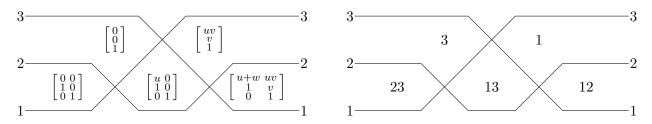
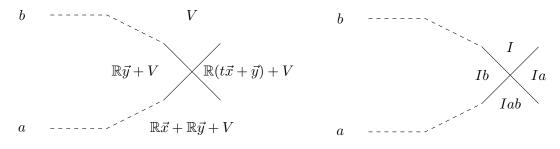
## WORKSHEET 10: INVERTING THE UNIPOTENT PRODUCT II:

We recall our previous example:



Continue to assume that the word  $s_{i_1}s_{i_2}\cdots s_{i_N}$  is reduced. We focus on a crossing j. Abbreviate  $i_j$  to i and  $t_j$  to t. Let the last  $n - i_j + 1$  columns of  $g_{j-1}$  be  $\begin{bmatrix} i & j \\ \vec{x} & \vec{y} & V \\ j & - \end{bmatrix}$ , so the last  $n - i_j + 1$  columns of  $g_j$  are  $\begin{bmatrix} i & j \\ \vec{x} & (t\vec{x} + \vec{y}) & V \\ j & - \end{bmatrix}$ . Let a be the source of the strand going up through the j-th crossing and let b be the source of the strand going down. So the chamber labels and the spaces look like:



**Problem 10.1.** Show that, as depicted in the picture, a < b.

The aim of the next few problems is to prove the formula:

$$t = \frac{\Delta^{Ib} \left( \begin{bmatrix} \vec{y} & V \end{bmatrix} \right) \ \Delta^{Ia} \left( \begin{bmatrix} t\vec{x} + \vec{y} & V \end{bmatrix} \right)}{\Delta^{Iab} \left( \begin{bmatrix} \vec{x} & \vec{y} & V \end{bmatrix} \right) \ \Delta^{I} \left( \begin{bmatrix} V \end{bmatrix} \right)}$$

where we have abused notation by writing V for a matrix whose columns are a basis of V.

Here we have written the argument of the minor as a matrix, not a subspace, so that the minor will be well-defined, not just defined up to scalars. We'll say more about that next time.

**Problem 10.2.** Show that  $\Delta^{Ia}([y V]) = 0$ .

**Problem 10.3.** Show that  $\Delta^{Ia}([t\vec{x}+\vec{y}V]) = t\Delta^{Ia}([\vec{x}V]).$ 

Problem 10.4. Show that

$$\Delta^{Iab}\left(\begin{bmatrix}\vec{x} & \vec{y} & V\end{bmatrix}\right) \Delta^{I}\left(\begin{bmatrix}V\end{bmatrix}\right) = \Delta^{Ib}\left(\begin{bmatrix}\vec{y} & V\end{bmatrix}\right) \Delta^{Ia}\left(\begin{bmatrix}\vec{x} & V\end{bmatrix}\right) - \Delta^{Ia}\left(\begin{bmatrix}\vec{y} & V\end{bmatrix}\right) \Delta^{Ib}\left(\begin{bmatrix}\vec{x} & V\end{bmatrix}\right).$$

(Remember your homework!)

Problem 10.5. Put all the parts together to prove

$$t = \frac{\Delta^{Ib}\left(\begin{bmatrix}\vec{y} & V\end{bmatrix}\right) \ \Delta^{Ia}\left(\begin{bmatrix}t\vec{x} + \vec{y} & V\end{bmatrix}\right)}{\Delta^{Iab}\left(\begin{bmatrix}\vec{x} & \vec{y} & V\end{bmatrix}\right) \ \Delta^{I}\left(\begin{bmatrix}V\end{bmatrix}\right)}$$