MATH 668 PROBLEM SET 7: DUE MONDAY, OCTOBER 31

Problem 1. The point of this exercise is to work through the representation theory of the symmetric S_3 and see that all of the claims we have made in class are true. I'll start by telling you the simple representations of S_3 ; there are three of them. One of them (called the trivial) is a one-dimensional representation with $\rho(q) = 1$ for all g. One of them (called the sign) is a one dimensional representation with $\rho(g) = \text{sign}(g) \in \{1, -1\}$. And one of

them is the two dimensional representation of S_3 on $\begin{bmatrix} 1\\1\\1 \end{bmatrix}^{\perp} \subset \mathbb{R}^3$.

- (1) Describe the conjugacy classes of S_3 . Check that there are also three of them.
- (2) Describe the characters of S_3 . Check that they give an orthogonal basis for conjugacy invariant functions on S_3 .
- (3) Write out matrices $\rho(g)$ for the actions on each of these representations, so that the matrices are orthogonal. Check that the functions $q \mapsto \sqrt{\dim V} \rho_V(q)_{ij}$ give an orthonormal basis for functions on S_3 .

Problem 2. The group O(2) is the group of 2×2 real orthogonal matrices. Every matrix in O(2) is either of the form $\begin{bmatrix} \cos\theta - \sin\theta\\ \sin\theta & \cos\theta \end{bmatrix}$ or $\begin{bmatrix} \cos\theta - \sin\theta\\ \sin\theta & -\cos\theta \end{bmatrix}$. In this problem, we will work out the continuous representation theory of O(2)in $\operatorname{GL}_n(\mathbb{C})$.

The subgroup of matrices in O(2) with determinant 1 is called SO(2). (In other words, SO(2) is the group of rotations.) We showed in class that every continuous representation of SO(2) is a direct sum of representations of the form $\rho_k : \begin{bmatrix} \cos\theta - \sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \mapsto [(\cos\theta + i\sin\theta)^k]$ for $k \in \mathbb{Z}$. Let V be a continuous complex representation of O(2). Write $V = \bigoplus_k V_k$ where SO(2) acts V_k by ρ_k .

- (1) Let σ be a matrix in O(2) with determinant -1 (in other words, a reflection). Show that σ maps V_k to V_{-k} .
- (2) Show that V_0 is a O(2)-subrepresentation of V and, for k > 0, show that $V_k \oplus V_{-k}$ is an O(2)-subrepresentation of V.
- (3) Show that V_0 is a direct sum of copies the following two representations: The 1-dimensional trivial representation given by $\rho(g) = 1$ for all $g \in O(2)$, and the 1-dimensional representation where $\rho(g) = \det(g)$.
- (4) Show that $V_k \oplus V_{-k}$ is a direct sum of copies of the 2-dimensional representation given by

$$\rho\left(\begin{bmatrix}\cos\theta & -\sin\theta\\\sin\theta & \cos\theta\end{bmatrix}\right) = \begin{bmatrix}(\cos\theta + i\sin\theta)^k & 0\\0 & (\cos\theta + i\sin\theta)^{-k}\end{bmatrix}$$

$$\rho\left(\begin{bmatrix}\sin\theta & \cos\theta\\\cos\theta & -\sin\theta\end{bmatrix}\right) = \begin{bmatrix}0 & (\cos\theta + i\sin\theta)^{-k}\\(\cos\theta + i\sin\theta)^k & 0\end{bmatrix}$$

Since you have shown that an arbitrary representation is the direct sum of the 1- and 2-dimensional representations listed here, you have found all representations of O(2).

Problem 3. Let κ be an infinite field of characteristic 0. Let G be the group of matrices of the form $\begin{bmatrix} t & u \\ 0 & 1 \end{bmatrix}$, with $t \in \kappa^{\times}$ and $u \in \kappa$. (As an abstract group, $G \cong \kappa^{\times} \ltimes \kappa^+$.) Let $\rho: G \to \operatorname{GL}(V)$ be an algebraic representation, meaning representations whose matrix entries are in $k[t, t^{-1}, u]$.

You have already shown, and may assume:

- That V decomposes as V = ⊕V_k, so that [^t₀] acts on V_k by t^k
 That there is a nilpotent matrix N such that ρ([¹₀]) = Σ[∞]_{k=0} u^kN^k/k!
- (1) Show that N maps V_k to V_{k+1} .
- (2) Given a finite dimensional vector space V with a direct sum decomposition $V = \bigoplus V_k$, and a nilpotent operator N mapping V_k to V_{k+1} , show that there is a corresponding algebraic representation of G.