

TENSOR INVARIANTS

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Throughout this note, let $\dim V = d$, and fix two positive integers m and n . We will be discussing $(V^{\otimes m} \otimes (V^\vee)^{\otimes n})^{SL(V)}$. I'll use v 's to denote elements of V and u 's for elements of V^\vee .

1. FIXED VECTORS VERSUS INVARIANT FUNCTIONS

$V^{\otimes m} \otimes (V^\vee)^{\otimes n}$ is the same thing as $\text{Hom}((V^\vee)^{\otimes m} \otimes V^{\otimes n}, \mathbb{C})$. So, instead of looking at fixed vectors in $V^{\otimes m} \otimes (V^\vee)^{\otimes n}$, we could think about $SL(V)$ invariant linear functions on $(V^\vee)^{\otimes m} \otimes V^{\otimes n}$.

For general analysis, this seems to just add a layer of complication. But for giving examples, it makes things nicer. Let's see why.

Remember that $X \otimes Y$ is spanned by simple tensors; meaning tensors of the form $x \otimes y$. To give an element ϕ of $(X \otimes Y)^\vee$ is to give a map which, to any $x \in X$ and $y \in Y$, computes a number $\phi(x \otimes y)$. Moreover, this computation must be linear in both x and in y .

So an element of $\text{Hom}((V^\vee)^{\otimes m} \otimes V^{\otimes n}, \mathbb{C})$ means a map ϕ which takes in m elements of V^\vee and n elements of V and, in a multilinear fashion, produces a scalar.

For example, $(u, v) \mapsto \langle u, v \rangle$ is an element of $\text{Hom}(V^\vee \otimes V, \mathbb{C})$. If $\dim V = 3$, then $(v_1, v_2, v_3) \mapsto v_1 \wedge v_2 \wedge v_3$ is an element of $\text{Hom}(V^{\otimes 3}, \mathbb{C})$ (where we have chosen an identification $\bigwedge^3 V \cong \mathbb{C}$.) Note that the first function is $GL(V)$ invariant, and the second is $SL(V)$ invariant.

For whatever reason, mathematicians don't have simple names for "the $GL(V)$ invariant element of $V \otimes V^\vee$ ", or for "the $SL(V)$ invariant element of $(V^\vee)^{\otimes 3}$ when $\dim V = 3$." Even if you have names for these, you probably don't have a name for the element of $V^{\otimes 3} \otimes (V^\vee)^{\otimes 3}$ which corresponds to

$$(u_1, u_2, u_3, v_1, v_2, v_3) \mapsto \det \begin{pmatrix} \langle u_1, v_1 \rangle & \langle u_1, v_2 \rangle & \langle u_1, v_3 \rangle \\ \langle u_2, v_1 \rangle & \langle u_2, v_2 \rangle & \langle u_2, v_3 \rangle \\ \langle u_3, v_1 \rangle & \langle u_3, v_2 \rangle & \langle u_3, v_3 \rangle \end{pmatrix}.$$

So, when we start talking about particular invariant elements in tensor products, it's very natural to switch to talking about multilinear functionals. I hope you can reach the point that the two languages seem interchangeable.

Note that multiplication corresponds to tensor here. For example, let E be the element of $V \otimes V^\vee$ which corresponds to the map $(u, v) \mapsto \langle u, v \rangle$. (If e_i and e^i are dual bases for V and V^\vee , then $E = \sum_i e_i \otimes e^i$.) Then $E \otimes E$, in $V \otimes V^\vee \otimes V \otimes V^\vee$, corresponds to the map $(u_1, v_1, u_2, v_2) \mapsto \langle u_1, v_1 \rangle \langle u_2, v_2 \rangle$.

2. CHANGING FROM DUALS TO ADJUGATES

Let $W = V^\vee \otimes \det$. This is the irreducible $GL(V)$ representation with character $s_{1^{d-1}}$. As an $SL(V)$ representation, it is isomorphic to V^\vee , since $SL(V)$ acts trivially on \det . We can

also describe W as $\bigwedge^{d-1}(V)$. The reason I bring up W is that, unlike V^\vee , it is a polynomial representation, so it fits more easily into our symmetric function techniques.

