

(1) Let $A = \begin{bmatrix} 1 & 2 & 3 & 0 \\ 2 & 0 & -1 & 0 \\ 3 & 2 & 2 & 0 \\ -1 & 2 & 4 & 0 \end{bmatrix}$.

- (a) Compute the reduced row echelon form of A .
 (b) Find a basis for $\ker(A)$ and for $\text{Im}(A)$.

(2) Let W be the plane $x - z = 0$ in \mathbb{R}^3 .

- (a) Find an orthonormal basis for W .
 (b) Find the standard matrix R for reflections of vectors over W .
 (c) Diagonalize R (Hint: try to understand R from geometry).
 (d) Is R invertible?

(3) Suppose Q is a 12×12 orthogonal matrix and $\mathbf{x} = \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}$ and $\mathbf{y} = \begin{bmatrix} 1 \\ -1 \\ \vdots \\ -1 \end{bmatrix}$ in \mathbb{R}^{12} .

Find $\|Q\mathbf{x}\|$ and $\langle Q\mathbf{x}, Q\mathbf{y} \rangle$.

(4) If $\{\mathbf{u}, \mathbf{v}\}$ is an orthogonal set in \mathbb{R}^{14} , Q is an orthogonal matrix in $M_{14 \times 14}$, and the distance from \mathbf{u} to $-\mathbf{v}$ is 4, compute the distance from $Q\mathbf{u}$ to $Q\mathbf{v}$.

(5) In the QR factorization of $A = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & 0 \end{bmatrix}$ (where $\sin(\theta) \neq 0$), find Q and check that $Q^T = Q^{-1}$.

(6) Let A be a 2×2 matrix. Suppose A has an eigenvector $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ with eigenvalue -2 and another eigenvector $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ with eigenvalue 3.

- (a) Find A .
 (b) Find a closed formula for A^n where n is a positive integer.

(7) Let Poly_1 be the space of all linear functions, i.e. functions of the form $f(x) = ax + b$, where a, b are real numbers. Consider the linear transformation $T : \text{Poly}_1 \rightarrow \text{Poly}_1$ that takes f to $-3f' + f$.

- (a) Find the matrix of T relative to the standard basis $\{1, x\}$.
 (b) Find the matrix of T relative to the basis $\{1 - x, 1 + x\}$.
 (c) What are the determinants of those matrices? Is the transformation invertible?

(8) (For this problem, imagine that there's generous partial credit for doing the parts for a single example $\mathbf{u} \in \mathbb{R}^2$.)

Let $\mathbf{u} \in \mathbb{R}^n$ be a column vector with unit length and define $H = I - \mathbf{u}\mathbf{u}^T$. (Not $\mathbf{u}^T\mathbf{u}$!)

- (a) Prove that H is symmetric and $H^2 = H$.
 (b) Prove that \mathbf{u} is an eigenvector and find its corresponding eigenvalue.
 (c) Prove that whenever $\mathbf{v} \perp \mathbf{u}$, then \mathbf{v} is also an eigenvector.

- (d) Prove that H is diagonalizable.
- (9) Recall that the *trace* of a square matrix is the sum of the entries on the main diagonal. Prove that similar square matrices have the same trace.
- (10) **Give an example if possible. If not, say why not.**
- A 5×4 matrix with with no zero entries with rank and nullity both 2.
 - A linear transformation $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ for which $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ are eigenvectors.
 - A 2×3 matrix Q such that $Q^T Q = \begin{bmatrix} 6 & 0 \\ 0 & 3 \end{bmatrix}$.
 - A linear transformation $T : \text{Poly}_2 \rightarrow \mathbb{R}^3$ such that $T(x) = 0$ and T is onto.
 - A linear transformation $T : \mathbb{R}^3 \rightarrow \text{Poly}_2$ such that $T(e_1) = x^2 + x + 1$ and T is onto.
- (11) **Short proofy problems.**
- Consider $M_{2 \times 2}$ with the standard basis \mathcal{Q} , and $T : M_{2 \times 2} \rightarrow M_{2 \times 2}$ be given by swapping rows. Prove that T is linear and find its \mathcal{Q} -matrix.
 - Let λ be an eigenvalue of a square matrix A . Show that $\lambda^3 + 5\lambda + 1$ is an eigenvalue of the matrix $A^3 + 5A + I$.
 - Find all possible determinants of all orthogonal $n \times n$ matrices for all n .
 - Let V be a vector space and $S, T : V \rightarrow V$ be linear transformations such that \mathbf{x} is an eigenvector for both S and T . Prove that \mathbf{x} is also an eigenvector for $S \circ T$.
 - Let $H \subset K \subset \mathbb{R}^n$ be subspaces. Prove that $K^\perp \subset H^\perp$.
 - Show that if $\mathbf{w}, \mathbf{v} \in V$ are vectors such that $\langle \mathbf{w}, \mathbf{x} \rangle = \langle \mathbf{v}, \mathbf{x} \rangle$ for all $\mathbf{x} \in V$, then $\mathbf{w} = \mathbf{v}$.
 - Suppose $A \in M_{4 \times 4}$ has complex eigenvalues $\lambda = 3 + i$ and $\lambda = 4 + 2i$. Show that A has no eigenvectors in \mathbb{R}^4 .
- (12) **Grammar check.** Meaningful/nonsense? If meaningful, true/false? If nonsense or false, replace with a similar true statement.
- The square of a vector is always nonnegative.
 - If W is a two-dimensional subspace of \mathbb{R}^3 , then W^\perp has one element.
 - If an elementary matrix is applied to every vector in a basis \mathcal{B} for \mathbb{R}^n , then the output vectors also form a basis.
 - If $A, B \in M_{2 \times 2}$ satisfy $AB = 0$, then $BA = I$.
 - If you apply the Gram-Schmidt method to the entries of $\begin{bmatrix} 5 & 7 \\ 0 & 4 \end{bmatrix}$, it will result in a factorization into $\begin{bmatrix} 5 & 0 \\ 0 & 4 \end{bmatrix} \begin{bmatrix} 1 & -7/5 \\ 0 & 1 \end{bmatrix}$.
- (13) (Input-Output Economics Problem)
- Suppose you want to study the paper sector and the electronics sector of your economy. Suppose the inter-industry consumption matrix and the final demand vector are $C = \begin{bmatrix} .1 & .6 \\ .5 & .2 \end{bmatrix}$, $\mathbf{d} = \begin{bmatrix} 10 \\ 22 \end{bmatrix}$. Solve the production equation. Give an interpretation of all the numbers in C , \mathbf{d} , and \mathbf{x} . Which industry is more efficient?
- (14) (Markov Chains Problem)
- Suppose you consider five possible mood statuses (happy, hungry, dazed, incensed, and ticklish), and you form a 5×5 stochastic matrix P describing the transition probabilities

between these moods from one moment to the next. If \mathbf{x} is an eigenvector of P corresponding to the eigenvalue $\lambda = 1$, give an interpretation of the meaning of \mathbf{x} in terms of your moods.

(15) (Least Squares Problem) Find a least-squares solution of $A\mathbf{x} = \mathbf{b}$ where

$$A = \begin{bmatrix} 1 & 2 \\ -1 & 4 \\ 1 & 2 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} 4 \\ -2 \\ -3 \end{bmatrix}.$$