in opposite directions). Next we go across to $f_1 - f_2 \in C^\infty(A \cap B)$. This is 0 in the connected component of $A \cap B$ containing P . On the other connected component, this is $\oint \omega$. Therefore, $f_1 - f_2$ is locally constant, with values 0 and $\oint \omega$ on the two connected components of $A \cap B$. Hence

$$f_1 - f_2 = \begin{pmatrix} \oint \omega \\ 0 \end{pmatrix}$$

in $\mathcal{L}\mathcal{C}(A \cap B) \cong \mathbb{R}^2$. The image in $H^1(S^1, \mathcal{L}\mathcal{C})$ is therefore $\oint \omega$.

There are two harder versions in HW 3: one involves using two complexes, $0 \rightarrow \mathcal{L}\mathcal{C} \rightarrow C^\infty \rightarrow Z^1 \rightarrow 0$ and $0 \rightarrow Z^1 \rightarrow \Omega^1 \rightarrow \Omega^2 \rightarrow 0$.

2. COMPLEX DIFFERENTIAL OPERATORS

The main objects today will be smooth functions $f : \mathbb{C}^n \rightarrow \mathbb{C}$,

$$(x_1 + iy_1, \dots, x_n + iy_n) \mapsto (u, v)$$

where $u(x_1, \dots, x_n, y_1, \dots, y_n)$ and $v(x_1, \dots, x_n, y_1, \dots, y_n)$ are elements of $C^\infty(\mathbb{R}^{2n})$. For such an f ,

$$df = du + idv.$$

In particular, $z_1, \dots, z_n, \bar{z}_1, \dots, \bar{z}_n$ are such functions $\mathbb{C}^n \rightarrow \mathbb{C}$, so we have $dz_1, \dots, dz_n, d\bar{z}_1, \dots, d\bar{z}_n$ with

$$dz_k = dx_k + idy_k \quad \text{and} \quad d\bar{z}_k = dx_k - idy_k.$$

We can rearrange to solve for dx_k and dy_k :

$$dx_k = \frac{dz_k + d\bar{z}_k}{2} \quad dy_k = \frac{dz_k - d\bar{z}_k}{2i}.$$

Geometrically, dz_k is the 1-form that takes a tangent vector and returns the k th component (as a complex number); $d\bar{z}_k$ returns the complex conjugate. Every smooth 1-form can be uniquely written as

$$\sum f_k(z)dz_k + \sum g_k(z)d\bar{z}_k$$

where $f_1, \dots, f_n, g_1, \dots, g_n$ are smooth \mathbb{C} -valued functions on \mathbb{C}^{2n} .

A 1-form ω is called a **(1,0)-form** if it is of the form

$$\sum f_k(z)dz_k.$$

Similarly, ω is called a **(0,1)-form** if it is of the form

$$\sum g_k(z)d\bar{z}_k.$$

For v a tangent vector to \mathbb{C}^n , let Jv be v rotated by i . Then ω is a (1,0)-form if and only if $\omega(Jv) = i\omega(v)$ and ω is a (0,1)-form if and only if $\omega(Jv) = -i\omega(v)$.

A smooth manifold X with a map

$$J : T_*X \rightarrow T_*X$$

obeying $J^2 = -\text{Id}$ and preserving the base (i.e., J takes tangent vectors at P to other tangent vectors at P) is called **almost complex**. On an almost complex manifold, (0,1)-forms and (1,0)-forms are defined in terms of J as above.

An almost complex manifold which locally looks like an open set in \mathbb{C}^n is called a **complex** manifold.

(The main difference between complex and almost complex: on almost complex manifolds, we can't necessarily find n holomorphic functions like z_1, \dots, z_n so that forms can be written in terms of dz_i and $d\bar{z}_i$.)

For $f : \mathbb{C} \rightarrow \mathbb{C}$ mapping (x, y) to $(u(x, y), v(x, y))$, we have

$$\begin{aligned} df &= du + idv \\ &= \left(\frac{\partial u}{\partial x} dx + \frac{\partial u}{\partial y} dy \right) + i \left(\frac{\partial v}{\partial x} dx + \frac{\partial v}{\partial y} dy \right) \\ &= \frac{\partial u}{\partial x} \left(\frac{dz + d\bar{z}}{2} \right) + \frac{\partial u}{\partial y} \left(\frac{dz - d\bar{z}}{2i} \right) + i \frac{\partial v}{\partial x} \left(\frac{dz + d\bar{z}}{2} \right) + \frac{\partial v}{\partial y} \left(\frac{dz - d\bar{z}}{2} \right) \\ &= \frac{1}{2} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} - i \frac{\partial u}{\partial y} + i \frac{\partial v}{\partial x} \right) dz + \frac{1}{2} \left(\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} + i \frac{\partial u}{\partial y} + i \frac{\partial v}{\partial x} \right) d\bar{z} \\ (2) \quad &= \frac{1}{2} \left(\frac{\partial(u + iv)}{\partial x} - i \frac{\partial(u + iv)}{\partial y} \right) dz + \frac{1}{2} \left(\frac{\partial(u + iv)}{\partial x} + i \frac{\partial(u + iv)}{\partial y} \right) d\bar{z} \end{aligned}$$

The 1-form df is a (1,0)-form if and only if the $d\bar{z}$ part vanishes; i.e., if and only if

$$\begin{aligned} \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} &= 0 \\ \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} &= 0. \end{aligned}$$

These are precisely the Cauchy-Riemann equations. So df is a (1,0)-form if and only if f is holomorphic. Moreover, if f is holomorphic, the above equation for df simplifies to

$$df = f'(z)dz.$$

In general, if $f : \mathbb{C}^n \rightarrow \mathbb{C}$, f is holomorphic if and only if df is a (1,0)-form, in which case

$$df = \sum \frac{\partial f}{\partial z_i} dz_i.$$

Let $df = \sum g_k dz_k + \sum h_k d\bar{z}_k$. Then we define **del** and **del-bar** as

$$\begin{aligned} \partial f &= \sum g_k dz_k \\ \bar{\partial} f &= \sum h_k d\bar{z}_k. \end{aligned}$$

The automorphism J on the complexification of the tangent bundle has eigenvalues i and $-i$. ∂ is the projection onto the i eigenspace and $\bar{\partial}$ is the projection on to the $-i$ eigenspace.