So $(V^{\otimes m} \otimes (V^\vee)^{\otimes n})^{SL(V)}$ is isomorphic to $(V^{\otimes m} \otimes W^{\otimes n})^{SL(V)}$. Now, $V^{\otimes m} \otimes W^{\otimes n}$ is a polynomial $GL(V)$ representation, on which $t \cdot \text{Id}$ acts by $t^{m+(d-1)n}$. Since any element of $GL(V)$ is a product of an element of $SL(V)$, and an element of the form $t \cdot \text{Id}$, we see that $GL(V)$ acts on $(V^{\otimes m} \otimes W^{\otimes n})^{SL(V)}$ by $\det^{(m+(d-1)n)/d}$.

So

$$(V^{\otimes m} \otimes W^{\otimes n})^{SL(V)} \cong \text{Hom}_{GL(V)}(\det^{(m+(d-1)n)/d}, V^{\otimes m} \otimes W^{\otimes n}).$$

In particular, it is nonzero only if d divides $m + (d-1)n$ or, equivalently, if $m \equiv n \pmod{d}$.

For notational convenience, we set $r = \frac{m+(d-1)n}{d}$.

3. COMPUTATION WITH SYMMETRIC POLYNOMIALS

We see that the dimension of the space $(V^{\otimes m} \otimes W^{\otimes n})^{SL(V)}$ is the same as the multiplicity of $(\det)^r$ in $V^{\otimes m} \otimes W^{\otimes n}$. In other words, this is the coefficient of $s_{r,d}$ in $s_1^m s_{1^{d-1}}^n = e_1^m e_{d-1}^n$. You could compute this using Pieri's rule.

I should say a little about working in Λ versus working in Λ_d . The ring Λ_d encodes the structure of tensor products of polynomial GL_d representations. So the multiplicity of $V_\nu(d)$ in $V_\lambda(d) \otimes V_\mu(d)$ is the same as the coefficient when $s_\lambda(x_1, x_2, \dots, x_d) s_\mu(x_1, \dots, x_d)$ is expanded in the Schur basis.

The map $\Lambda \rightarrow \Lambda_d$ is a map of rings. Its kernel is $\text{Span}_{\mathbb{Z}}(s_\nu)_{\ell(\nu) > d}$. So it is fine to multiply $s_\lambda s_\mu$ in Λ and read off the coefficient of s_ν there. You'll get the same result, since the map $\Lambda \rightarrow \Lambda_d$ sends $s_\nu \rightarrow s_\nu$ if $\ell(\nu) \leq d$, and sends s_ν to 0 if $\ell(\nu) > d$.

3.1. So, how does the inner product fit in? In this course, I only defined the inner product on Λ , not Λ_d . Perhaps it would have been clearer to define it on Λ_d as well: Make the definition be that $(s_\lambda)_{\ell(\lambda) \leq d}$ is an orthonormal basis for Λ_d . This will ensure that $\langle \chi_V, \chi_W \rangle = \dim \text{Hom}_{GL}(V, W)$.

Then the map $\Lambda \rightarrow \Lambda_d$ is norm preserving *on the subspace spanned by $(s_\lambda)_{\ell(\lambda) \leq d}$* . So we may transfer inner product computations from Λ to Λ_d if they do not involve partitions with more than d parts. More specifically, it is enough for one of the two sides of the inner product to involve no such terms.

It is convenient to note that $\text{Span}(s_\lambda)_{\ell(\lambda) \leq n} = \text{Span}(h_\lambda)_{\ell(\lambda) \leq n}$.

Let's demonstrate a WRONG computation. Suppose we wanted to find $\dim(V^{\otimes n} \otimes (V^\vee)^{\otimes n})^{GL(V)}$. This is the same as $\dim \text{Hom}_{GL(V)}(V^{\otimes n}, V^{\otimes n})$. It would NOT be right to say that this is $\langle s_1^n, s_1^n \rangle$, unless we knew that d was large enough that s_1^n contained not partitions with more than d parts. (Specifically, we would need $d \geq n$. Conveniently for you, in Problem 3.(a), Problem Set 6, I specified $\dim V \geq n$.)

On the other hand, computing this quantity as $\langle s_1^n s_{1^{d-1}}^n, s_{n^d} \rangle$, as we described above, is fine. The quantity s_{n^d} does not contain any partitions with more than d parts.