

Algebraic and Geometric Multiplicity: Proofs

Let A be an $n \times n$ square matrix with eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_k$. Let a_i be the algebraic multiplicity of λ_i . Let V_i be the λ_i -eigenspace and let $g_i = \dim V_i$, the geometric multiplicity of λ_i .

Theorem 1: We have $\sum g_i = n$ if and only if A has an eigenbasis.

Theorem 2: We have $g_i \leq a_i$.

Theorem 3: We have $\sum a_i \leq n$, and $\sum a_i = n$ if and only if $\det(A - t\text{Id})$ factors completely into linear terms.

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We told the story in the order that explains the importance of the results, but the proofs are easiest in the reverse order.

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Theorem 3: We have $\sum a_i \leq n$, and $\sum a_i = n$ if and only if $\det(A - t\text{Id})$ factors completely into linear terms.

We have

$$\det(A - t\text{Id}) = \prod_i (\lambda_i - t)^{a_i} \cdot (\text{some polynomial with no roots}).$$

So

$$\deg \det(A - t\text{Id}) = n \geq \sum a_i.$$

We have equality if and only if $\det(A - t\text{Id})$ factors into linear terms. **QED**

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To make notation simpler, abbreviate λ_i to λ , g_i to g and a_i to a .

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Complete $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_g$ to a basis

$\mathfrak{B} = (\vec{v}_1, \vec{v}_2, \dots, \vec{v}_g, \vec{w}_1, \vec{w}_2, \dots, \vec{w}_{n-g})$ for \mathbb{R}^n .

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$$\left[\begin{array}{cccc|c} \lambda & & & & ? \\ & \lambda & & & \\ & & \ddots & & \\ & & & \lambda & \\ \hline & & & 0 & ? \end{array} \right]$$

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$$\left[\begin{array}{ccc|c} \lambda & & & \\ & \lambda & & \\ & & \ddots & \\ & & & \lambda \\ \hline & & & 0 \\ & & & C \end{array} \right]$$

So

$$A - t\text{Id}_n = \left[\begin{array}{ccc|c} \lambda-t & & & \\ & \lambda-t & & \\ & & \ddots & \\ & & & \lambda-t \\ \hline & & & 0 \\ & & & C - t\text{Id}_{n-g} \end{array} \right]$$

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$$\det(A - t\text{Id}_n) = \det \left[\begin{array}{ccc|c} \lambda-t & & & \\ & \lambda-t & & \\ & & \ddots & \\ & & & \lambda-t \\ \hline & & & 0 \\ \hline & & & C - t\text{Id}_{n-g} \end{array} \right] \begin{array}{l} B \\ \\ \\ \\ \\ \end{array} \\ = (\lambda - t)^g \det(C - t\text{Id}_{n-g}). \quad \mathbf{QED}$$

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First of all, suppose that A has an eigenbasis: $\vec{x}_1, \vec{x}_2, \dots, \vec{x}_n$.

For each λ_i , let h_i be the number of \vec{x}_i which are λ_i -eigenvectors.

So $n = \sum h_i$.

The λ_i -eigenvectors are contained in V_i , so the number of them is at most $\dim V_i$. So $h_i \leq g_i$.

So $n = \sum h_i \leq \sum g_i$. But we also already noted that

$\sum g_i \leq \sum a_i \leq n$. So $\sum g_i = n$.

Let A be an $n \times n$ square matrix with eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_k$. Let a_i be the algebraic multiplicity of λ_i . Let V_i be the λ_i -eigenspace and let $g_i = \dim V_i$, the geometric multiplicity of λ_i .

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The notation for this one gets hairy, so let's rename things.

Let's suppose there are 3 eigenvalues: α, β, γ .

Let the eigenspaces be U, V and W .

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Let $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_a$ be a basis of U ; let $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_b$ be a basis of V and let $\vec{w}_1, \vec{w}_2, \dots, \vec{w}_c$ be a basis of W .

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These are eigenvectors, so our goal will be to show that $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_a, \vec{v}_1, \vec{v}_2, \dots, \vec{v}_b, \vec{w}_1, \vec{w}_2, \dots, \vec{w}_c$ is a basis of \mathbb{R}^n .

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Since $a + b + c = n$, we just need to show that $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_a, \vec{v}_1, \vec{v}_2, \dots, \vec{v}_b, \vec{w}_1, \vec{w}_2, \dots, \vec{w}_c$ are linearly independent.

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Suppose that we had a linear relation:

$$f_1\vec{u}_1 + \dots + f_a\vec{u}_a + g_1\vec{v}_1 + \dots + g_b\vec{v}_b + h_1\vec{w}_1 + \dots + h_c\vec{w}_c = \vec{0}.$$

Let's suppose there are 3 eigenvalues: α, β, γ . Let the eigenspaces be U, V and W . Let the geometric multiplicities be $a = \dim U$, $b = \dim V$, $c = \dim W$, with $a + b + c = n$.

Let $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_a$ be a basis of U ; let $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_b$ be a basis of V and let $\vec{w}_1, \vec{w}_2, \dots, \vec{w}_c$ be a basis of W . Our goal is to show that $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_a, \vec{v}_1, \vec{v}_2, \dots, \vec{v}_b, \vec{w}_1, \vec{w}_2, \dots, \vec{w}_c$ is a basis of \mathbb{R}^n .

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$$\underbrace{f_1 \vec{u}_1 + \dots + f_a \vec{u}_a}_{\alpha\text{-eigenvector}} + \underbrace{g_1 \vec{v}_1 + \dots + g_b \vec{v}_b}_{\beta\text{-eigenvector}} + \underbrace{h_1 \vec{w}_1 + \dots + h_c \vec{w}_c}_{\gamma\text{-eigenvector}} = \vec{0}.$$

Let's suppose there are 3 eigenvalues: α, β, γ . Let the eigenspaces be U, V and W . Let the geometric multiplicities be $a = \dim U$, $b = \dim V$, $c = \dim W$, with $a + b + c = n$.

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Since α, β and γ are distinct, we must have

$$f_1 \vec{u}_1 + \dots + f_a \vec{u}_a = g_1 \vec{v}_1 + \dots + g_b \vec{v}_b = h_1 \vec{w}_1 + \dots + h_c \vec{w}_c = \vec{0}.$$

$$f_1\vec{u}_1 + \cdots + f_a\vec{u}_a = g_1\vec{v}_1 + \cdots + g_b\vec{v}_b = h_1\vec{w}_1 + \cdots + h_c\vec{w}_c = \vec{0}.$$

But, since $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_a$ is a basis of U , this means that

$$f_1 = \cdots = f_a = 0.$$

Similarly, $g_1 = \cdots = g_b = 0$ and $h_1 = \cdots = h_c = 0$.

We have shown that all the coefficients of our linear relation are 0.

So we have shown that the vectors $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_a, \vec{v}_1, \vec{v}_2, \dots, \vec{v}_b, \vec{w}_1, \vec{w}_2, \dots, \vec{w}_c$ are linearly independent.

Since $a + b + c = n$, we have shown that $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_a, \vec{v}_1, \vec{v}_2, \dots, \vec{v}_b, \vec{w}_1, \vec{w}_2, \dots, \vec{w}_c$ is a basis of \mathbb{R}^n . **QED**