Given $\omega \in \Omega^k(X)$ with $k = p + q$, ω is called a (p, q) -form if

$$\omega = \sum f_{I,J} dz_{i_1} \wedge \dots \wedge dz_{i_p} \wedge d\bar{z}_{j_1} \wedge \dots \wedge d\bar{z}_{j_q}.$$

Every smooth k -form is uniquely a sum of a $(k, 0)$ -form, a $(k-1, 1)$ -form, ..., and a $(0, k)$ -form. On a (p, q) -form, we have

$$\begin{aligned} d\left(\sum f_{I,J} dz_{i_1} \wedge \dots \wedge dz_{i_p} \wedge d\bar{z}_{j_1} \wedge \dots \wedge d\bar{z}_{j_q}\right) &= \sum (df_{I,J}) dz_{i_1} \wedge \dots \wedge dz_{i_p} \wedge d\bar{z}_{j_1} \wedge \dots \wedge d\bar{z}_{j_q} \\ &= \sum \left(\sum \dots dz_i + \sum \dots d\bar{z}_j\right) (dz_{i_1} \wedge \dots \wedge dz_{i_p} \wedge d\bar{z}_{j_1} \wedge \dots \wedge d\bar{z}_{j_q}), \end{aligned}$$

a sum of $(p+1, q)$ -forms and $(p, q+1)$ -forms. We define ∂ as the projection onto the $(p+1, q)$ part and $\bar{\partial}$ as the projection onto the $(p, q+1)$ part.

∂ (and same for $\bar{\partial}$) obeys all the usual formal properties:

- (1) $\partial(u + v) = \partial u + \partial v$
- (2) $\partial(au) = a\partial u$
- (3) $\partial(u \cdot v) = u\partial v + v\partial u$
- (4) $\partial(\omega \wedge \eta) = (-1)^k \omega \wedge \partial\eta + \partial\omega \wedge \eta$ where $\omega \in \Omega^k$.

Additionally, if f is analytic, $\bar{\partial}(f \cdot v) = f\bar{\partial}(v)$.

To integrate

$$\int_{\gamma} f(z) dz$$

for some $f : \mathbb{C} \rightarrow \mathbb{C}$, we break up γ into N subintervals and take the limit

$$\lim_{N \rightarrow \infty} \sum_{i=0}^N f(z_i) \cdot \overset{\text{1-form tan. vector}}{(dz)}(z_{i+1} - z_i) = \lim_{N \rightarrow \infty} \sum_{i=0}^N f(z_i)(z_{i+1} - z_i)$$

to get the usual complex integral.

For f analytic on some domain D ,

$$\int_{\partial D} f dz = \int_D d(f dz) = \int_D df \wedge dz = \int_D \frac{\partial f}{\partial z} dz \wedge dz = \int_D 0 = 0.$$

For $f : \mathbb{C}^n \rightarrow \mathbb{C}$, we define $\frac{\partial f}{\partial z_i}$ and $\frac{\partial f}{\partial \bar{z}_i}$ such that

$$df = \sum \frac{\partial f}{\partial z_i} dz_i + \sum \frac{\partial f}{\partial \bar{z}_i} d\bar{z}_i.$$

Note that this is defined whenever f is smooth (not necessarily holomorphic). Note that f is holomorphic if and only if $\frac{\partial f}{\partial \bar{z}_1}, \dots, \frac{\partial f}{\partial \bar{z}_n}$ are 0.

Something I didn't say in class (but should have) One has the explicit formulas:

$$\frac{\partial}{\partial z} = \frac{1}{2} \left(\frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right) \quad \frac{\partial}{\partial \bar{z}} = \frac{1}{2} \left(\frac{\partial}{\partial x} + i \frac{\partial}{\partial y} \right)$$

These can be read off from the last line in equation (2).

A warning about the partial notation: on \mathbb{R}^2 , consider the coordinate charts (x, y) and $(x, x+y)$ (a grid and a slanted grid). Let f be the same function on each. Then $\frac{\partial f}{\partial x}$ means different things in the two charts! (Hence the partial notation can be misleading.)

Next time: The **Dolbeault complex**¹

$$0 \rightarrow \text{holomorphic functions} \rightarrow \Omega^{0,0} \xrightarrow{\bar{\partial}} \Omega^{0,1} \xrightarrow{\bar{\partial}} \Omega^{0,2} \xrightarrow{\bar{\partial}} \dots \xrightarrow{\bar{\partial}} \Omega^{0,n} \rightarrow 0.$$

and more generally,

$$0 \rightarrow \text{holomorphic } (p, 0)\text{-forms} \rightarrow \Omega^{p,0} \xrightarrow{\bar{\partial}} \Omega^{p,1} \xrightarrow{\bar{\partial}} \Omega^{p,2} \xrightarrow{\bar{\partial}} \dots \xrightarrow{\bar{\partial}} \Omega^{p,n} \rightarrow 0.$$

When is this exact?

¹I got this wrong on the board; I fixed it here. DES